

Operator's Guide 03/2004 Edition

sinumerik

SINUMERIK 840D/810D  
HMI Embedded

**SIEMENS**



# SIEMENS

## SINUMERIK 840D/810D

### HMI Embedded

#### Operator's Guide

#### Valid for

<i>Control</i>	<i>Software version</i>
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SINUMERIK 840Di	3
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# SINUMERIK® Documentation

## Printing history

Brief details of this edition and previous editions are listed below.

The status of each edition is shown by the code in the "Remarks" columns.

*Status code in the "Remarks" column:*

- A ....** New documentation.
- B ....** Unrevised reprint with new Order No.
- C ....** Revised edition with new status.

<b>Edition</b>	<b>Order No.</b>	<b>Remarks</b>
02.01	6FC5298-6AC00-0BP0	A
11.01	6FC5298-6AC00-0BP1	C
11.02	6FC5298-6AC00-0BP2	C
03.04	6FC5298-6AC00-0BP3	C

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This publication was produced with WinWord V 7.0 and Designer V 4.0.

Other functions not described in this documentation might be executable in the control. This does not, however, represent an obligation to supply such functions with a new control or when servicing.

We have checked that the contents of this documentation correspond to the hardware and software described. Nonetheless, differences might exist and therefore we cannot guarantee that they are completely identical. The information contained in this document is, however, reviewed regularly and any necessary changes will be included in the next edition. We welcome suggestions for improvement.

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## Preface

### Structure of the documentation

The SINUMERIK documentation is organized in 3 parts:

- General Documentation
- User Documentation
- Manufacturer/Service Documentation

### Target group

This document is designed for machine tool users. The document describes in detail all the technical facts an operator needs to understand how to operate the SINUMERIK 840D, 840Di, 810D control systems.

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<http://www.siemens.com/motioncontrol>

Since 09.2001 the

- SINUMERIK 840D powerline and
- SINUMERIK 840DE powerline (export version)

have been available with improved performance. The hardware description below contains a list of the available **powerline** modules:

**References:** /PHD/ SINUMERIK 840D Configuration Manual

### SINUMERIK 810D powerline

Since 12.2001 the

- SINUMERIK 810D powerline and
- SINUMERIK 810DE powerline (export version)

have been available with improved performance. The hardware description below contains a list of the available **powerline** modules:

**References:** /PHC/ SINUMERIK 810D Configuration Manual

**Export version**

Function	810DE	840DE
Five axis machining package	–	–
Handling transformation package, (five axes)	–	–
Multi-axis interpolation, (> four axes)	–	–
Helical interpolation, 2D+6	–	–
Synchronized actions, stage 2	–	0 <sup>1)</sup>
Measurements, stage 2	–	0 <sup>1)</sup>
Adaptive control	0 <sup>1)</sup>	0 <sup>1)</sup>
Continuous dressing	0 <sup>1)</sup>	0 <sup>1)</sup>
Utilization of compile cycles, (OEM)	–	–
Sag compensation, multi-dimensional	–	0 <sup>1)</sup>

– Function not available

1) restricted functionality

**Standard scope**

This Operator's Guide describes the functionality of the standard scope. Extensions or changes made by the machine tool manufacturer are documented by the machine tool manufacturer.

Please contact your local Siemens office for more detailed information about other SINUMERIK 840D, 810D publications, and publications that apply to all SINUMERIK controls (e.g. universal interface, measuring cycles, etc.).

Other functions not described in this documentation might be executable in the control. This does not, however, represent an obligation to supply such functions with a new control or when servicing.

**Validity**

Catalog NC 60 is definitive in terms of the validity of the functions /BU/ Machine Tools, catalog NC 60

## Structure of the descriptions



Wherever sensible and possible, all functions and operating options have been described using the same internal structure. By structuring the explanations in different information levels, we have made it possible for users to specifically access the required information.

### Explanation of symbols

#### Function

This theoretical part serves as a learning document, particularly for those who are new to the world of NC applications. Important information about understanding operating functions is offered to users at this point.

You should work through the manual at least once to get an overview of the operational scope and performance capability of your SINUMERIK control.

#### Operating sequence

This point shows the sequence of key operations which need to be executed. Any inputs or additional information required in the individual operating steps are described next to the pictures of the keys.

#### Notes

This symbol is always displayed in this document to draw your attention to an important item of information in a more complex description.

#### Machine manufacturer

For safety reasons some functions are locked against unauthorized access. The machine manufacturer can influence or change the described functional behavior. Always refer to the information and specifications provided by the machine manufacturer.

#### Further information

For safety reasons some functions are locked against unauthorized access. The machine manufacturer can influence or change the described functional behavior. Always refer to the information and specifications provided by the machine manufacturer.

#### Reference notes

You will find this symbol wherever further information on a particular topic can be looked up in specialist literature.

A complete list of available literature is included in the Appendix of this Operator's Guide.



### Ordering data option

In this documentation you will find the symbol shown on the left with a reference to an ordering data option. The function described will only be executable if the control contains the designated option.

### Warning Information

The following warning notices with varying degrees of significance are used in the document:



#### Danger

Indicates an imminently hazardous situation which, if not avoided, **will** result in death or serious injury or in substantial property damage.



#### Warning

Indicates a potentially hazardous situation which, if not avoided, **could** result in death or serious injury or in substantial property damage.



#### Caution

Used with the safety alert symbol indicates a potentially hazardous situation which, if not avoided, **may** result in minor or moderate injury or in property damage.

#### Caution

Used without safety alert symbol indicates a potentially hazardous situation which, if not avoided, **may** result in property damage.

#### Notice

Used without the safety alert symbol indicates a potential situation which, if not avoided, **may** result in an undesirable result or state.

**Principle**

Your SIEMENS 840D, 810D is designed using state-of-the-art technology in conformity with recognized safety regulations, standards and specifications.

**Supplementary devices**

The applications of SIEMENS controls can be expanded by adding special additional devices, equipment and expansions supplied by SIEMENS.

**Personnel**

Only **properly trained, authorized, reliable personnel** must be allowed to use this equipment. No-one without the necessary training must be allowed to operate the control, even temporarily.

The **areas of responsibility** assigned to personnel involved in setting up, operating and maintaining the equipment must be clearly **specified** and their compliance **verified**.

**Procedure**

**Before** the control is started up, personnel responsible for its operation must have read and understood the Operator's Guides. The company using this equipment is also obliged to carry out **continuous monitoring** of the overall technical condition of the equipment (with a view to identifying externally visible defects and damage as well as changes in the operating behavior of the control).

**Servicing**

Repairs to equipment may only be carried out by **personnel specially trained and qualified** for the application in question in accordance with the provisions specified in the maintenance and servicing guides. All relevant safety regulations must be followed.



The following are deemed as **improper usage** and **exclude the manufacturer from all liability**:

**Any** usage or application incompatible with or beyond the scope of the items specified above.

Cases where the control is operated **in a technically imperfect condition**, without due provision for safety considerations and/or hazards, or in contravention with any of the instructions in the relevant documentation.

Cases where faults which could affect safety are not remedied **before** starting up the control.



Any **modification, bypassing or decommissioning** of equipment on the control whose intended purpose is to ensure proper functioning, unrestricted use of equipment and/or active and passive safety.

**Unforeseen danger** can arise with reference to:

- life and limb of personnel,
- the control, machine or other assets of the owner and the user.



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## Introduction

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## 1.1 The product SINUMERIK 840D/810D

### General

SINUMERIK 840D and 810D are CNC control systems (**C**omputerized **N**umerical **C**ontrol) for machine tools.

You can implement the following basic functions (for a machine tool) via the operator panel front of the CNC control:

- Creating and adapting parts programs.
- Execution of parts programs,
- Manual control,
- Input and output of parts programs and data,
- Editing of data for programs,
- Display and precisely recover alarms,
- Editing machine data,
- Creating communication connections between 1 or more PCUs, or 1 or more NCs (m:n, m-HMI units and n-NCK/PLC units).

The user can call up all the functions via the user interface.

The user interface consists of:

- Display devices such as a screen, light diodes, etc.
- Operator controls such as keys, switches, hand wheels, etc.

This Operator's Guide describes the procedure for PCU/PC with the **HMI Embedded Software, SW 6.5**

The HMI Embedded software is installed in the PCU as standard when supplied from the factory.

Read Chapter 2 "Operator Components" carefully before proceeding with further chapters.

All subsequent chapters are written on the assumption that you have done so!



## 1.2 Switching control system on and off



### Function

#### Switching the control ON

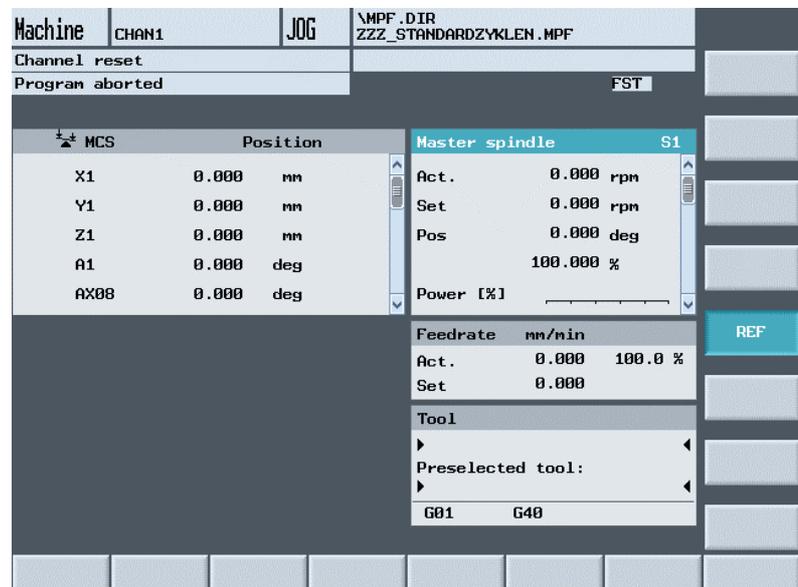
A variety of methods can be employed to switch on the power supply to the control system or to the whole station, therefore:



#### Machine manufacturer

Please refer to the information and specifications provided by the machine manufacturer!

After the control has been switched on, the "Reference point approach" display or another basic display programmed by the machine manufacturer will appear.



#### Switching the control OFF

Please follow the instructions for switching off the control or the entire system!

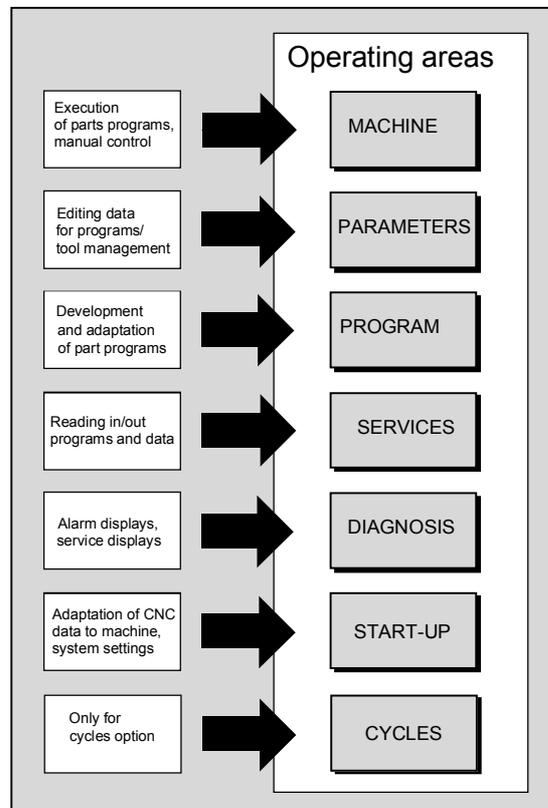


#### Machine manufacturer

Please refer to the information and specifications provided by the machine manufacturer!

### 1.3 Operating areas

The basic functions are grouped in the following operating areas in the control (in gray boxes):



### Operating sequence

When you press the "Area switchover" key, operating areas are displayed on the horizontal softkey bar and operating modes are displayed on the vertical softkey bar. You can use this key to go to the area menu bar from any location in the menu hierarchy if you wish to select another operating mode or a different operating area.



Machine	CHAN1	JOG	\MPF.DIR ZZZ_STANDARDZYKLEN.MPF		
Channel reset			FST		
Program aborted			AUTO		
MCS		Position	Masterspindel S1		
X1	0.000	mm	Act.	0.000 rpm	
Y1	0.000	mm	Set	0.000 rpm	
Z1	0.000	mm	Pos	0.000 deg	
A1	0.000	deg		100.000 %	
AX08	0.000	deg	Power [%]		
			Feedrate mm/min		
			Act.	0.000 100.0 %	
			Set	0.000	
			Tool		
			Preselected tool:		
			G01 G40		
Machine	Parameter	Program	Services	Diagnostics	Start-up



By pressing the "Area switchover" key twice, you can toggle between the operating areas last selected, e.g. between the "Parameters" and "Machine" areas.

**1.3 Operating areas**

## Operator Components/Operating Sequences

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## 2.1 Operator panels

The recommended hardware base for HMI Embedded is a SINUMERIK 840D/810D with PCU 20 or PCU 50.

You can use one of the following operator panels for the PCU:

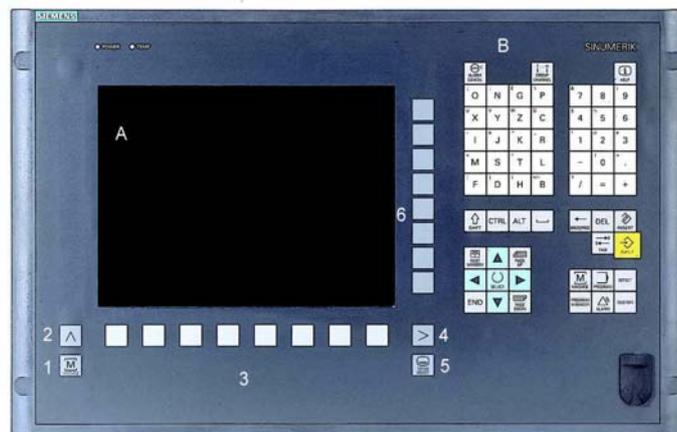
- OP 010
- OP 010C
- OP 010S with OP 032S full CNC keyboard
- OP 012
- OP 015 with 19" full CNC keyboard

TP 012 and TP 015A (only with customer-specific software)

### OP 010 Operator Panel

- A Display
- B Alphanumeric keypad  
Correction/cursor keys

- 1 Machine area key
- 2 Recall (Return)
- 3 Softkey bar (horizontal)
- 4 ETC key  
(menu extension)
- 5 Area switchover key
- 6 Softkey bar (vertical)



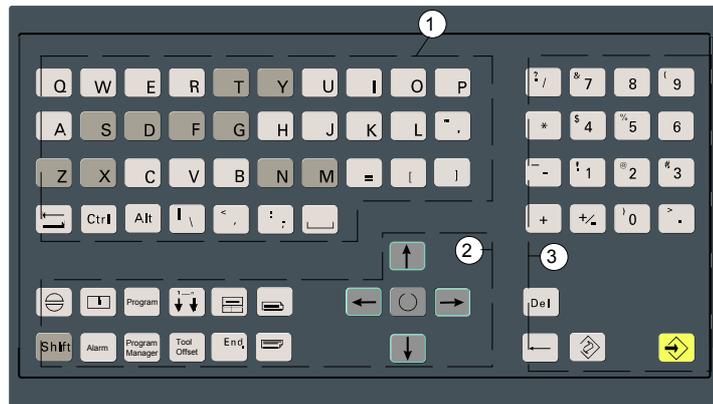
All keys are described in the following sections.

**OP 010S Operator Panel****A Display**

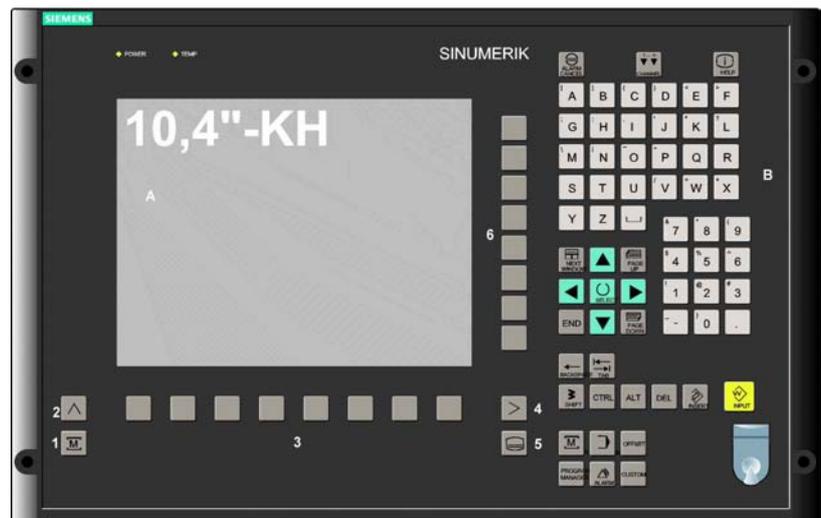
- 1 Machine area key
- 2 Recall (Return)
- 3 Softkey bar (horizontal)
- 4 ETC key  
(menu extension)
- 5 Area switchover key
- 6 Softkey bar (vertical)

**OP 032S with full CNC keyboard**

- 1 Alpha pad
- 2 Correction/cursor pad with control keys
- 3 Numeric pad

**OP 010C Operator Panel****A Display****B Alphanumeric keypad  
Correction/cursor keys**

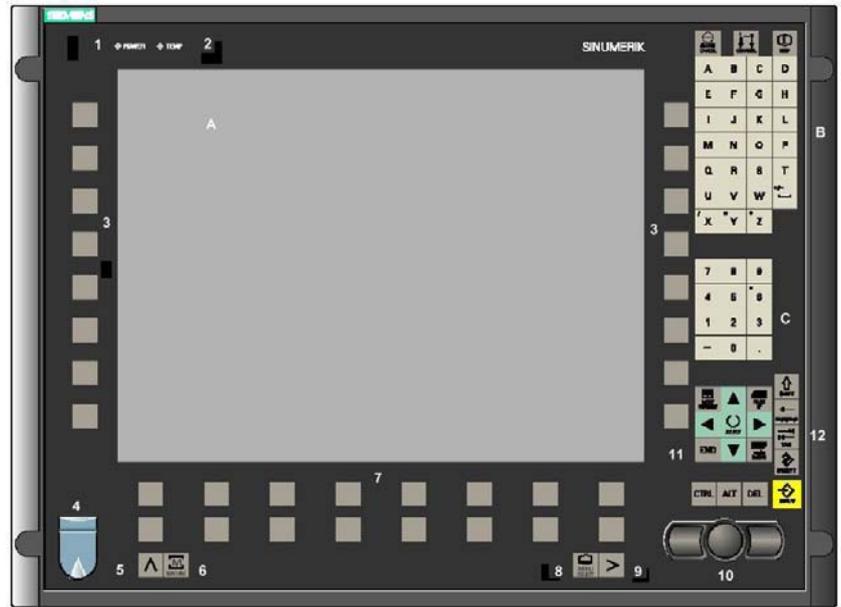
- 1 Machine area key
- 2 Recall (Return)
- 3 Softkey bar (horizontal)
- 4 ETC key  
(menu extension)
- 5 Area switchover key
- 6 Softkey bar (vertical)





**OP 015A Operator Panel**

- A Display
- B Alpha pad
- C Numeric pad
- 1 Status LED: Power
- 2 Status LED: TEMP\*)
- 3 Softkeys and direct keys
- 4 Front USB interface
- 5 Recall
- 6 Machine area
- 7 Softkeys
- 8 Area switchover key
- 9 ETC key
- 10 Mouse
- 11 Cursor pad
- 12 Control keypad



\*) Wear will probably be high when the TEMP LED is lit.

**Notice**

If a high contrast picture is displayed on the TFT display for more than an hour, there is a danger of irreversible display damage due to the so-called "burn-in effect".

In order to avoid this undesired effect, the screen saver must always be active.

**References**

/IAM/IM2, Installation Guide HMI Embedded, Chapter 5 Switching on Display Darkening Switch

**2.1.1 Operator panel keys**

The elements of the operator panel keyboard and the symbols used to represent them in this manual are shown and explained below.

The keys marked with an \* correspond to the key symbols in US layout.

**MACHINE**

Direct branch to the "Machine" operating area.

**Recall key**

Return to the next higher menu. Recall closes a window.

**ETC key**

Expansion of the softkey bar in the same menu.

**MENU SELECT**

You can call the basic menu from any operating area by pressing this key. Pressing the key twice in succession changes from the current operating area to the previous one and back again.

The standard basic menu branches into the following operating areas:

1. Machine
2. Parameters
3. Program
4. Services
5. Diagnostics
6. Start-up

**ALARM CANCEL**

By pressing this key, you can acknowledge the alarm marked by this cancel symbol.

**CHANNEL**

In a configuration with several channels, it is possible to switch between channels (switch from channel 1 to channel n).

When a "Channel menu" is configured, all existing communication links to other NCUs plus the associated channels are displayed on softkeys.

(See also Section "Channel switchover")

**HELP**

This key displays explanatory information about the current operating status (e.g. support for programming, diagnosis, PLC, alarms).

The letter "i" displayed in the dialog line indicates that information is available.

**SHIFT**

Depress the Shift key to enter the uppermost character shown on the dual input keys.


 CTRL
**CTRL**

Use the following key combinations to navigate in the process plan and in the G code editor:

Ctrl + Pos1: Jump to the start.

Ctrl + End: Jump to the end.

Ctrl + C: **Copy** a selected area to the same global memory. If nothing is selected, the content of the entire field is saved in the buffer.

Ctrl + X: Copy a selected area to the same global memory and **cut**.

CTRL +V: **Insert** the contents from the global memory to the cursor position.


 ALT
**ALT****Blank, empty character****BACKSPACE**

- Delete the value in the input field from the right.
- Delete the character after the cursor in insertion mode.


 DEL
**DEL**

- Delete the value in the parameter field
- Delete the character marked by the cursor in insertion mode.

**INSERT**

- Switch to tables and input fields in the editing mode (in this case the input field is located in the insert mode) or
- UNDO function on the table element and input fields (when leaving a field with the edit key, the value is not accepted, but rather reset to the previous value = UNDO).
- Activate pocket calculator mode

**TAB**

Tab key

**INPUT**

- Accepts an edited value
- Open/close a directory or program

**NEXT WINDOW**

If several windows are displayed on the screen, it is possible to make the next window the active one using the window selection key (the active window has a thicker border).

Keyboard input, e.g. the page keys, is possible only in the active window.

**Cursor up**

Move between different fields or lines.

**PAGE DOWN**

You "page" down by one display.

In a part program you can scroll the display down (towards end of program).

With the page keys you scroll the visible/displayed area of the window that is active. The scroll bar indicates which part of the program/document/... is selected.

**Cursor to the left**

- Move between different fields or lines.
- Switch to the higher level directory.

**SELECT**

This key has the same function as the "Alternat." softkey.

- Selection key for values set in fields and selection lists labeled with this key symbol.
- Activate or deactivate a field:

= active

= inactive

= active

= inactive

Multiple selector button  
(you can select several options  
or none)

Single selection button/option  
(only one option can be active at a  
time)

- Switch Select mode on and off in the editor

**Cursor to the right**

- Move between different fields or lines.
- Open a directory or program.

**END**

- The cursor in the editor moves to the end of the line in the opened page with this key.
- Rapid positioning of the cursor on a group of related input fields.

**Cursor down**

Move between different fields or lines.

**PAGE UP**

You "page" up by one display. With the page keys you scroll the visible/displayed area of the active window. The scroll bar indicates which part of the program/document/... is selected.

**PROGRAM** (only OP 010 and OP 010C)

Open the "Program" operating area.

This key has the same function as the "Prog. edit" softkey.

**OFFSET =** (only OP 010 and OP 010C)

Tool management

Open the "Tools/zero offset" operating area.

This key has the same function as the "Tool zero point" softkey

**PROGRAM MANAGER** (only OP 010 and OP 010C)

Open the "Program" operating area.

This key has the same function as the "Program" softkey.

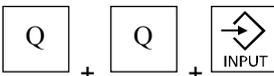
**ALARM** (only OP 010 and OP 010C)

In the main diagnostic display, open the "Messages/Alarms" overview of alarms.

This key has the same function as the "Alarm list" softkey.

**CUSTOM**

The customer configures this key.

**Initiates a PCU reset**

**2.2 Machine control panels**

Standard turning machines/milling machines

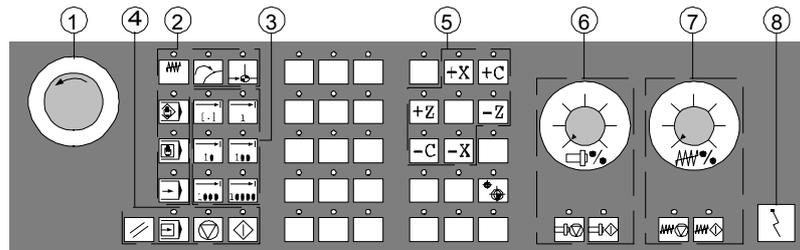
Actions on the machine tool, for example traversing the axes or program start, can only be initiated via a machine control panel.

The machine tool can either be equipped with a standard machine control panel from SIEMENS or with a specific machine control panel from the machine-tool manufacturer.

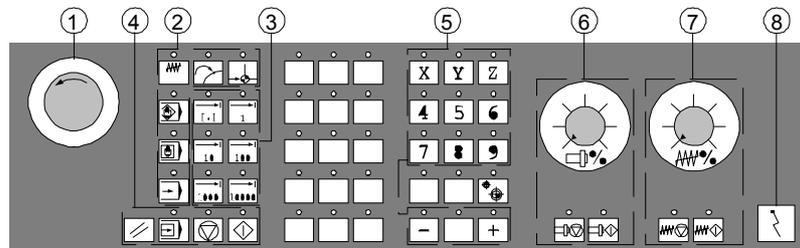
The machine control panel described in this document is the panel supplied by SIEMENS. If you are using another machine control panel, please consult the operating instructions of the machine-tool manufacturer.

The standard machine control panel from SIEMENS is equipped with the following operator controls:

- 1 EMERGENCY STOP key
- 2 Operating modes (with machine functions)
- 3 Incremental traverse/Increment
- 4 Program control
- 5 Direction key with rapid traverse override
- 6 Spindle control
- 7 Feedrate control
- 8 Key switch

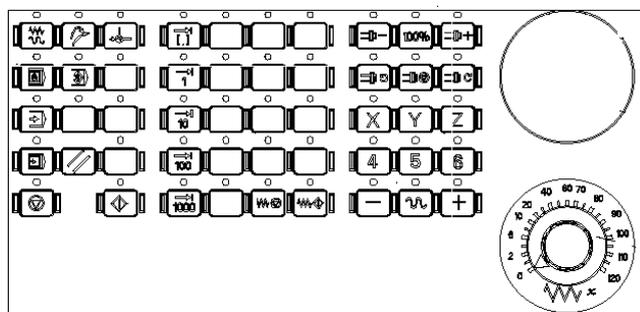


Machine control panel for turning machines



Machine control panel for milling machines

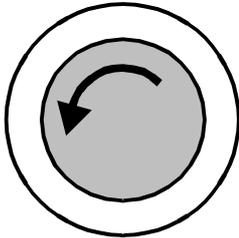
Machine control panel  
 OP 032S



Machine control panel OP 032S

## 2.3 Machine control panel keys

### 2.3.1 Emergency stop key



**Machine manufacturer**

Press this red key in emergency situations:

1. If life is at risk,
2. When there is the danger of machine or workpiece being damaged.

An EMERGENCY STOP generally shuts down all drives with the greatest possible braking torque in a controlled manner.

For details of other or additional reactions to an EMERGENCY STOP: Please refer to the information and specifications provided by the machine manufacturer.

### 2.3.2 Operating modes and machine functions



If you press a "Mode key", the corresponding mode is selected if permissible, and all other modes and functions are deselected.

The active mode is signaled and confirmed by the associated LED which lights up.

#### Jog

Select Machine Manual operating mode. Conventional traversing of the axes via:

- continuous motion of the axes using the direction keys or
- incremental motion of the axes using the direction keys or
- the handwheel.

#### Teach In

Creation of programs in interactive mode with the machine in "MDA" mode.

#### MDA (Manual Data Automatic)

Select "Machine Auto" operating mode.

Control of machine through execution of a block or a sequence of blocks. The blocks are entered on the operator panel front.

## 2.3 Machine control panel keys



### Automatic

Select "Machine Auto" operating mode.

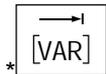
Control of machine through automatic execution of programs.



### Inc keys

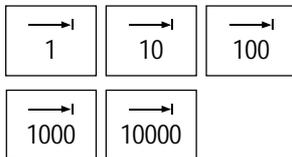
You can activate the Inc functions in conjunction with the following modes:

- Operating mode: "Jog"
- Operating mode: "MDA/Teach In"



### VAR (Incremental feed variable)

Incremental traverse with variable increment size (see "Parameters" operating area, setting data).



### Inc (Incremental Feed)

Incremental traverse with preset increment size of 1, 10, 100, 1000, 10000 increments.



The way that the incremental value is evaluated depends on the setting in the machine data.

See machine manufacturer's specifications.

### Machine functions



### REPOS

Repositioning

Reposition, re-approach contour in "Jog" mode.

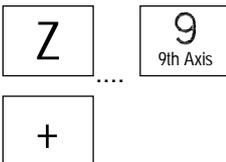
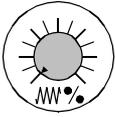


### Ref Point

Approaching a reference point

Approach the reference point (Ref) in "Jog" mode.

### 2.3.3 Feedrate control



#### Feedrate rapid traverse override (feedrate override switch)

##### Control range:

0% to 120% of programmed feedrate.

In rapid traverse, the 100% value is not exceeded.

##### Settings

0%, 1%, 2%, 4%, 6%, 8%, 10%, 20%, 30%, 40%, 50%, 60%, 70%, 75%, 80%, 85%, 90%, 95%, 100%, 105%, 110%, 115%, 120%

#### Feed Stop

- Execution of the active program is stopped,
- The axis drives are shut down,
- The associated LED illuminates as soon as feed stop has been accepted by the control,
- FST (= feed stop) appears in the header (program control display)

##### Example:

- In the "MDA" operating mode an error is discovered during execution of a block.
- Tool change is to be carried out.

#### Feed Start

If you press the "Feed start" key:

- the part program in the current block is continued,
- the feed is accelerated to the value defined in the program,
- the associated LED illuminates as soon as feed start has been accepted by the control.

#### Axis keys (for turning machines):

Traverse the selected axis (X.... Z).

#### Axis keys (for milling machines):

Select axis (X.... 9) for traversing

in a positive direction with the "+" key or

## 2.3 Machine control panel keys



in a negative direction with the "-" key



### Rapid

Move axis at rapid traverse (fastest speed).



### Machine manufacturer

- The specified increments and control range apply to standard machines.
- Increments and control range can be modified by the machine tool manufacturer to suit specific applications.
- Feedrate/rapid traverse and the values for the feedrate override switch settings (if the feedrate override switch is also operative in rapid traverse) are defined in a machine data.

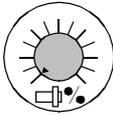
Please refer to the information and specifications provided by the machine manufacturer.



### WCS/MCS

Switch between the workpiece coordinate system (WCS = work) and machine coordinate system (MCS = machine).

### 2.3.4 Spindle control



### Spindle override (spindle speed override switch)

- The rotary switch with latch positions allows you to increase or decrease the programmed spindle speed "S" (equivalent to 100%).
- The set spindle speed value "S" is output as an absolute value and a percentage in the "Spindles" display (vertical softkey in basic display).

#### Control range:

50% to 120% of programmed spindle speed

#### Increment:

5% between latch positions



Spindle Stop

### Spindle stop

When you press the "Spindle Stop" key:

- the spindle is decelerated down to zero speed and
- the associated LED illuminates upon "Spindle Stop".

#### Example:

- to change a tool.
- to enter S, T, H, M functions during setup.



Spindle Start

### Spindle start

When you press the "Spindle Start" key:

- the spindle speed is accelerated to the value defined in the program and
- the associated LED lights up as soon as "Spindle Start" has been accepted by the control.



### Machine manufacturer

- The specified increment and the control range apply to standard machine data (MD). These MD can be changed by the machine-tool manufacturer to suit the application.
- The maximum spindle speed and the values for the spindle speed override position are defined in the machine data and setting data (see information supplied by the machine-tool manufacturer).

## 2.3.5 Key switch

### SIEMENS key switch

The key switch on the SINUMERIK 840D, 810D has 4 settings to which protection levels 4 to 7 are assigned.



### Machine manufacturer

Functions can be assigned to key switch positions by the machine manufacturer. Using machine data it is also possible to set access to programs, data, and functions to suit the user's requirements. The key switch has three different colored keys which can be removed in the specified positions:

## 2.3 Machine control panel keys

### Key positions



Position 0  
No key  
Protection level 7



Position 1  
Key 1 **black**  
Protection level 6



Position 2  
Key 1 **green**  
Protection level 5



Position 3  
Key 1 **red**  
Protection level 4

Lowest  
access authorization



Highest  
access authorization



### Changing access rights

The screen is not automatically updated after a change in access authorization (e.g. when the key switch position is changed), but only when the screen is next refreshed (e.g. on closing and opening a directory).

The currently valid access authorization is checked every time a function is executed.

If the PLC is in the stop state, the input image of the machine control panel is not scanned. For this reason the key switch positions are not evaluated during start-up.

### Passwords

Access authorization can also be set through the input of three passwords in the basic display of the "Start-Up" operating area. If the password is set, the key switch positions are irrelevant.



### References

/IAD/Installation & Start-Up Guide 840D or  
/IAC/Installation & Start-Up Guide 810D

### 2.3.6 Program control



#### Cycle Start

Start execution of a selected program:  
The associated LED illuminates.

#### Cycle Stop

Stop processing of a running parts program:  
The associated LED illuminates.  
Press the "Cycle Start" key to continue processing.

#### Single Block

Execute a part program block by block. You can activate the "Single Block" function in "Automatic" and "MDA" modes. If single block is activated, the associated LED on the machine control panel lights up. If single block execution is active,

- a stop in the cycle is displayed on the screen (in the program control display line),
- (in interruption status) in the channel operational messages line - the text "Stop: Block ended in SBL mode" is output,
- the current block of the part program is only processed once you press the "Cycle Start" key,
- the processing is stopped after execution of one block,
- you can execute the next block by pressing the "Cycle Start" key again.

You can deselect the function by pressing the "Single Block" key again.

The current status is shown in the program control display (global machine status display, see Chapter 2 Screen Layout)

This function is dependent on the settings under "Program control" in the Machine operating area.





### Reset

- Execution of the current program is aborted.
- Messages from the cycle monitoring are deleted (except for POWER ON, Cycle Start and "Acknowledge alarm" alarms).
- The channel is shifted to "reset" state, i.e.,
  - The NC control remains synchronized with the machine.
  - The control is in its initial state and ready for a new program run.
 (See also)

### References

/FB1/K1: Description of Functions Mode Group, Channel, Program Operation

### 2.3.7 Standard PC keyboard MF-II

A standard PC keyboard can be connected. However, a machine control panel is required in addition to this keyboard.

The special function keys on the operator panel front can also be used with the standard PC keyboard. The following table shows the keys on which the horizontal and vertical softkeys are mapped:

Standard PC Keyboard	F1	F2	F3	F4	F5	F6	F7	F8	F9	F10	F11	F12
with SHIFT	vertic Soft. 1	vertic Soft. 2	vertic Soft. 3	vertic Soft. 4	vertic Soft. 5	vertic Soft. 6	vertic Soft. 7	vertic Soft. 8				CUSTOM
without SHIFT	horiz Soft. 1	horiz Soft. 2	horiz Soft. 3	horiz Soft. 4	horiz Soft. 5	horiz Soft. 6	horiz Soft. 7	horiz Soft. 8				

Standard PC keyboard	Esc	Insert	Home	Page Up	Page Down	Enter	Tab		Num Block				
with SHIFT									5	1	3	7	9
without SHIFT							END						
switched off Num Block													

### Caution

The standard PC keyboard does not meet the requirements (EMC) of a SINUMERIK control. For this reason, it should only be used for installation and servicing purposes.

### 2.3.8 Mouse operability with HMI Embedded Win32



The HMI Embedded Win32 software with the PCU 50/70/ PC hardware can also be operated with a mouse.

#### Right mouse button functionality

Right clicking the mouse has the same effect as activating the area switchover key.

#### Left mouse button functionality

Single-click

- The dialog cursor is positioned on a closed IO field; input starts with the first character.
- If the IO field is open, it closes and the input is not validated. When you enter a value, the old value is deleted.
- If you click a character in an open field, the mouse pointer is positioned after the last character in the string.

Double-click

The field is opened in input mode, the editor cursor is positioned on the first character.

Drag depressed mouse button

The characters are highlighted according to the mouse position.

Click the scroll bar

Paging though

Double-click a program

Open the program

Click characters in open part program

Click selection field

Make next selection

Click check field

Invert field, make next selection



#### Note

This function is not supported on the PCU 20.

## 2.4 Screen layout

### 2.4.1 Overview



#### Softkeys

Keys to which functions are assigned by means of a menu bar displayed on the screen.

- It is possible to access further menu levels via the horizontal softkeys in any operating area. Each horizontal menu item has a vertical menu bar/softkey assignment.
- The vertical softkeys are assigned functions for the currently selected horizontal softkey.

A function is called up by pressing one of the vertical softkeys. The assignments of the vertical softkey bar can change if further subsidiary functions are classified under a function.

#### Global machine status display

Machine 1	CHAN1	4	JOG 6	\MPF_DIR ZZZ_STANDARDZYKLEN.MPF	7	15
Channel reset		2	FST		8	AUTO
Program aborted		3	MCS		9	MDI
MCS		Position		Master spindle S1		JOG
X1	0.000	mm	11	Act.	0.000 rpm	REPOS
Y1	0.000	mm		Set	0.000 rpm	REF
Z1	0.000	mm		Pos	0.000 deg	
A1	0.000	deg		11	100.000 %	
AX00	0.000	deg		Power [%]		
Feedrate mm/min		11		Act.	0.000 100.0 %	
				Set	0.000 11	
Tool				Preselected tool: 11		
				G01 G40		Single block
i 10	12	14	10 >		3D sin.	
Machine	Parameter	Program	Services	Diagnosis	Start-up	Cycles

1. Operating areas
2. Channel status
3. Program status
4. Name of channel
5. Alarm and message line
6. Operating mode
7. Program name/path of the selected program
8. Channel operational messages
9. Program control
10. Additional explanatory information (Help) recallable
  - i Information can be displayed via the i-key
  - ^ Recall: Return to higher-level menu
  - > ETC: Expansion of the softkey bar in the same menu.

#### 11. Working windows, NC displays

The working windows (program editor) and NC displays (feedrate, tool) available in the selected operating area are displayed here.

##### **From SW 6.2**

Positional data in the working windows show the diameter symbol  $\varnothing$  before the unit if the axis is currently the traverse axis and if the tool coordinate system is set. If diameter programming is disabled with DIAMOF, the symbol preceding the unit is no longer visible.

#### 12. Dialog line with operator notes. Operator notes for the selected function appear here (if available)

#### 13. Active window

The selected window is displayed by its own frame. The window header display is inverted. Data entered on the operator panel front apply to this window.

#### 14. Horizontal softkeys

#### 15. Vertical softkeys

The softkey functions available in the selected operating area are displayed in the horizontal and vertical softkey menus (corresponding to F1 to F8 on the full keyboard).

### 2.4.2 Global machine status display

1 Operating areas	The currently selected operating area is displayed (Machine, Parameters, Program, Services, Diagnosis, Start-Up).
2 Channel status	The current channel status is displayed, <ul style="list-style-type: none"> <li>• Channel reset</li> <li>• Channel interrupted</li> <li>• Channel active</li> </ul>
3 Program status	The current status of the running part program is output: <ul style="list-style-type: none"> <li>• Program aborted</li> <li>• Program running</li> <li>• Program stopped</li> </ul>

**2.4 Screen layout**

4 Channel name	Name of channel in which program is running.
5 Alarm and message line	<ul style="list-style-type: none"> <li>Alarms and messages or</li> <li>References that were inserted in the part program with the MSG command (if no alarms are active)</li> </ul>
6 Operating mode display	The currently selected operating mode, i.e. Jog, MDA or AUTO (automatic) is displayed.
7 Program name	This program can be executed with Cycle Start.
8 Channel operational messages	<ol style="list-style-type: none"> <li>Stop: No NC ready</li> <li>Stop: No mode group ready</li> <li>Stop: Emergency Stop active</li> <li>Stop: Alarm active with stop</li> <li>Stop: M0/M1 active</li> <li>Stop: Block ended in SBL mode</li> <li>Stop: Cycle Stop active</li> <li>Wait: Read-in enable missing</li> <li>Wait: Feedrate enable missing</li> <li>Wait: Remaining dwell time: ... secs</li> <li>Wait: Aux. funct. ackn. missing</li> <li>Wait: Axis enable missing</li> <li>Wait: Exact stop not reached</li> <li>Waiting for positioning axis</li> <li>Waiting for spindle</li> <li>Waiting for other channel</li> <li>Wait: Feedrate override to 0%</li> <li>Stop: Error in NC block</li> <li>Waiting for NC blocks from external</li> <li>Waiting due to SYNACT instruction</li> <li>Wait: Block search active</li> <li>Wait: No spindle enable</li> <li>Wait: Axis feedrate value is 0</li> <li>Waiting for tool change acknowledgement</li> <li>Waiting for gear stage change</li> <li>Waiting for position control</li> <li>Waiting for thread cut</li> <li>Wait:</li> <li>Waiting for punching</li> <li>Waiting for safe operation</li> </ol>

- 31 Stop: Channel not ready
- 32 Stop: Oscillation active
- 33 Stop: Axis replacement active (block change inhibited because axis replacement in progress)
- 34 Waiting for axis container rotation
- 35 Wait: AXCT axis active as slave axis
- 36 Wait: AXCT axis active as master axis
- 37 Wait: AXCT axis changing to follow-up
- 38 Wait: AXCT internal status change in axis
- 39 Wait: AXCT axis drive disable
- 40 Wait: AXCT axis overlaid motion active
- 41 Wait: AXCT axis, axis replacement active
- 42 Wait: AXCT axis interpolator active
- 43 WAIT\_FOR\_CC\_ENABLE: Waiting for compile cycle
- 44 Waiting for access to system variable
- 45 Stop; Serupro has found search target and the NCK has stopped.  
ERUPRO is the abbreviation for SEArchRUn by PROgramtest; it is a new type of block search. SERUPRO is activated via PI service "\_N\_FINDBL" parameter == 5; SW \$[[SW41000]] and later.
- 46 = Stop; ESR activated
- 47 Wait: Axis container rotation waiting for spindle stop
- 48 Wait: Axis container rotation waiting for MD data match (New-Config)
- 49 Waiting for axis replacement: Axis currently coupled
- 50 Waiting for axis replacement: Liffast active
- 51 Waiting for axis replacement: New-Config active
- 52 Waiting for axis replacement: Axis container rotation active
- 53 Waiting for axis replacement: Waitp active
- 54 Waiting for axis replacement: Axis is currently in another channel
- 55 Waiting for axis replacement: Axis is currently PLC axis
- 56 Waiting for axis replacement: Axis is currently reciprocating
- 57 axis
- 58 Waiting for axis replacement: Axis is currently jog axis
- 59 Waiting for axis replacement: Axis is currently command axis
- 60 Waiting for axis replacement: Axis is currently OEM axis  
Waiting for axis replacement: Axis is currently slave axis in master-value coupling
- 61 Waiting for axis replacement: Axis is currently coupled-motion axis
- 62 Waiting for axis replacement: Axis is currently coupled slave axis

9 Program control

Functions that have been activated are displayed (settable via "Program control").

## 2.4.3 Program control display



Only functions that have been activated are visible (settable via "Program control"). The channel status line is displayed irrespective of the selected menu.

**SKP**

Skip block

**References**

/PG/ Programming Guide Fundamentals, Chapter 2

**DRY**

Dry run feedrate

Traverse movements are performed with the feedrate value set in the setting data "Dry run feedrate". The dry run feedrate function replaces the programmed travel commands.

**ROV**

Rapid traverse override

The override switch for the feedrate also applies to the rapid traverse feedrate.

**M01**

Programmed stop

When this function is active, processing of the program is stopped at every block in which miscellaneous function M01 is programmed. The message "Stop: M00/M01 active" is then displayed on the screen. You restart processing with the Cycle Start key. If the function is not active, then the miscellaneous function M01 (from the part program) is **disregarded**.

**M101**

Halt at cycle end

According to option set.

**DRF**

DRF selection

When the "DRF" function is active, DRF offsets are applied.

**PRT**

Program test

In program test mode, set point outputs to the axes and spindles are disabled. The set point display "simulates" the traverse movements.

**FST**

Feed stop

The activated feed stop is displayed.



This function is not activated/deactivated under Program Control, but via the Feed Start/Feed Stop keys on the machine control panel.

## 2.5 General operating sequences



### Keys

A range of keys and menus is provided in the various operating areas. The function of the keys and menus is the same in all operating areas.

### Functions

The following section describes functions which you can select in several operating modes.

### 2.5.1 Program overview and program selection



#### Function

After selection of a workpiece or program overview, individual workpieces or programs can be enabled or disabled for execution.



#### Operating sequence

"AUTO" is selected in the "Services" or "Machine" operating area. The appropriate channel is selected. The channel is in reset state. The workpiece/program to be selected is in the memory.

An overview of all workpiece directories/programs that exist is displayed.

Position the cursor on the desired workpiece/program.

Select the workpiece/program for execution:

Select  
program

The name of the selected workpiece is displayed on the screen in field "Program name" at the top. The program is then loaded.

### 2.5.2 Selecting and opening directory/file



The "Direction keys" can be used to position the cursor on the desired directory/file.

If you enter a character on the alphanumeric keyboard, the cursor moves to the first name that begins with the character.



#### Open/close directory:

You can open a directory with the "Input" key.



Press "Recall" to close it again.



#### Open file:

You can open a file with the "Input" key if you wish to edit it in the ASCII editor. The editor is opened automatically.

### 2.5.3 Editor



#### Function

The editor is used to create, update and modify programs and texts (e.g. alarm texts).



#### Machine manufacturer

Please note the information supplied by the machine tool manufacturer!

#### Opening a second editor window:

You have the option of opening a second program and displaying this alongside the one already open on the screen.



#### Operating sequence



Press the ETC key. The horizontal softkey menu displays the "2<sup>nd</sup> file" softkey. After pressing the softkey, select another program and open it using the input key. Now both editor windows are displayed alongside each other on the screen.



Use the "Next window" key to toggle between the windows.

Enlarge window

Decrease window

Close editor



Settings

Editor settings

If you press the "Enlarge window" softkey, the program where the cursor is displayed over the whole screen.

If you press the "Decrease window" softkey, both editor windows are displayed next to each other.

### Close editor

The current program overview appears again when you activate the "Close editor" softkey.

Changes are saved in the program immediately when the cursor leaves the modified line.

### Editor settings

You can define the following values in the "Editor Settings" window:

- Enable a newly created program automatically when it is closed,
- Skip the "Line feed",  
See also Chapter 6: Selective Program Protection: RO
- Display hidden lines (HD) in the program,  
See also Chapter 6: Hidden program lines: display HD
- Shorten positioning time within a large file (e.g. in mold making).  
You can select a special procedure as well as specify file size up to 58 KB.

### Operating sequence

If you press the horizontal softkey "Settings"

and the vertical softkey "Editor settings" you get the following window:

Program	KANAL 1	JOG REF	MPF0	100 1519252
Channel reset		Program aborted		Setting editor
		ROV		
Program editor: \MPF.DIR\ACSSER.MPF				Setting contour
etms(1)]				Program overview
N5 NIX: G1 F50000 Z20 ;C20 U20 V20]				
N10 SPOS=0]				
N15 GB4 F4]				
Settings editor:				
Release of new programs <input type="checkbox"/> Yes				
Skip LF in program <input type="checkbox"/> Yes				
Show hidden program lines <input checked="" type="checkbox"/> Yes				
Enable active programs for editing <input type="checkbox"/> Yes				
Special handling in mold making <input checked="" type="checkbox"/> Yes 58 KB				
Accept altered settings with OK! Otherwise reject.				Abort
				OK

Contour  
settings

### Contour programming

The following settings are possible for contour programming:

- Specify the contour end, the entered line (e.g. "End of contour") is displayed after each contour.
- Specify the technology, turning or other
- Display the softkeys for contour elements as symbols or text.

For information on what to do next, see Chapter 6: Free contour programming

### 2.5.4 Changing menu window



Using the "Window selection" key, you can toggle between individual menu windows. You only need to do this if you wish to enter data on the operator panel front. The focus changes to the selected menu window (the header and border of the active window appear in a different display format).



#### Scroll in menu window:

If the contents of a window cover several screen pages, you can use the "Page" keys to scroll up or down through the information.

A scroll bar indicates that the contents of the window extend beyond the visible display.



#### Position cursor in menu window:

You can position the cursor at the desired point in the menu window with the "Direction keys".

## 2.5.5 Editing inputs/values

If you wish to edit inputs/values, the corresponding key is always displayed automatically on the right of the input field. The following input fields are available:



### 1. Option buttons (single selection button/multiple selection button):

You can use the "Select" key to activate or deactivate a selection field.

Multiple selector button  
(you can select several options  
or none)

Single selection button/option  
button (only one option can be  
active at a time)

= active

= active

= not active

= not active

### 2. Input fields:

Position the cursor on the input field and start to type. When you begin typing, you automatically switch to Insert mode.

Always confirm your input with the "Input" key. The value is accepted.



To explicitly alter an existing value, press the "Insert" key to switch to input mode.



Enter the value or word (e.g. file name, etc.) on the alphanumeric keypad.



In some fields you can choose between several preset values using the "Select" key.



- The editor displays only the characters which can be input via the operator panel front keyboard.

### 2.5.6 Confirming/canceling input



#### Confirming input:

Your inputs are accepted when you press softkey "OK". The selected function is executed. The window is closed, and you return to the call menu level.

#### Canceling input:

Your inputs are rejected if you select the "Abort" softkey. The selected function is aborted. The window is closed and you return to the menu level from which the window was called.

The response is the same on return from a function (vertical softkey bar).

The "Insert" key can also have an "Undo" function if you abandon the input/modification you have just entered. The cursor remains positioned in the currently selected field.

Switch from the horizontal menu level back to the call menu level.

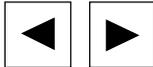
### 2.5.7 Editing a part program in the ASCII Editor



#### Function

The ASCII editor provides you with the following functions:

- Switch between insert and overwrite mode
- Mark, copy, delete block
- Paste block
- Position cursor / find/replace text
- Create contour (programming support)
- Configure cycle parameters (drilling, milling, turning)
- Start simulation
- Recompile (cycles, free contour programming)
- Renumber blocks
- Change settings



### Further information

A part program selected in the NC can generally only be edited when the channel is in the reset state.

When a part program is selected and the relevant channel in the "Channel Reset" state, the program can be fully edited.

### Operating sequence

The following functions are fully enabled in the Program operating area but only partially in operating areas Machine and Services. In the Machine operating area, the ASCII editor is called via the program editor, in Services, by selecting a file in the file manager.

You have selected the file you wish to edit in the directory and pressed the "Input" key, the vertical softkey bar changes. Your selected file is opened in the text editor.

#### Cursor block:

Use the "Direction keys" to position the cursor in the text.

You can page up and down using the "Page" keys.

The character on which the cursor is positioned is deleted.

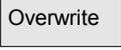
Press the "Delete" key to delete the character to the left of the cursor.

Press the "Input" key to end a block. The characters "LF" ("Line Feed") are automatically generated. The block will not be accepted for processing without a line feed character.

## Vertical softkeys

### Overwrite

The softkey toggles between insert and overwrite modes.



### Mark block

When you press this softkey, the vertical softkey bar changes. The area marked by the cursor is selected.



The selected block is copied to a buffer. It remains stored in the buffer even if another part program is selected.



The selected block is deleted.



You can cancel select mode with softkey "Mark block" or "Select". A block generated with the support function is not automatically selected.



or



A limit is applied to the block area which can be selected. When the limit is reached the following warning appears in the dialog line: "Buffer limit for selection reached".

### Paste block

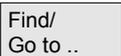
The softkey pastes the cut or copied block from the buffer into the text in front of the cursor position.



### Find/Go to...

The window "Find/Go to..." is opened.

You can select functions for positioning and searching via the vertical softkeys:



The following search methods are available:



or



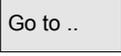

- to the beginning of the part program (cursor on the first character in the program),
- the end of the part program (cursor on the last character in the program) and



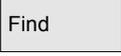
or




- to position on a particular NC block with "Go to.."



- or search for a particular character string with "Find".



"Go to...":

Enter the block number you are looking for.

- If the line being searched for contains an "N" or ":" you are taken to that block,
- If there is no block with the specified number, a message is output.

OK

Press softkey "OK" or the "Input" key to position the cursor on the block number/line number of your choice.

The "Go to..." window is closed.

Abort

If you abort positioning, the process is stopped and the window closed.

Find

"Find"

Enter the character string you wish to find.

The string you enter is sought downwards from the current cursor position, the find result appears as highlighted text.

Find  
next

or



You can start a new search by pressing softkey "Find next" or the "Input" key.

Replace

or



Enter the new text with the "Replace" softkey.

The text found is replaced by the "replacement text". The new text is replaced when you press "Input". Every time you press "Input", a new find and replace process is started.

Abort

If you abort Find + Replace, the process is stopped and the window closed. You are in "Edit mode" again.

Save file

### Save file

Changes are saved in the file loaded in the editor.

### Further information

Please note that the changes to programs stored in the NC memory take immediate effect.

Support

New  
contourAccept  
contour

### Horizontal softkeys

#### Free contour programming

You can call the free control programming function via softkeys "Support" and "New contour".

The part program block is inserted in the part program with the appropriate parameters.

Drilling

Milling

Turning

OK

### Cycle parameterization

The following programming support functions are available:

- Drilling, milling, turning (cycles)
- Contouring (free contour programming)

You can call up the relevant cycle compilation via the vertical softkeys Drilling, Milling, Turning.

The part program block is inserted in the part program with the appropriate parameters.

#### Example:

```
CYCLE81 (110, 100, 2, 35)
```

```
/PGZ/Programming Guide Cycles
```

### References

Simulation

### Simulation

The simulation function is called.

Pressing the Cycle Start key starts the graphics simulation.

See Chapter 6: Section on "Program Simulation"

### Cycle recompilation

If program steps (cycle/contour) have already been parameterized but must be changed, you can display and edit the parameter values with their meanings.

Position the cursor in the text editor on the line with the program step (contour/cycle) whose parameters you wish to change.

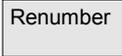




A screen form containing the parameter settings for the selected cycle/contour appears on the screen.



Change the parameters.



The part program block is automatically inserted in the part program with the new parameters.

The block numbering in the program shown in the editor is executed again according to the values defined under the "Settings" softkey. Once the softkey is selected another window opens. Specify the "Block number" and the "Increment".



### Machine manufacturer

The coordinate system and the technology to be used are set via the machine data. Please refer to the information and specifications provided by the machine manufacturer.



### References

//IAM/IM2, Installation & Start-Up Guide HMI Embedded

## 2.5.8 Channel switchover



It is possible to switch between channels when several are in use. Since individual channels may be assigned to different mode groups, a channel switchover command is also an implicit mode switchover command.

If the selected channel is located on another NCU (m:n link), the HMI Embedded is switched implicitly to this NCU.

When a "Channel menu" is configured, all existing communication links to other NCUs plus the associated channels are displayed on softkeys.

### Channel states

The following three channel states can occur in each mode:

#### 1. Channel reset

The machine is in the initial state, e.g. after power-on or after end of program. The initial state is defined by the machine-tool manufacturer in the PLC program.

**2. Channel active**

A program has been started, program execution or reference point approach is in progress.

**3. Channel interrupted**

The running program or reference point approach has been interrupted.

In this context a program can be a main program, subprogram, cycle or a series of NC blocks.

There are 3 different switchover levels:

1. Switch to next channel.
2. Switch over configured channel group/channels (1 NC).
3. Switch to another NC (with m:n link involving several NCs).

**2.5.9 m:n communication links****General**

An m:n link means that m-HMI Embedded-units and n-NCU/PLC-units are linked together. This does not however mean that all possible links are active.

An HMI Embedded is linked with only one NC at a given point in time (cf. 1:1 link) and communicates only with this NC. With an m:n link, the link can also be switched over to another NC. Using the channel switchover key and channel menu, you can switch the MMC over to another link.

You can change to the channel menu in all operating areas by activating the channel switchover key. The only change is to the horizontal and vertical softkeys.

Use the horizontal softkeys to select a channel group (max. 8), 8 links to channels on different NCUs can be set up in each channel group.

All current communication links and associated symbol names are listed in display "Channel menu".

**Important**

Only two links may be active simultaneously on one NCU.

**References**

/FB2/B3: Several Operator Panels and NCUs





### Function

You can set up a link in any operating area between the HMI unit and the connected NCU/PLC units via the operator interface.

Machine	CHAN1	JOG	\MPF.DIR ZZZ_STANDARDZYKLEN.MPF	
Channel reset				
Program aborted			FST	Channel 11
MCS		Position	Master spindle S1	Channel 12
X1	0.000	mm	Act. 0.000 rpm	Channel 13
Y1	0.000	mm	Set 0.000 rpm	Channel 14
Z1	0.000	mm	Pos 0.000 deg	Channel 15
A1	0.000	deg	100.000 %	
AX08	0.000	deg	Power [%]	
			Feedrate mm/min	
			Act. 0.000 100.0 %	
			Set 0.000	
			Tool	
			Preselected tool:	
			G01 G40	
MILL1	MILL2			

Activate the channel switchover key. The currently existing connection is displayed by means of the highlighted softkeys (horizontal, vertical) if the channel menu is active.

### Channel switchover

You can switch to other channels by means of the vertically arranged softkeys.

### Group switchover

Use the horizontal softkeys to switch over to a different group; the channels of the current group are now displayed on the vertical softkeys. Switchover to another channel (and if necessary to another NC) only takes place upon activation of a vertical softkey.

### NC switchover

You can change to another NC via the vertical softkeys if the channel is not on the current NC.



### Further information

- When you select a vertical softkey, you are selecting a channel and potentially an NC as well.
- Channels that are configured in the channel menu, but defined as a channel gap in the corresponding NC, will not be displayed.

### 2.5.10 Pocket calculator



#### Precondition:

The cursor is positioned on an input field or input/output field.

You can switch to **Pocket calculator mode** with the equals key. If you enter a basic arithmetic symbol (+, −, /, \*) followed by a value (e.g. 13.5) in this mode and

and then press the input key, the next value to be entered is calculated with the previous value.

If the input/output field is opened with the input or equals key, the editor is in insert mode; if the field is opened directly with a character, the editor is in write-over mode.

#### Help display

If pocket calculator mode is active, you can call a help display which explains how to operate the input editor by pressing the Info key.

### 2.5.11 Input of fits



#### Function

The letter "F" ("f") is used to identify a fit. The letter is followed by the diameter/length specification. This is followed by the tolerance class and the tolerance quality identifier.

The arithmetic mean is calculated from the upper and lower limiting value and displayed in the field.



### Note

Angle specifications are not supported.

### Example:

F20H7            This input stands for 20H7  
 or:    F20h7            This input stands for 20H7  
 or:  
 F        = fit  
 20       = Diameter/length specification (1... 500 mm)  
 H (h)   = tolerance class (tolerance classes for drill holes and shafts:  
           A, B, C, D, E, F, G, H, J, JS, T, U, V, X, Y,  
           Z, ZA, ZB, ZC)  
 7        = Tolerance quality identifier (01... 18, DIN standard 7150  
           limits the area!)

### Restrictions:

1. The diameter/length must be specified as an integer.
2. Quality identifiers 6, 7, 8 are available for class J.
3. For class j, only qualities 5, 6, 7 and 8 are available for diameter 1...3 mm.
4. Only qualities 8...18 are available for classes P, R, S; T, U, V, X, Y, Z, ZA, ZB, ZC, p, r, s, t, u, v, x, y, z, za, zb, zc.
5. Qualities CD, EF, FG, cd, ef, fg are only available for up to 10 mm.
6. According to the standard,
  - classes T, t are only available for diameters > 24 mm,
  - classes T, t are only available for diameters > 14 mm,
  - classes Y, y are only available for diameters > 18 mm,

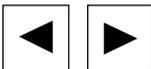
Recompilation of the value is not possible.

### Upper/lowercase notation:

The operator panel does not have separate keys for lowercase letters, but you can use the selection key to change between upper and lowercase notation.

Position the cursor on a letter in the input field and press the selection key to toggle between upper and lowercase notation.

When you have finished, press the ENTER key to confirm your input.



## 2.5.12 Blue screen error status screen



In the event of a system crash, an error status screen displays the current system information. The screen shows a brief description of the error and displays any relevant process registers.

You will find various options for saving system information in the following documentation:

**References:** /IAM/ Installation & Start-Up Guide HMI Embedded (IM2)



## 2.5 General operating sequences

## Operating Example



3.1 Typical operating sequence ..... 3-66

### 3.1 Typical operating sequence

To provide support for entry-level users or an orientation guide for others, this section uses a typical operating sequence (from control system power-up to back-up of a user-generated part program) to explain how the functions described can be located.

	Step	Described in Section
<b>Setup</b>	• Switch on machine	1.3
	• Homing	4.3
	• Clamp workpiece/blank	5
	• Select tools	5
	• Define workpiece zero for coordinate inputs	5.8
	• Enter tool offsets	5.2
	• Calculate speeds and feedrates	4.2
	• Define a reference point (scratching)	4.4
<b>Enter/test a program</b>	• Create a part program or read one in via an external Import data interface	6.4 7.5
	• Select a part program	4.6
	• Test a program (without a tool) <ul style="list-style-type: none"> <li>- Start a part program (e.g. in single block)</li> <li>- Edit part program using program editing function or diagnostics guide/help</li> </ul>	4.2 2.6/ 4.6 8.1
	• Optimize a part program	4.2
	<b>Machining the workpiece</b>	• Insert tool and run machining program
<b>Storing a program</b>	• Save a part program	6.7
	- on external storage devices	4.6
	- Read out via RS-232 interface	7.5



## Machine Operating Area

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4.6.7	Program control.....	4-112
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## 4.1 Data structure of the NC control

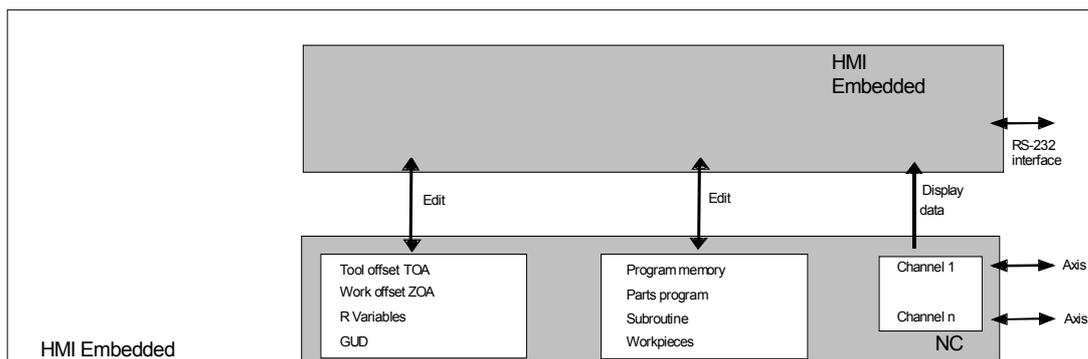


## Function

- NC with part program memory
- Part programs are processed in different channels (one program per channel).

## HMI Embedded

The data are always stored in the NC and changed directly in the NC.



## 4.1.1 Operating modes and machine functions



## Function

The Machine operating area includes all functions and parameters which initiate actions on the machine tool or measure its status.

There are three different modes in this area:

- Jog: "Jog" is the mode required for manual operation and setting up of the machine. The setup functions provided are "Reference point approach", "Repositioning", "Handwheel" or "Traverse in preset increments" and "Redefine control zero" (preset).

- MDA: Semi-automatic operation  
Part programs can be set up and processed block by block in this mode. The tested blocks can then be stored in the part program.
- In "Teach In" mode, positions can be traversed and stored to generate motion sequences which are then stored in the MDA program.
- Automatic: Fully automatic operation  
Part programs are executed fully automatically in "Automatic" mode, i.e. programs are selected, started, corrected, selectively controlled (e.g. single block) and executed in Automatic.

### Select machine area



You can switch to the "Machine" area at any time from any of the other operating areas simply by pressing the "Machine area" key.



When you switch on the control, it is usually in the operating area "Machine" in operating mode "Jog". (Please consult the machine manufacturer's documentation!)



### Machine manufacturer

The state after power-up can be configured and might therefore deviate from the default.

### Machine functions

In operating mode "Jog" you can select the following machine functions via the machine control panel or softkeys in the basic menu:



Inc (traverse in preset increments)



Repos (reposition at a defined position)



Ref (reference point approach to coordinate machine with the control zero points)



In "MDA" mode, it is possible to select "Teach In" (storage of motion sequences in a part program through position approach) by pressing the MCP key.

## 4.1 Data structure of the NC control

### Preparation for production

To start actual production some preparatory measures must be taken:

1. Set up the tools and workpiece,
2. Traverse the tools or workpiece to the start position required in the setup plan.
3. Load the part program in the control memory,
4. Check or input the work/zero offsets,
5. Check or input the tool offsets.

### 4.1.2 Operating mode group and channels



#### Function

Every channel behaves like an independent NC in which a maximum of one part program can be processed.

- Control with one channel:  
Only one operating mode group exists.
- Control with several channels:  
Channels can be grouped to form several "operating mode groups."

#### Example:

Control with 4 channels, where machining is carried out in 2 channels and 2 other channels are used to control the transport of the new workpieces.

Mode Group1	Channel 1 (machining)
	Channel 2 (Transport)
Mode Group2	Channel 3 (Processing)
	Channel 4 (Transport)

Technologically related channels can be combined in an operating mode group.

Axes and spindles of the same mode group can be controlled by one or more channels.

An operating mode group is either in "Automatic," "Jog" or "MDA" operating mode, i.e. several channels of one operating mode group can not assume different operating modes at the same time.

### 4.1.3 Selection of operating mode / changing operating mode



#### Function

The defined modes for operating a SINUMERIK control system are Jog, MDA and Automatic. They are selected via the MCP or by means of softkeys.



#### Machine manufacturer

Whether the requested mode can be accessed and the manner in which it is accessed can be configured machine-specifically in the PLC program.

#### Operating mode change

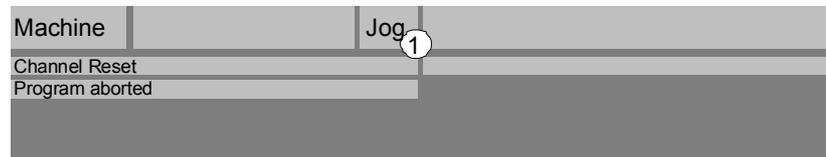
Not all mode changes are permitted. An error message is output if a mode change request is rejected by the system. The error message will indicate the error cause and possibly the remedy.



#### Operating sequence

##### Selection of mode

The selected mode is displayed in the mode field on the screen.



1 = operating mode



To select the modes

- Jog
- MDA
- Automatic

press one of the keys shown on the left on the machine control panel or

the corresponding vertical softkey that you can access via the "Area switchover" key:

## 4.1 Data structure of the NC control



AUTO

MDA

JOG

- Automatic
- MDA
- JOG

When a mode is selected, the LED next to the selection key on the MCP lights up. The same status is signaled in the mode field on the screen.

### Further information

The basic display of the selected mode appears on the screen.

If a mode change is not possible, please contact your installation engineer, the machine-tool manufacturer or our service personnel. In many cases, a mode change is enabled only for trained personnel for reasons of safety. To provide this type of protection, the control system offers a facility for disabling or enabling mode changes.

### References

/FB//K1: Mode Group, Channel, Program Operation

## 4.2 General functions and displays

### 4.2.1 Start/stop/abort/continue part program



#### Function

The following section describes how to start and stop part programs and to resume them after they have been aborted.

#### Operating sequence

"AUTO" mode is selected in the "Machine" operating area.

#### Precondition:

No alarms are pending.  
The program is selected.  
Feedrate enable is active.  
Spindle enable is set.

#### Start part program:

The part program is started and executed.

#### Stop/abort part program:

The program run is interrupted, but can be restarted with "Cycle Start"

The current program is aborted.

#### Resume part program:

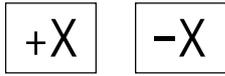
After a program interruption ("Cycle Stop") you can retract the tool in manual mode ("Jog") from the contour. The control saves the coordinates of the point of interruption. The distances traversed by the axes are displayed.

#### Repositioning:

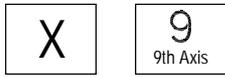
Select the "Machine" operating area.

Select "Jog" mode.

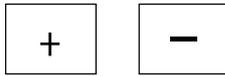
Press the "Repos" key to reposition the tool on the contour.

**Turning machine:**

Press the "+X" or "-X" key.

**Milling machine:**

Select the axis to be traversed and



Press the "+" or "-" key.

Traverse the axes to the point of interruption.

### 4.2.2 Display program level

**Function**

If subprograms are called while a part program is running, the block numbers for the main program and subprograms together with their pass number (P) can be displayed.

**Operating sequence**

"AUTO" mode is selected in the "Machine" operating area.

When you press the "Program level" softkey, the "Program level" window appears instead of the "Current block" window. The softkey labeling changes to "Current block".



During execution of a part program, the block numbers for the main program and subprograms, together with their pass number (P), are displayed in the "Program level" window. The main level is always visible, a nesting depth of up to 12 subroutines can be displayed.

Current  
block

When you press the "Current block" softkey, the "Current block" window containing the program blocks of the current part program is displayed again.

### 4.2.3 Switching between the machine/workpiece coordinate system (MCS/WCS)



#### Function

The display can be toggled between the machine and workpiece coordinate systems by means of special key "MCS/WCS" on the MCP or via softkeys (depending on MCP model and user program). The actual position display for the distance-to-go and the corresponding axes change.

#### Machine axes

Machine axes are axes that actually exist on the machine and have been parameterized during installation.

#### Geometry axes and special axes

These are the axes programmed in the part program. Geometry axes and special axes are offset by the selected zero offset relative to the machine axes.

Three is the maximum number of Cartesian geometry axes.

#### MCS

The machine coordinate system (= MCS) refers to the coordinates of the machine axes, i.e. all machine axes are displayed in the machine coordinate system.

Machine position	Repos offset
X	
Y	
Z	

#### WCS

An offset (e.g. zero offset, rotation) can be used to set up a relationship, e.g. with the workpiece clamp. This relationship defines the position of the workpiece coordinate system (= WCS) in relation to the machine coordinate system. The workpiece is always represented in a Cartesian coordinate system.

All geometry axes and special axes are displayed in the workpiece coordinate system.

Work position	Repos offset
X1	
Y1	
Z1	



### Machine manufacturer

Machine data are used to define whether the programmed frames are to be calculated when displaying the WCS (settable zero system = SZS display).

Please refer to the information and specifications provided by the machine manufacturer!



### Operating sequence

"Jog" mode is selected in the "Machine" operating area.

Act. val.  
MCS

The actual values of the machine axes and their positions are displayed.

The softkey label changes to "Act. val. WCS".

The machine coordinate system comprises all the physically existing machine axes. Reference points, tool and pallet change points are defined in the MCS.

Act. val.  
WCS

When you select softkey "Act. val. WCS", the geometry and auxiliary axes plus their positions appear in the "Position" window.

The softkey label changes to "Act. val. MCS".

The workpiece coordinate system is assigned to a specific workpiece. Settings in the NC program refer to the WCS.

Zoom  
act. val.

Once the softkey has been pressed, the display comes up in enlarged view.



You can get back to normal view via the Recall key.



WCS MCS

- You can also toggle between the workpiece and machine coordinate systems by pressing the "WCS/MCS" key on the MCP.
- The number of places displayed after the decimal point and units of measure can be set in machine data.



### Coordinate system for changing the actual value display

#### Function

Via the MD you can define whether the actual values are to be displayed

- without the programmed offsets = WCS or
- including programmed offsets = SZS (settable zero offset system).

#### Example:

Program	WCS display	SZS display
....		
N110 X100	100	100
N120 X0	0	0
N130 \$P_PFRAME=CTRANS (X, 10)	0	0
N140 X100	100	110
N150 ...		



#### References

/FB1/K2: Coordinate Systems...

### 4.2.4 Display axis feedrates



#### Function

In operating mode "Jog" or "MDA" or "AUTO", you can display the current feedrate, residual path information and the associated override data.



#### Operating sequence

"Jog" mode is selected in the "Machine" operating area.

Press the "Axis feedrate" softkey:

- On "MCS" the feedrate window with the current feedrates and the residual path information, as well as the associated override data, is displayed.
- On "WCS", the feedrate window is displayed for the axes that are subject to the interpolation, with current feedrate, residual path information and path override, as well as for the other axes with current feedrate, residual path information and single axis override.

You can use the "Page" keys to display other axes if required.

Axis  
feedrate



or



### 4.2.5 Display spindles



Spindle



or



#### Function

The current spindle values (actual speed, setpoint speed, position on oriented spindle stop and spindle override) can be displayed.

#### Operating sequence

"AUTO"/"MDA"/"Jog" mode is selected in the "Machine" operating area.

The "Spindle" window appears on the screen.

The window contains the spindle setpoint and actual value, position, setting of spindle override switch and spindle output.

The spindle load for 2 analog spindles in total can be displayed in the window.

Using the "Page" keys you can scroll up and down to display other spindles if any are configured.

#### Further information

- The "Spindle" window is displayed only if at least one spindle is configured.
- If a master spindle "S1" is configured, this is automatically displayed in the spindle window, even if it is not the first spindle.

### 4.2.6 Display help functions



#### Function

Auxiliary functions active in the selected channel can be displayed.

#### Operating sequence

"Auto"/"MDA"/"Jog" mode is selected in the "Machine" operating area.



Auxiliary functions

The "Auxiliary functions" window appears on the screen. Up to 3 M functions or 3 H functions can be displayed.

**References**

/PG/Programming Guide Fundamentals

### 4.2.7 Display G functions, transformations and swivel data record



**Function**

Active G functions and transformations can be displayed in the active channel.



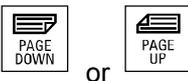
**Operating sequence**

"AUTO"/"MDA"/"Jog" mode is selected in the "Machine" operating area.



Transform./G functions

The window "Transform. + G functions" with the active G functions and transformations is displayed.



or

Using the "Page" keys you can scroll up and down to display other G functions.



**Further information**

Every G group has a fixed location.

The group number (no.) and the current G function of the G groups are displayed only if a G function is active.



**References**

/PG/Programming Guide Fundamentals

**Swivel data status display**

**Precondition:**

The swivel function (CYCLE800) has been set up by the machine manufacturer.

The active swivel data record (orientable toolholder TOOLCARRIER) is displayed concurrently with the transformations.

The following values are displayed:

TCARR = 1 .. n\*                    \*n max. no. of set swivel data (TOOLCARRIER) that are active.



**References**

/PGZ/Programming Guide Cycles: Chapter 3 "Swiveling"

### 4.2.8 Handwheel



#### Function

Using the "Handwheel" function, you can assign an axis to the handwheels and activate them.



#### Operating sequence

"Jog" mode is selected in the "Machine" operating area.

The "Handwheel" window appears on the screen.

Position the cursor on the handwheel of your choice (1–3).

Handwheel



An axis identifier is suggested in the "Axis" field. All other existing axes can be selected via the "Select" key. The settings are accepted immediately and an axis is assigned to each handwheel (1–3).



Every time you press the "Select" key in the "Active" field you activate or deactivate enabling of the relevant handwheel. The settings become active immediately.

When you turn the handwheel, the assigned axis traverses by the number of increments set for it ("Inc" keys).



#### Machine manufacturer

The machine-tool manufacturer is responsible for the design of handwheels. Operation may therefore differ from the explanation above.

Please refer to the information and specifications provided by the machine manufacturer.

### 4.2.9 Preset



#### Function

The "Preset" function can be used to redefine the control zero in the machine coordinate system.

The preset values act on machine axes.

Axes do not move when "Preset" is active.



### Danger

After the actual value has been reset, none of the protection zones or software limit switches are operative! Only after another reference point approach are the protection zones and software limit switches active again.



### Further information

A new position value is entered for the current axis positions. Please refer to the information and specifications provided by the machine manufacturer.



Machine manufacturer



### Operating sequence

"Jog" mode is selected in the "Machine" operating area.

Preset

The "Preset" window appears on the screen.

Enter the new actual value, which must in the future correspond to the current axis position for each individual axis. By doing so, you are redefining the control zero in the MCS. When the control zero is redefined, the tool change point, for example, also changes.



### Further information



Machine manufacturer

The "Preset" function can be disabled by means of protection levels (keyswitch position).

#### 4.2.10 Set actual value



### Function

The "Set actual value" function sets the workpiece coordinate system to a defined actual coordinate and calculates the resultant offset between the old and a newly entered actual value in the WCS in the 1st basic offset.

The "Set actual value" function can only be used if the control is in the workpiece coordinate system.

The functions are stored under the same softkey.



### Machine manufacturer

Please refer to the information and specifications provided by the machine manufacturer.



### References

/IAM/ Installation & Start-Up Guide /IM2, HMI Embedded



Set actual  
value

1 9



Set actual value assigns the 1st base offset, rough.

### Operating sequence

The new setpoint position of the axes in the workpiece coordinate system can be entered using "Set actual value" in the actual value window. When you transfer a value to the system by pressing "Input", the deviation from the current actual value is entered in the basic offset. The new actual value is displayed in the "Position" column.

Machine	CHAN1	JOG	\MPF_DIR CMM_SINGLE.MPF
Channel reset			
Program aborted			
Work	Position	Repos	offset
X	0.000 mm		0.000
Y	0.000 mm		0.000
Z	-20.000 mm		0.000
A	0.000 deg		0.000
B	0.002 deg		0.000
Masterspindel			
Act.		0.000 rpm	
Set		0.000 rpm	
Pos		0.000 deg	
Power [%]		100.000 %	
Feedrate mm/min			
Act.		0.000 100.0 %	
Set		0.000	
Tool			
Zent2		D1	
Preselected tool:		Zent2	
G01		G40	
Delete Basic WO			
OK			

Delete  
Basic WO

OK

"Delete Basic WO" can be selected to undo all the previously entered offset settings.

Confirm with "OK".

### 4.2.11 Inch/metric switchover



#### Machine manufacturer



Switch  
mm > inch



#### References

#### Function

The control system can operate with the inch or the metric system of measurement. You can switch between the inch and metric measuring systems in the "Machine" operating area. The control converts the values accordingly.

The switchover is only possible if:

- The corresponding machine data have been set.
- All channels are in the Reset state.
- Axes are not traversing with JOG, DRF or PLC control.
- Constant grinding wheel peripheral speed (GWPS) is not active.

The display resolution for the inch system of measurement is defined by machine data.

Actions such as parts program start or mode change are disabled for the duration of the switchover.

#### Operating sequence

"AUTO"/"MDA"/"Jog" mode is selected in the "Machine" operating area.

Press the ETC key followed by

the "Switch mm > inch" softkey.

When the system of measurement is changed, all length-related parameters are automatically converted to the new system of measurement from the perspective of the operator.

If the switchover cannot be performed, this is indicated by a message in the user interface.

/FB1/G2: Section: Metric/Inch System of Measurement

## 4.2.12 Actual value display: Settable zero offset system, SZS

**Function**

You can make a setting in the MD to define whether

- the position of the workpiece coordinate system, WCS (= programmed position, corresponds to default setting) or
- the tool holder position of the active tool relative to workpiece zero (settable zero offset system)

is to be displayed in the actual value display.

For configuring instructions see:

/IAM/IM2, Installation & Start-Up Guide HMI Embedded:  
Chapter "Zero Offset"

**References**

## 4.3 Reference point approach

**Function**

The "Ref Point" function ensures that the control and machine are synchronized after power ON.

Before a reference point approach can be carried out, the axes must be located at positions (if necessary, traversed to these positions using the axis keys/handwheels) from where the machine reference point can be approached without collision.

If reference point approach is called from a part program all axes can be traversed simultaneously.

Reference point approach can only be performed by machine axes. The actual value display does not match the real position of the axes when the control is switched on.

**Caution**

- If the axes are not safely positioned, you must traverse them to safe positions in "Jog" or "MDA" mode.
- You must follow the axis motions directly on the machine!
- Ignore the actual value display until the axes have been referenced!
- The software limit switches are not active!

**Machine manufacturer**

Please refer to the information and specifications provided by the machine manufacturer.



### Operating sequence

"Jog" or "MDA" is selected in the "Machine" operating area.  
The channel for reference point approach is selected.

The "Ref Point" machine function is selected.

#### Turning machine:

Press the "Axis" keys.

#### Milling machine:

Select the axis to be traversed and

press the "+" or "-" key.

The selected axis moves to the reference point. The direction and sequence is defined by the machine-tool manufacturer in the PLC program.

If you have pressed the wrong direction key, the action is not accepted and the axes do not move.

The display shows the reference point value.

No symbol is displayed for axes that do not refer to a reference point.

- This symbol appears for axes that must be referenced.
- This symbol is displayed next to the axis when the reference point has been reached.



The axis, once started, can be stopped before it reaches the reference point.

#### Turning machine:

Press the "Axis" keys.

#### Milling machine:

Select the axis to be traversed and

press the "+" or "-" key.

The selected axis moves to the reference point.



### Caution

The machine is synchronized as soon as the reference point is reached. The actual value display is set to the reference point value. The display is the difference between the machine zero and the slide reference point. From now on path limits, such as software limit switches, are active.

You can end the function by selecting another operating mode ("Jog", "MDA" or "Automatic").

- All axes of a mode group can approach the reference point simultaneously (depending on the PLC program of the machine-tool manufacturer).
- The feedrate override is active.



### Machine manufacturer

Your machine manufacturer will instruct you how to select axes if you intend to enter more than nine.



### Further information

The sequence in which axes must be referenced can be defined by the machine-tool manufacturer.

The machine can be started in Automatic mode only when all axes with a defined reference point (see machine data MD) have reached it.

## 4.4 Jog operating mode

### 4.4.1 Function and basic display



or



#### Function

In manual mode you can:

1. Synchronize the measuring system of the control with the machine (reference point procedure).
2. Set up the machine, i.e. activate manually controlled motions on the machine using the keys and handwheels provided on the machine control panel.
3. Activate manually controlled motions on the machine using the keys and handwheels provided on the machine control panel while a part program is interrupted.

The following basic display "Jog" is displayed when you press the "Area switchover" key and the "Jog" key.

The "Jog" basic display contains values relating to position, feedrate, spindle and tool.

Machine	CHAN1	JOG	\MPF.DIR CMM_SINGLE.MPF	
Channel reset				Trans./G function
Program aborted				
Work	Position	Repos offset	Master spindle S1	Auxiliary function
X	0.000 mm	0.000	Act. 0.000 rpm	Spindles
Y	0.000 mm	0.000	Set 0.000 rpm	
Z	-20.000 mm	0.000	Pos 0.000 deg	Axis feedrate
A	0.000 deg	0.000	100.000 %	
B	0.002 deg	0.000	Power [%]	
			Feedrate mm/min	
			Act. 0.000 100.0 %	
			Set 0.000	Zoom act. val.
			Tool	
			▶Zent2 D1 ◀	Act. val. Mach(MCS)
			Preselected tool:	
			▶Zent2 ◀	
			G01 G40	
	Set act. value	Scratch		Handwheel
				INC

### Explanation of the Jog basic display



Motion symbol in actual value window: The axes are still moving, i.e. they are not within the exact stop window.



WCS  
+ X2\*  
Y2\*  
Z2\*

Displays the addresses of the existing axes with the machine axis identifier (MCS) or with the geometric axis identifier (WCS).  
(see also Section "Toggling between Machine/Workpiece Coordinate System (MCS/WCS)")



### Machine manufacturer

Machine data are used to define whether the programmed frames are to be calculated when displaying the WCS (settable zero system = SZS display). Please refer to the information and specifications provided by the machine manufacturer.



- If the axis identifier can only be displayed in an abbreviated form it is replaced by the character \*.
- If you traverse an axis in the positive (+) or negative (-) direction, a plus or minus sign is shown in the relevant field.  
The axis is in position if neither + nor – is displayed in the position display.

### Position

0.0  
0.1  
-0.1  
1.1  
0.0

The actual position of each configured axis in the machine (MCS) or work (WCS) is displayed in these fields.  
The sign is only displayed for negative values.

### Repos. offset

0.0  
0.1  
-0.1  
1.1  
0.0

If the axes are traversed in the "Program interrupted" status in "Jog" mode, the path traversed by every axis with respect to the point of interruption is displayed in the REPOS offset.

### Spindle rpm

#### Spindle window (if spindle is available)

Displays the set and actual value of the spindle speed, the position of the spindle, the position of the spindle override switch , and the spindle power.

Feed  
mm/min

Tools

Zoom  
act. val.

### Nibbling

The spindle window is replaced by a nibble window if the "Nibbling" technology option is set.

The active function, if any, appears at the top left in the window header:

- PON      Punching ON
- SON      Nibbling ON
- SPOF     Punching/nibbling OFF

The following values are displayed:

- "Section" and "Number of strokes" are displayed inverted, if you have programmed "Length of section" or "Number of sections" at the automatic block partition.
- The "Time delay" is only displayed if you have set "Punching with time delay".

### Feedrate window

Display of the setpoint and actual value of the feedrate as well as the



position of the feedrate override switch (in %). The actual setpoint to be traversed is dependent on the override switch.

When G00 (rapid traverse movement) is programmed, the rapid override value is displayed.

### Tool window

Display of active tool offset (e.g. D1), tool currently in use (T no.), pre-selected tool (on milling machines) plus currently active travel commands (e.g. G01, SPLINE, ...), or tool radius compensation not active (e.g. G40).

Increases the size of the actual-value display.

## 4.4.2 Traversing axes

### Traversing speed

The initial settings for traversing velocity and feed mode are stored in setting data for JOG mode.

Traversing velocities are defined by the machine-tool manufacturer.

The default setting for the feedrate is mm/min.

See operating area "Parameters/Setting data/Jog data".



### Operating sequence

"Jog" mode is selected in the "Machine" operating area.

#### Traverse the axes

Using the "Inc" (increment) function, manually traverse the selected axis in preset increments in the appropriate direction by pressing an "Axis key" repeatedly:

- [.] Variable increment can be set via softkey "Inc" (see Subsection 3.2.5).
- [1], [10], ..., [10000] fixed increment



#### Turning machine:

Press the "Axis" keys.

If necessary, set the speed with the override selector.

If you press "Rapid traverse override" at the same time, you can traverse the axis in rapid traverse mode.

#### Milling machine:

Select the axis to be traversed and

press the "+" or "-" key.

Feedrate and rapid traverse override switches can be operative.

One or several axes can be selected at the same time (depending on PLC program).





### Machine manufacturer

#### Further information

- When the control is switched on, axes can be traversed to the limits of the machine because they have not yet been referenced. Emergency limit switches might be triggered as a result.
- The software limit switches and the working area limitation are not yet operative!
- The feedrate enable must be set (FST display must not light up in the program control display).

If no advantage is to be gained from moving several axes simultaneously, the machine manufacturer must implement the appropriate interlock in the PLC program.

#### 4.4.3 Inc: Incremental dimension



INC

Abort

OK

→  
[VAR]

#### Function

The "INC" (Increment) function can be used to enter a settable increment value for Inc variable traversing.

#### Operating sequence

"Jog" mode is selected in the "Machine" operating area.

The "Increment traverse keys" window appears on the screen.

Enter the desired "INC-Var" increment size

Go to the previous screen form again without accepting value.

Click on "OK" to save.

Press this key in manual mode together with the "Axis" key to traverse the axis in increments of the size set above in the appropriate direction (see also Section "Traversing axes").

Increment keys with preset increment sizes are temporarily inoperative.

## 4.4.4 Repos

**Function**

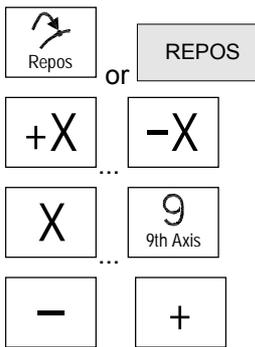
After a program interruption in automatic mode (e.g. to take a measurement on the workpiece or to compensate tool wear values or after tool breakage), you can retract the tool manually from the contour after selecting "Jog" mode. In such cases, the control stores the coordinates of the point of interruption and displays the path distances traversed by the axes in "Jog" mode as a "Repos" offset (Repos = repositioning) in the actual value window.

"Repos" offsets can be displayed in the machine coordinate system (MCS) or workpiece coordinate system (WCS).

**Operating sequence**

"Jog" mode is selected in the "Machine" operating area. The axes have been moved away from the point of interruption.

Select machine function "Repos".

**Turning machine:**

Press the "Axis" keys.

**Milling machine:**

Select the axis to be traversed and press the "+" or "-" key.

It is not possible to pass over the point of interruption. The feedrate override switch is active.

**Warning**

The rapid traverse override switch is active.

Non-adjusted Repos offsets are adjusted on switchover to Automatic mode followed by start with program advance and linear interpolation.



#### 4.4.5 SI (Safety Integrated): User confirmation



##### Function

If the "User enabling" option is installed on the NC, you must enable or disable the function depending on the keyswitch position in the "Approach reference point" operating mode.

User enabling can only be granted if keyswitch position 3 or higher is selected for the keyswitch position.

The displayed values always refer to the machine coordinate system (MCS).



##### Operating sequence

"Jog Ref" mode is selected in the "Machine" operating area.  
The channel to be referenced is already selected.

User  
confirmation

Press softkey "User confirmation".

The "Confirm machine positions" window is opened.

The machine axes in the MCS are displayed, together with the current position and a checkbox for activating/deactivating the user confirmation.



Place the cursor on the required machine axis.

Activate or deactivate the user confirmation for the selected machine axis via the "Select" key.



Check whether a reference point approach has been performed on the relevant axis. If not, error message "Please reference axis first" is displayed. User agreement cannot be activated for the axis until it has been referenced.



##### Further information

The function user enabling is only provided if user enabling is required for at least one axis of the channel.

For more information please refer to:

/FBSI/, Description of Functions SINUMERIK Safety Integrated.



##### References

#### 4.4.6 Determine scratching/zero offset



Scratch

### Function

You can determine the zero offset by "scratching", taking an (active) tool and, if necessary, the basic offset into account.

A window is provided for the "Scratching" function.

### Operating sequence

1. Press softkey "Scratch":
  - The active plane is displayed and can be altered (via "Select" key).
  - The active WO is displayed and can be altered (via "Select" key).
  - The active tool is displayed. No tool is displayed if none is active (message).

Machine	CHAN1	JOG	\MPF_DIR CMM_SINGLE.MPF	
Channel reset				
Program aborted			Swivel Adjust	
Work	Position	Repos offset	Master spindle S1	
X	0.000 mm	0.000	Act.	0.000 rpm
Y	0.000 mm	0.000	Set	0.000 rpm
Z	-20.000 mm	0.000	Pos	0.000 deg
A	0.000 deg	0.000		100.000 %
B	359.999 deg	0.000	Power [%]	
Scratch				
Plane	G17 <input checked="" type="checkbox"/>	T no.	Zent2	
Work offset	G500 <input checked="" type="checkbox"/>	Cut edge		D1
Axis	Offset	Setpt. pos.	Approach dir.	Tool offset
X	0.000	-->   <input type="checkbox"/>	R	5.000 mm
Y	0.000	-->   <input type="checkbox"/>	R	5.000 mm
Z	0.000		L1	20.000 mm
A	0.000			deg
				Abort
				OK

Meanings of columns in the "Scratch" window:

- "Offset": Current value of offset to be determined. The coarse offset is displayed. The fine offset is taken into account and remains valid.
- "Set position": Input of subsequent setpoint position for scratched edge.

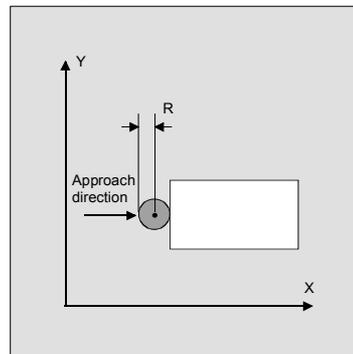
"Approach direction": Selection fields for positive/negative approach direction.



Use the cursor to select the first axis to be moved in the "Scratch" display.

2. Move the axis up to the workpiece, enter the chosen setpoint position (e.g. "0") and press the "Input" key. The offset is then calculated.  
Repeat the process for other axes.
3. Press "OK" to transfer all values to the selected WO. The offset is always calculated in relation to the current work (WCS).
4. To change the direction of approach, position the cursor on the axis to be modified in the "Approach direction" column and press the "Select" key.

Example:



Set "+R" using the "Select" key.

The values defined by scratching are displayed in the basic screen "Overview of WO" under system frame "Set zero position" if G500 was selected as work offset. Otherwise, the data are saved in the "selected settable WO".



#### Machine manufacturer

Please refer to the information and specifications provided by the machine manufacturer!

#### Scratching in swiveled plane (NC software version 6.3 and higher)

##### Precondition:

The swivel function (CYCLE800) has been set up by the machine manufacturer.

The "Activate swivel data" softkey is only displayed if a TOOLCARRIER is active.

The "Swivel Adjust" softkey is used to declare the swiveled plane as the new "zero" plane for the active swivel data record (TOOLCARRIER).

In this case, when you select "Swivel", positioning is at this swiveled plane with rotation through

X=0

Y=0

Z=0

The following messages are output for checking purposes:

"Swivel: Adjustment terminated"

"Swivel: Adjustment not possible"



## References

/PGZ/ Programming Guide Cycles, Chapter 3 "Swiveling"

### 4.4.7 Displaying system frames

If system frames are activated via MD, they can be displayed via the Parameter operating area, Work offsets.

The following assignment is applicable:

\$P_SETFR	System frame for actual value setting, scratching
\$P_EXTFR	System frame for work offset external
\$P_PARTFR	System frame for TCARR and PAROT
\$P_TOOLFR	System frame for TOROT and TOFRAME
\$P_WPFR	System frame for workpiece reference points
\$P_CYCFR	System frame for cycles

Both the offset set via frames (coarse and fine) and the rotation and mirroring defined there are displayed. Display is according to the position in the frame chain.

The following figure shows an example screen layout:

Machine	CHAN1	Jog	MPF.DIR CHIRON.MPF				
Channel RESET							Axis +
Program aborted			ROV	FST			Axis -
Work offset (WO) overview							
	Axis		X	Y	SP1		
Settable WO	Rotation (in °)		0.000	0.000			
	Scale		1.000	1.000	1.000		Offset
	Mirroring		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>		
Programmed WO	Rotation (in °)		0.000	0.000			
	Scale		1.000	1.000	1.000		Basic WO
	Mirroring		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>		
Total basic WO	Rotation (in °)		0.000	0.000			
	Scale		1.000	1.000	1.000		Settable WO
	Mirroring		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>		
Resulting WO	Rotation (in °)		0.000	0.000			
	Scale		1.000	1.000	1.000		Overview
	Mirroring		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>		
External WO	Rotation (in °)		0.000	0.000			
	Scale		1.000	1.000	1.000		
	Mirroring		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>		
Tool offset	R variable	Setting data	Work offset	User data			



### Machine manufacturer

Please refer to the information and specifications provided by the machine manufacturer.

## 4.5 MDA operating mode

### 4.5.1 Function and basic display

In "MDA" (Manual Data Automatic) mode, you can write part programs block by block and execute them. You can transfer the required motions as single part program blocks to the control using the operator panel.

The control starts processing the entered blocks when you press the "Cycle Start" key.



#### Caution

The same safety interlocks must be applied as used in fully automatic operation. The same preconditions must be fulfilled as for fully automatic operation.

The automatic functions (traverse blocks) are active in "MDA" mode.

#### Teach In

The functions associated with "Jog" are active in submode "Teach In" and can be accessed via an MCP key. You can therefore create and store a program in the input and manual modes by alternating between "MDA" and "Teach In".

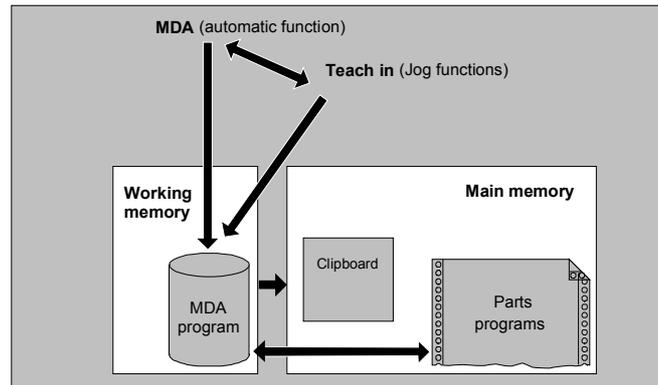
You can use the editor to edit the program blocks in the MDA window. You can view blocks that have already been processed by paging upwards.

Blocks that have already been executed can only be edited in the Reset state.

Further blocks can be added with "Input".

Blocks can be input and operated only with the channel in the "Channel Reset" or "Channel interrupted" state.

The program created in MDI mode is saved in the "MPF" directory as a part program (MPF).



The "MDA" basic display contains values relating to position, feedrate, spindle and tool as well as the contents of the MDA clipboard.

Machine	CHAN1	MDA	SYF_DIR OSTORE1.SYF
Channel active			Trans. + G fct.
Program running			Auxiliary func.
MCS	Position	Dist.-to-go	Master spindle S1
-X	90.301 mm	9.699	Act. + 0.000 rpm
+Y	80.081 mm	9.919	Set 0.000 rpm
+Z	0.000 mm	0.000	Pos 0.000 deg.
+V	0.000 mm	0.000	0.000 %
Power [%]			<input type="text"/>
MDA program		Feedrate mm/min	
N51 Y0 H55=99		Act. 7000.000 0.000 %	
Y120 F7000		Set 7000.000	
		Tool	
		Preselected tool: ◀	
		▶ G0 G91	
Program control			Handwheel
Delete MDA buffer			Save MDA program

### Explanation of "MDA" basic display

Save MDA program

Analogous to the Jog basic display, the actual value window, spindle window, feedrate window and tool window are output.

The "Save MDA program" softkey stores the MDA program in the "MPF" directory.

### Vertical softkeys

Like the Jog basic display, the MDA contains the "Trans. + G fct." "Auxiliary functions" and "Spindles" softkeys (if spindle is configured).

Delete MDA prog.

The contents of the MDA program in the NC are erased.

### 4.5.2 Save program



Save MDA  
program

#### Function

A program created in MDI can be temporarily stored in directory "MPF" and permanently

- incorporated as a program or
- read out to an external device via the RS-232 C interface.

The system will ask you to enter a name for the file to be saved to the MDA program.

The program is saved/stored as a part program (MPF.dir) under the specified name in directory "MPF".

### 4.5.3 Teach In



Teach In

#### Function

With the "Teach In" function, part programs (main programs and subroutines) for motion sequences or simple workpieces can be created, modified and executed by approaching and then storing positions in combination with the function "MDA".

There are two possible methods of writing programs with "Teach In" and "MDA":

- Manual positioning.
- Manually inputting the coordinates and additional information.

Both entry of blocks (input, delete, insert) and automatic insertion by manual approach of positions are possible only at points that have not yet been executed.

#### 1. Manual positioning

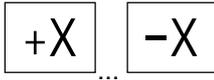
#### Operating sequence

"MDA" mode is selected in the "Machine" operating area.

The program is not running.

Submode "Teach In" is selected.

After selecting the function, the cursor is located in the first blank line of the "Teach In program" window.

**Turning machine:**

Press the "Axis" keys.

**Milling machine:**

Select the axis to be traversed

and then press the "+" or "-" key.

The axis name and the path being traversed are displayed continuously on the screen in the "Teach In program" window. The axis name and axis positions are transferred to the MDA program as values referred to the workpiece coordinate system.

**Saving the position value:**

The position values of the axes can be altered in the clipboard until this block is saved with the "Cycle Start" key.

When you use the "Save block" function for the first time you will be asked to enter the name of the teach program.

The teach program is now set for the duration of the MDA/Teach in procedure.

After "Jog" or "AUTO" mode has been selected, a new Teach program can be set.

**Additional functions:**

Place the cursor at the desired position in the "Buffer" window.

Enter the additional functions (e.g. feedrates, miscellaneous functions, etc.) in the program (if permitted).

**Delete/insert/save block:**

Position the cursor at the desired point.

The block is deleted automatically.

The block stored in the delete memory is automatically inserted in front of the line in which the cursor is located.

New position values and miscellaneous functions are saved.



When "Cycle Start" is pressed, the appropriate travel motions and functions additionally entered are executed as program blocks. While the program is being processed, the blocks traversed by the NC are displayed in the "Current block" window.

## 2. Manual input of coordinates

### Operating sequence

"MDA" mode is selected in the "Machine" operating area.

#### **Save position values/additional functions:**

Transfer the coordinates of the traversing positions plus any additional functions (preparatory functions, auxiliary functions, etc.) in the program by entering them in the "MDA program" window.

### Further information

- Changes to the zero offset cause the axis to execute compensatory motions after Cycle Start.
- In the case of G64, the end point response will differ when the part program is executed in "Automatic" mode.
- All the G functions can be used.

## 4.6 Automatic mode

### 4.6.1 Function and basic display

#### Prerequisites

You can execute part programs fully automatically in "Automatic" mode; this is the normal operating mode for part machining. The following conditions must be fulfilled before you can execute part programs:

- You have already synchronized the control measuring system with the machine (i.e. "approached" reference points).
- You have already loaded the associated part program in the control.
- You have checked or entered the necessary offset values, such as work offsets or tool offsets.
- The required safety interlocks are already active.

The "Automatic" basic display contains values relating to position, feedrate, spindle, and tool as well as the block currently being processed or program pointer.

Machine	CHAN1	AUTO	\MPF.DIR CMM_SINGLE.MPF		Trans./G function		
Channel reset							
Program aborted							
MCS	Position	Dist-to-go	Master spindle S1		Auxiliary function		
X1	0.000 mm	0.000	Act.	0.000 rpm	Spindles		
Y1	0.000 mm	0.000	Set	0.000 rpm			
Z1	0.000 mm	0.000	Pos	0.000 deg	Axis feedrate		
A1	0.000 deg	0.000		100.000 %			
B1	359.996 deg	0.000	Power [%]				
Actual block	CMM_SINGLE.MPF		Feedrate	mm/min	Program blocks		
↑			Act.	0.000 100.0 %			
↑			Set	0.000	Zoom act. val.		
PROC CMM_SINGLE SBLOF↑			Tool				
			Zent2 D1		Act. val. Work (WCS)		
			Preselected tool: Zent2				
			G01 G40		Program level		
Over- store		DRF offset	Program control	Block search	Handwheel	Correct program	Program overview

#### Explanation of basic display

Like the Jog display, the Automatic display contains actual value, spindle window, feedrate and tool windows.

If the NC detects G0 during part program execution, the current value of the rapid traverse override is displayed in the "Feedrate" window.



Program  
overview

### Horizontal softkeys

The workpiece or program overview is displayed. In this area it is possible to select programs for execution.

Current  
block

### Vertical softkeys

The "Current block" window is also displayed.

The current block is highlighted while the program is running.

The name of the program to which the blocks on the screen belong is output in the window header.

Program  
level

When you press the "Program level" softkey, the window headed "Program level" appears instead of the "Current block" window.

The program nesting depth (P = number of passes) is displayed.

Program  
level

or

Current  
block

In program operation it is possible to toggle between the "Program level" and "Current block" displays.

Program  
blocks

Seven program blocks of the current program are displayed together with the current position in the part program.

The 7-block display always shows the programmed part program and not the actual program run. In particular with subroutine calls, the block displayed as next block after the UP is only the block which is executed after the UP call, not the first block of the subprogram (program execution).

### Further information

The other softkeys are described in the sections below.

## 4.6.2 Execute program



Program  
overview



### Function

After selection of a workpiece or program overview, individual workpieces or programs can be enabled or disabled for execution.

### Operating sequence

The "Auto" operating mode is selected in the "Machine" operating area.

The appropriate channel is selected.

The channel is in reset state.

The workpiece/program to be selected is in the memory.

When you press softkey "Program overview", the software automatically changes to the "Program" operating area. An overview of all workpiece directories/programs is displayed.

See Chap. 6:

- Execute a program on the NC for execution
- Execute program from network drive, compact flash card, diskette.

Once you have selected the desired workpiece/program for execution, use the machine area key to change back to the "Machine" operating area.

The program starts running when you press the "NC Start" key, and you can track the axis position, spindle, etc in the display.

### 4.6.3 Program editing



Correct  
program

  
Cycle Start



#### Function

As soon as a syntax error in the part program is detected by the control, program processing is interrupted and the syntax error is displayed in the alarm line.

You can make small changes in the stop or reset state.

#### Operating sequence

"AUTO" mode is selected in the "Machine" operating area.

It is not possible to pass over the point of interruption. The feedrate correction switch is active.

The program status is in the "Stop" or "Reset" state.

The correction editor is displayed with this softkey. If an error occurs, the faulty block is highlighted and can be corrected. The cursor is positioned on the error.

Once you have corrected the block with an error, you can continue the program with the "Cycle Start" key.

- Stop state:  
Only program lines that have not yet been executed can be edited.
- Reset status:  
All program lines can be edited.
- Program Running state:  
Program cannot be edited!

#### 4.6.4 Setting block search/search destination



##### Function

The block search function allows you to run the part program forward until you reach the block you require. Three types of search are available:

1. With calculation on contour:  
During block searches with calculation, the same calculations are performed as in normal program mode. The complete destination block is then executed analogously to normal program execution.
2. With calculation at block end point:  
During block searches with calculation, the same calculations are performed as in normal program mode. The interpolation mode valid in the destination block is then applied to approach its end point or the next programmed position.
3. Without calculation:  
No calculations are performed during the block search. The values stored in the control remain the same as they were before the block search.

You can define the search destination

- by direct positioning or
- by specifying a block number, a label, a string, a program name or any character string.



##### References

For further information about block search, please refer to:  
/FB/ K1, Mode Group, Channel, Program control



Block  
search

Calculate  
contour



Calc. block  
end point

without  
calculation



Search  
position

Program  
level +

or

Program  
level -

## Operating sequence

"Auto" is selected in the "Machine" operating area.

The channel is in the reset state.

The program in which the block search is to be performed is selected.

Calls up the "Search position" function.

Position the cursor on the destination block.

The block search is started when you press one of the following three softkeys:

Block search start with calculation on contour

- When you press "Cycle Start", the axes execute a compensatory motion between the current actual position and the position of the block located by the block search.
- The new position is determined by the program status (all axis positions, active auxiliary functions) at the beginning of the selected block, i.e. after the block search, the control is positioned at the end position of the last NC block before the search destination.

Block search start with calculation at block end point

Block search start without calculation

- If the destination block is found this block becomes the current block. HMI Embedded signals "Search target found" and displays the target block in the current block display.
- Alarm 10208 is output to indicate that operator interventions such as Overstore or Mode Change after JOG are permissible.
- After "Cycle Start" the program is started and executed from the target block.

Block search can be aborted with Reset.

### Define search destination in program editor:

The current selected program level is displayed.

Position the cursor bar on a destination block of your choice in the part program.

If the program interruption occurred in a subprogram level, you can change program levels here.

Search  
pointer

0 ... 5

A ... Z

0 ... 9

Interrupt.  
point

#### Defining the search destination in the search pointer:

Once the softkey "search pointer" has been pressed, a screen form with the program pointer is displayed.

It contains input fields for program name, search type (block number, text, ...) and search destination (content). The cursor is positioned in the input field for the "search type."

You must enter your selected search type for the search destination in the input field "Type."

Information about the available search types is displayed in the dialog line.

The following search types can be entered:

Search type (= jump to ...)	Value in search type field
Program end	0
Block number	1
Jump label	2
Any character string	3
Program name	4
Line number	5

Different search types can be specified for different program levels.

You can enter your chosen search destination (according to search type) in the "Search destination" field.

You can enter the corresponding number of program passes in the "P" field (pass counter).

#### Preset search destination to last program interruption point:

The search pointer is assigned the data of the last program interruption point.

### 4.6.5 Accelerated block search for execution from external source



#### Function

The block search function allows you to run the part program forward until you reach the block you require.

In the "Search position" and "Search pointer" menus, you can use the "External w/o calc." softkey to start an accelerated block search on programs executed from an external device.

You can define the search destination

- by directly positioning the cursor on the target block, or
- by specifying a block number or a line number.

#### Block search sequence:

In certain circumstances, external program parts are not transferred or are only partially transferred to the NC.

Only those programs and program parts which are needed in order to reach the specified search target and to continue program execution are transferred to the NC. This applies to the following:

- "Execution from external source" function
- Execution of EXTCALL instructions.

#### Notice

Since certain program parts may not have been transferred to the NC, it must be assumed that modal functions such as feed and motion commands are incorrect at the target block (main block).

Consequently, when using the variants "Without calculation" and "External – without calculation", you will either need to make sure that any information required for machining is available in the selected target block (main block) and following blocks, or use the override to complete the necessary settings.

#### Operating sequence

"Auto" is selected in the "Machine" operating area.

The channel is in the reset state.

The program in which the block search is to be performed is selected.

Switch to the "Search position" dialog.

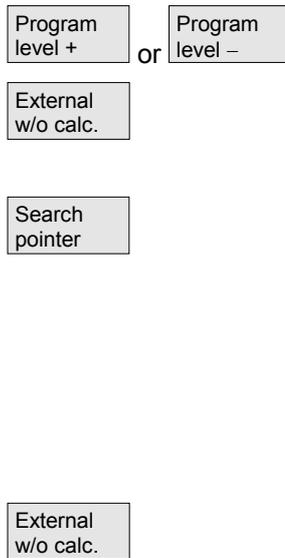
Block  
search

Search  
position

#### Define search destination in program editor:

The current selected program level is displayed.

The block search via "Search position" is only possible for programs which have been loaded onto the NC and not for programs executed from the hard disk.



Position the cursor bar on a destination block of your choice in the part program.

If an interruption point is available on the NC, you can switch back and forth between the program levels.

Start search without calculation for external programs.

#### Defining the search destination in the search pointer:

Once the softkey "Search pointer" has been pressed, a screen form with the program pointer is displayed.

It contains input fields for program name, search type (block number, text, ...) and search destination (content). The cursor is positioned in the input field for the "search type".

Type 1 (block number) and type 5 (line number) are possible as search target types.

Start search without calculation for external programs.

### 4.6.6 Overstoring



#### Function

In "Auto" mode you can overstore technological parameters (auxiliary functions, all programmable instructions ...) in the working memory of the NC. You can also enter and execute any NC block.

#### Operating sequence

"Auto" is selected in the "Machine" operating area.

Stop the program by selecting "Cycle Stop."

The "Overstore" window is opened.

In this window you can now enter the desired NC blocks that are to be processed.

On "Cycle Start" the entered blocks are executed, the "Current block" window displayed and the softkeys hidden. The "Overstore" window and associated softkeys are not displayed again until the "Channel interrupted", "Stop" or "Reset" state is reached.



More blocks can be added (to the overstore buffer) when these blocks have been processed.



**Note:**

- After "Overstore" a subroutine with the content REPOSA is executed. The program is displayed for the operator.
- Overstoring is not possible in the "Program running" state.



**Further information**

- You can close the window and exit the Overstore function by pressing the "Recall" key. You have now exited the Overstore function.
- You cannot change operating modes until you have deselected "Overstore" with the "Recall" key.
- In "AUTO" mode the program selected prior to the overstore operation is now executed when you press "Cycle Start" again.
- Overstore does not alter the programs stored in the part program memory.
- The function is also available in single-block mode.

#### 4.6.7 Program control



**Function**

You can use this function to change a program sequence in "Auto" and "MDA" modes. The following program control functions can be activated or deactivated:

SKP	Skip block
DRY	Dry run feedrate
ROV	Rapid traverse override
M01	Programmed stop
M101	Halt at cycle end (optional)
SBL1	Single block with stop after machine function blocks
SBL2	Single block with stop after each block.
DRF	Select DRF offset
PRT	Program test
-	Display all blocks in the current block display
-	Display only traversing blocks in the current block display window

See Chapter 2, "Program Control Display"





### References

The display is dependent on the machine data of the operator panel front in which access authorization can be set.

/FB/, A2, Various Interface Signals: Chapter 4, or  
/FB/ K1, Mode Groups, Channels, Program Operation



### Operating sequence

"Auto" or "MDA" mode is selected in the "Machine" operating area.

Program  
control

The "Program control" window appears on the screen.

Place the cursor at the required position.



Every time you press the "Select" key you activate or deactivate the selected function.

#### 4.6.8 DRF offset



### Function

The DRF (Differential Resolve Function) offset allows an additional incremental zero offset to be set using the handwheel. "DRF" is an axial traverse that works in the basic coordinate system. The handwheel selection is only permitted via the axial interface, i.e., only machine axes can be used.

### Activation/deactivation

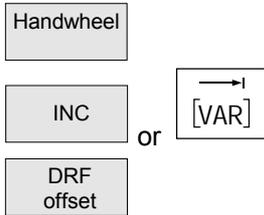
The DRF offset can be switched on and off for specific channels by means of the "Program control" function.

It remains stored until

- Power On for all axes
- DRFOF (deselect DRF by means of part program)
- PRESETON (changing the actual value via Preset)

### Change DRF

You can alter the DRF offset by traversing the appropriate machine axis using the handwheel (the actual value display does not change).



### Operating sequence

"AUTO" mode is selected in the "Machine" operating area.  
The standard axis assignment is defined.

Enter the desired handwheel or select via the MCP.

Enter the desired increment or select via the MCP.

The window "DRF offset" is displayed.

Traverse the required axes using the handwheel.

Using the same operating sequence, you can also return the DRF offset to the value "0".



## Parameters Operating Area

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## 5.1 Tool data

### 5.1.1 Tool offset structure

		<p>A tool is selected in the program with the T function. Numbers T0 to T32000 can be assigned to tools. Each tool can have up to 9 cutting edges: D1 - D9. D1 to D9 activates the tool offset of a cutting edge for the active tool.</p> <p>The tool length compensation is applied with the first traversing motion (linear or polynomial interpolation) of the axis.</p> <p>A tool radius compensation is activated by programming G41/42 in the active plane (G17, 18, 19) and in a program block with G0 or G1.</p>
	<b>Tool wear</b>	<p>Allowances for changes in the active tool shape can be made in the tool length (tool parameters 12-14) and tool radius (tool parameters 15-20).</p>
	<b>Tool offset with D numbers only</b>	<p>Tool management is implemented outside the NCK. T numbers are irrelevant. This function is activated via the MD.</p> <p>The D number range increases to 1 - 32000. A D number can be assigned only once for each tool, i.e. each D number represents precisely one tool offset data record.</p>
	 <b>Tool cutting edges</b>	<p>Each tool can have up to 9 cutting edges: D1–D9.</p>

### 5.1.2 Tool types and tool parameters

	<b>Entries</b>	<p>T No.            Number of the tool</p> <p>D No.            Number of the cutting edge</p> <p>Every data field (offset memory) that can be called with a D number contains not only the geometric information for the tool but also additional entries, i.e. the tool type (drill, milling cutter, turning tools with cutting edge position etc.).</p>
--	----------------	-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------

**Tool types**

Tool type classification:

- **Group with type 1xy (cutter):**
  - 100 Cutter to CLDATA
  - 110 Ball end cylindrical die mill
  - 120 End milling cutter without corner rounding
  - 121 End mill with corner rounding
  - 130 Angle head cutter without corner rounding
  - 131 Angle head mill with corner rounding
  - 140 Facing tool
  - 145 Thread cutter
  - 150 Side mill
  - 155 Bevel cutter without rounding
  - 156 Bevel cutter with rounding
  - 157 Tapered die mill

**Required offset values for a milling cutter**

Entries in tool parameters		
DP1	1xy	
DP3	Length 1	
DP6	Radius	
Wear values according to requirement		Effect
Other values must be set to zero		G17: Length 1 in Z Radius in X/Y
		G18: Length 1 in Y Radius in Z/X
		G19: Length1 in X Radius in Y/Z
		F: Toolholder reference point

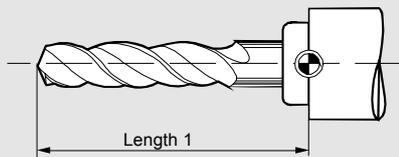
**Milling tool with adapter**

Entries in tool parameters		
DP1	1xy	
DP3	Length 1 <sub>Geometry</sub>	
DP6	Radius <sub>Geometry</sub>	
DP21	Length <sub>Adapter</sub>	
Wear values according to requirements		Effect
Other values must be set to zero		G17: Length 1 in Z Radius in X/Y
		G18: Length 1 in Y Radius in Z/X
		G19: Length 1 in X Radius in Y/Z
		F': Toolholder reference point

- **Group type 2xy (drills):**

- 200 Twist drill
- 205 Drill
- 210 Boring bar
- 220 Center drill
- 230 Countersink
- 231 Counterbore
- 240 Tap regular thread
- 241 Tap fine thread
- 242 Tap Whitworth thread
- 250 Reamer

**Required offset values  
for a drill**

Entries in tool parameters			F: Toolholder reference point								
DP1	2xy										
DP3	Length 1										
Wear values according to requirements		<table border="1"> <thead> <tr> <th colspan="2">Effect</th> </tr> </thead> <tbody> <tr> <td>G17:</td> <td>Length 1 in Z</td> </tr> <tr> <td>G18:</td> <td>Length 1 in Y</td> </tr> <tr> <td>G19:</td> <td>Length 1 in X</td> </tr> </tbody> </table>		Effect		G17:	Length 1 in Z	G18:	Length 1 in Y	G19:	Length 1 in X
Effect											
G17:	Length 1 in Z										
G18:	Length 1 in Y										
G19:	Length 1 in X										
Other values must be set to zero											

- **Group type 4xy (grinding tools):**

- 400 Surface grinding wheel
- 401 Surface grinding wheel with monitoring
- 403 Surface grinding wheel with monitoring without base dimension for GWPS grinding speed
- 410 Facing wheel
- 411 Facing wheel with monitoring
- 413 Facing wheel with monitoring without base dimension for GWPS grinding speed
- 490 Dresser

**Offset values required by a surface grinding wheel**

Entries in tool parameters		
STC_DP1	403	
STC_DP3	Length 1	
STC_DP4	Length 2	
STC_DP6	Radius	
Wear values according to requirements		
Other values must be set to zero		
Effect		
G17:	Length 1 in Y Length 2 in X Radius in X/Y	
G18:	Length 1 in X Length 2 in Z Radius in Z/X	
G19:	Length 1 in Z Length 2 in Y Radius in Y/Z	

**Required offset values for inclined grinding wheel with implicit monitoring selection**

Entries in tool parameters		STC_TPG1	Spindle number
		STC_TPG2	Chaining rule
STC_DP1	403	STC_TPG3	Minimum wheel radius
STC_DP3	Length 1	STC_TPG4	Minimum wheel width
STC_DP4	Length 2	STC_TPG5	Current wheel width
STC_DP6	Radius	STC_TPG6	Maximum speed
Wear values according to requirement		STC_TPG7	Max. surface speed
		STC_TPG8	Angle of the inclined wheel
		STC_TPG9	Parameter no. for radius calculation
Other values must be set to zero		F: Toolholder reference point	
Effect			
G17:	Length 1 in Y Length 2 in X Radius in X/Y		
G18:	Length 1 in X Length 2 in Z Radius in Z/X		
G19:	Length 1 in Z Length 2 in Y Radius in Y/Z		

**Example of required offset values for inclined grinding wheel with implicit monitoring selection**

Entries in tool parameters		STC_TPG1	Spindle number
		STC_TPG2	Chaining rule
STC_DP1	403	STC_TPG3	Minimum wheel radius
STC_DP3	Length 1	STC_TPG4	Minimum wheel width
STC_DP4	Length 2	STC_TPG5	Current wheel width
STC_DP6	Radius	STC_TPG6	Maximum speed
		STC_TPG7	Max. surface speed
		STC_TPG8	Angle of the inclined wheel
		STC_TPG9	Parameter no. for radius calculation
Wear values according to requirement		F: Toolholder reference point	
Other values must be set to zero			
Effect			
G17:	Length 1 in Y Length 2 in X Radius in X/Y		
G18:	Length 1 in X Length 2 in Z Radius in Z/X		
G19:	Length 1 in Z Length 2 in Y Radius in Y/Z		

**Required offset values of a surface grinding wheel without base dimension for GWPS**

Entries in tool parameters		STC_TPG1	Spindle number
		STC_TPG2	Chaining rule
STC_DP1	403	STC_TPG3	Minimum wheel radius
STC_DP3	Length 1	STC_TPG4	Minimum wheel width
STC_DP4	Length 2	STC_TPG5	Current wheel width
STC_DP6	Radius	STC_TPG6	Maximum speed
STC_DP21	L1 base	STC_TPG7	Max. surface speed
STC_DP22	L2 base	STC_TPG8	Angle of the inclined wheel
		STC_TPG9	Parameter no. for radius calculation
Wear values according to requirement		F: Toolholder reference point	
Other values must be set to zero			
Effect			
G17:	Length 1 in Y Length 2 in X Radius in X/Y		
G18:	Length 1 in X Length 2 in Z Radius in Z/X		
G19:	Length 1 in Z Length 2 in Y Radius in Y/Z		

## 5.1 Tool data

### Required offset values of a facing wheel with monitoring parameters

Entries in tool parameters		\$TC_TPG1	Spindle number
		\$TC_TPG2	Chaining rule
\$TC_DP1	403	\$TC_TPG3	Minimum wheel radius
\$TC_DP3	Length 1	\$TC_TPG4	Minimum wheel width
\$TC_DP4	Length 2	\$TC_TPG5	Current wheel width
\$TC_DP6	Radius	\$TC_TPG6	Maximum speed
		\$TC_TPG7	Max. surface speed
Wear values according to requirement		\$TC_TPG8	Angle of the inclined wheel
		\$TC_TPG9	Parameter no. for radius calculation
Other values must be set to zero		F: Toolholder reference point e.g. G18: Z/X plane	
Effect			
G17:	Length 1 in Y Length 2 in X Radius in X/Y		
G18:	Length 1 in X Length 2 in Z Radius in Z/X		
G19:	Length 1 in Z Length 2 in Y Radius in Y/Z		

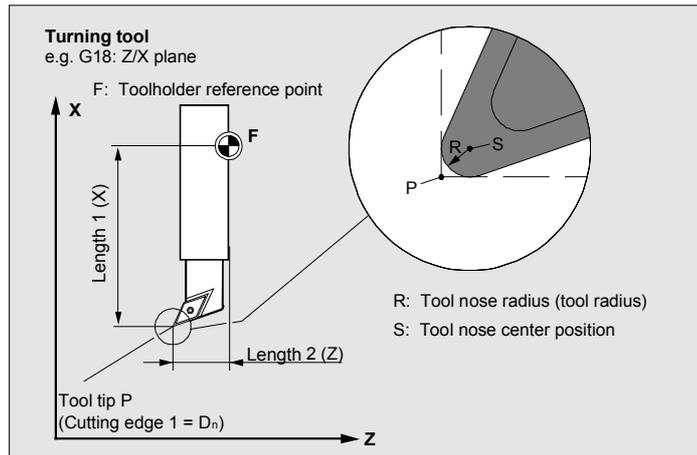
### Assignment of Tool-specific Parameters

Parameters	Meaning	Data Type
Tool-specific parameters		
\$TC_TPG1	Spindle number	Integer
\$TC_TPG2	Chaining rule	Integer
\$TC_TPG3	Minimum wheel radius	Real
\$TC_TPG4	Minimum wheel width	Real
\$TC_TPG5	Current wheel width	Real
\$TC_TPG6	Maximum speed	Real
\$TC_TPG7	Maximum surface speed	Real
\$TC_TPG8	Angle of inclined wheel	Real
\$TC_TPG9	Param. no. for radius calc.	Integer
Additional parameters		
\$TC_TPC1	Angle of inclined wheel	Real
up to		
\$TC_TPC10		Real

• **Group type 5xy (turning tools):**

- 500 Roughing tool
- 510 Finishing tool
- 520 Plunge cutter
- 530 Parting tool
- 540 Threading tool

**Required offset values for a turning tool with tool radius compensation**



**Required offset values for a turning tool with tool radius compensation**

Tool parameter DP2 defines the tool nose position. Any value between 1 and 9 can be entered.

X **Tool nose position DP2**

1 2 3 4 5

6 7 8 9

X

Z

Note:  
Length 1, length 2 refer to point P for edge positions 1-8;  
but in case of 9 to S (S = P)

Entries in tool parameters		Wear values according to requirements	Effect	
DP1	5xy		G17:	Length 1 in Y Length 2 in X
DP2	1...9		G18:	Length 1 in X Length 2 in Z
DP3	Length 1		G19:	Length 1 in Z Length 2 in Y
DP4	Length 2			
DP6	Radius			

Other values must be set to zero

- Group type 7xy special tools
  - 700 Slotting saw
  - 710 3D Probe
  - 711 Edge probe

**Example of required offset values for a slotting saw**

Entries in tool parameters												
DP3 Length 1 - Base												
DP4 DP3 Length 2 - Base												
DP6 Diameter - Geometry												
DP7 Zero width - Geometry												
DP8 Projection - Geometry												
Wear values according to requirement				Effect								
Other values must be set to zero				<table border="1"> <tr> <td>G17:</td> <td>Semi-diameter (L1) in Z Projection in (L2) Y Saw blade in (R) X/Y</td> <td>Plane selection 1st-2nd axis (X-Y)</td> </tr> <tr> <td>G18:</td> <td>Semi-diameter (L1) in Y Projection in (L2) X Saw blade in (R) Z/X</td> <td>Plane selection 1st-3rd axis (X-Z)</td> </tr> <tr> <td>G19:</td> <td>Semi-diameter (L1) in Z Projection in (L2) Z Saw blade in (R) Y/Z</td> <td>Plane selection 2nd-3rd axis (Y-Z)</td> </tr> </table>			G17:	Semi-diameter (L1) in Z Projection in (L2) Y Saw blade in (R) X/Y	Plane selection 1st-2nd axis (X-Y)	G18:	Semi-diameter (L1) in Y Projection in (L2) X Saw blade in (R) Z/X	Plane selection 1st-3rd axis (X-Z)
G17:	Semi-diameter (L1) in Z Projection in (L2) Y Saw blade in (R) X/Y	Plane selection 1st-2nd axis (X-Y)										
G18:	Semi-diameter (L1) in Y Projection in (L2) X Saw blade in (R) Z/X	Plane selection 1st-3rd axis (X-Z)										
G19:	Semi-diameter (L1) in Z Projection in (L2) Z Saw blade in (R) Y/Z	Plane selection 2nd-3rd axis (Y-Z)										

$L1 = DP3 + DP6/2$   
 $L2 = DP4 + DP7/2 - DP8$   
 $R = DP7/2$

The offset data (TOA data) you can enter for tool type 700 "slotting saw" are as follows:

	Geometry	Wear	Base	
<b>Length compensation</b>				
Length 1	\$TC_DP3	\$TC_DP12	\$TC_DP21	mm
Length 2	\$TC_DP4	\$TC_DP13	\$TC_DP22	mm
Length 3	\$TC_DP5	\$TC_DP14	\$TC_DP23	mm
<b>Radius compensation</b>				
Diameter	\$TC_DP6	\$TC_DP15		mm
Slot width b	\$TC_DP7	\$TC_DP16		mm
Projection k	\$TC_DP8	\$TC_DP17		mm

## Calculating the tool parameters

Types 1xy (milling cutters), 2xy (drills), and 5xy (turning tools) are calculated according to the same scheme.

Several entries exist for the geometric variables (e.g. length 1 or radius). These are added together to produce a value (e.g. total length 1, total radius) which is then used for the calculations.

Tool parameter number (P)	Meaning	Remarks
1	Tool type	For overview see list
2	Length of cutting edge	only for turning tools
Geometry		Length compensation
3	Length 1	Calculation according to type and plane
4	Length 2	
5	Length 3	
Geometry		Radius
6	Radius	Does not apply to drills
7	Reserved	
8	Reserved	
9	Reserved	
10	Reserved	
11	Reserved	
Wear		Length and radius compensation Radius compensation
12	Length 1	
13	Length 2	
14	Length 3	
15	Radius	
16	Reserved	
17	Reserved	
18	Reserved	
19	Reserved	
20	Reserved	
Base dimensions/ adapter		Length offsets
21	Length 1	
22	Length 2	
23	Length 3	
Technology		
24	Clearance angle	for turning tools
25	Clearance angle	

Offsets that are not required must be set to zero (= default when the offset memory is set up).

The individual values of the offset memory (P1 to P25) can be read and written by the program via system variables.

The tool offsets can be entered not only via the operator panel front but also via the data input interface.



**Calculation of tool base dimensions for two-dimensional millhead**

Entries in tool parameters			
DP1	5xy		
DP3	Length 1 - Geometry		
DP6	Radius - Geometry		
DP21	Length 1 - Base		
DP22	Length 2 - Base		
DP23	Length 3 - Base		
Wear values according to requirements  Other values must be set to zero	Effect		
	G17:	Length 1 in Z Length 2 in Y Length 3 in X Radius in Y/Z	
	G18:	Length 1 in Y Length 2 in X Length 3 in Z Radius in X/Y	
	G19:	Length 1 in X Length 2 in Z Length 3 in Y Radius in Z/X	

**Calculation of tool base dimensions for three-dimensional millhead:**

Entries in tool parameters			
DP1	5xy		
DP3	Length 1 - Geometry		
DP6	Radius - Geometry		
DP21	Length 1 - Base		
DP22	Length 2 - Base		
DP23	Length 3 - Base		
Wear values according to requirements  Other values must be set to zero	Effect		
	G17:	Length 1 in Z Length 2 in Y Length 3 in X Radius in Y/Z	
	G18:	Length 1 in Y Length 2 in X Length 3 in Z Radius in X/Y	
	G19:	Length 1 in X Length 2 in Z Length 3 in Y Radius in Z/X	

**Required length compensation values for turning tools:**

Entries in tool parameters		
DP1	5xy	
DP3	Length 1	
DP4	Length 2	
Wear values according to requirements	Effect	
	G17:	Length 1 in Y Length 2 in X
	G18:	Length 1 in X Length 2 in Z
Other values must be set to zero	G19:	Length 1 in Z Length 2 in Y

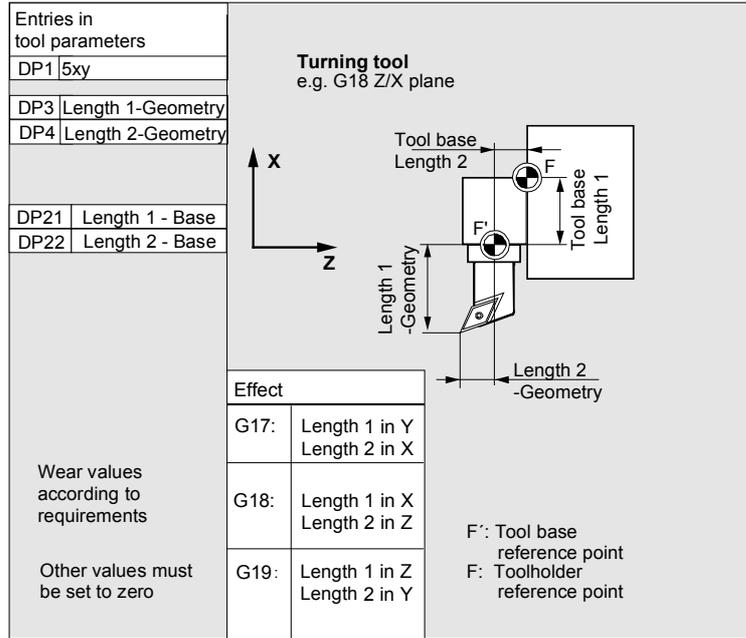
F: Toolholder reference point

**Turning tool with several cutting edges – length compensation:**

Entries in tool parameters		
DP1	5xy	
DP3	Length 1	
DP4	Length 2	
Wear values according to requirement	Effect	
	G17:	Length 1 in Y Length 2 in X
	G18:	Length 1 in X Length 2 in Z
Other values must be set to zero	G19:	Length 1 in Z Length 2 in Y

F: Toolholder reference point

**Calculation of tool base dimensions for turning machine:**



Tool type 4xy (grinding tools) is calculated separately.

For the geometric values (e.g. length or radius), there are several entry components.

Parameters	Grinding wheel comp. left	Grinding wheel comp. right	Dresser left	Dresser right
Tool-specific parameters				
\$TC_DP1	Tool type	$*(2^0=1)$	Tool type	Tool type
\$TC_DP2	Length of cutting edge	Length of cutting edge	Length of cutting edge	Length of cutting edge
Geometry tool length compensation				
\$TC_DP3	Length 1	$*(2^2=4)$	Length 1	Length 1
\$TC_DP4	Length 2	$*(2^3=8)$	Length 2	Length 2
\$TC_DP5	Length 3	$*(2^4=16)$	Length 3	Length 3
\$TC_DP6	Radius	Radius	Radius	Radius
\$TC_DP7 to \$TC_DP11	Reserved	Reserved	Reserved	Reserved
Wear tool length compensation				
\$TC_DP12	Length 1	$*(2^{11}=2048)$	Length 1	Length 1
\$TC_DP13	Length 2	$*(2^{12}=4096)$	Length 2	Length 2
\$TC_DP14	Length 3	$*(2^{13}=8192)$	Length 3	Length 3
\$TC_DP15	Radius	Radius	Radius	Radius
\$TC_DP16 to \$TC_DP20	Reserved	Reserved	Reserved	Reserved
Base dimension/adaptor dimension tool length compensation				
\$TC_DP21	Basic length 1	$*(2^{20}=1048576)$	Basic length 1	Basic length 1
\$TC_DP22	Basic length 2	$*(2^{21}=2097152)$	Basic length 2	Basic length 2

\$TC_DP23	Basic length 3	*(2 <sup>22</sup> =4194304)	Basic length 3	Basic length 3
-----------	----------------	-----------------------------	----------------	----------------

Technology				
\$TC_DP24	Reserved	Reserved	Reserved	Reserved
\$TC_DP25	Reserved	Reserved	Reserved	Reserved
Additional parameters				
\$TC_DPC1				
up to				
\$TC_DPC10				

\* Value of the chaining parameter if the compensation parameter is to be chained.

### Parameter no. for radius calculation

#### \$TC\_TPG9

With this parameter it is possible to define which offset value is used for grinding wheel surface speed, tool monitoring and centerless grinding. The value always refers to cutting edge D1.

\$TC_TPG9 = 3	Length 1 (geometry + wear + base, depending on tool type)
\$TC_TPG9 = 4	Length 2 (geometry + wear + base, depending on tool type)
\$TC_TPG9 = 5	Length 3 (geometry + wear + base, depending on tool type)
\$TC_TPG9 = 6	Radius

\*: The tool parameter of cutting edge 2 is chained to the parameter of cutting edge 1 (see tool-specific grinding data \$TC\_TPG2, chain rule). Here, typical chains are shown and the associated place value is specified in brackets.

### Spindle number

#### \$TC\_TPG1

This parameter contains the number of the spindle to which the monitoring data and GWPS refer.

### Chain rule \$TC\_TPG2

This parameter defines which tool parameters of the right wheel edge (D2) and left wheel edge (D1) must be chained (see TOA data). If the value of one of the chained parameters is changed, it is then automatically included in the chained parameter.

It must be noted that the minimum grinding wheel radius must be specified in the Cartesian coordinate system for an inclined grinding wheel. The length compensations always specify the distances between the tool holder reference point and the tool tip in Cartesian coordinates.

## 5.1 Tool data

The monitoring data apply to both the left-hand and the right-hand cutting edge of the grinding wheel.

The tool lengths are not automatically compensated when the angle is altered.

On inclined axis machines the same angle must be specified for the inclined axis and the inclined wheel.

Offsets that are not required must be assigned the value 0 (= default when the offset memory is set up).

The tool offsets can be entered not only via the operator panel front but also via the data input interface.

For programming of compensation data see  
/PG/ Programming Guide Fundamentals



### References

## 5.2 Tool offset

### 5.2.1 Tool offset function and basic display



Tool offset data consist of data that describes the geometry, wear, identification, tool type, and the assignment to parameter numbers. The unit used for the dimensions of the tool is displayed.

The input field is highlighted.

If no tool management, e.g. Standard, ShopMill, ShopTurn is available, the following window appears after selecting the “Parameters” operating area:



Parameter	CHAN1	JOG	VMPF.DIR ZZZ_STANDARDZYKLEN.MPF																																																																													
Channel reset					T no. +																																																																											
Program aborted	FST				T no. -																																																																											
<b>Tool offsets</b>					D no. +																																																																											
T number 100 D number 1 No. of c.edges 1					D no. -																																																																											
Tool type 121 End mill (with corner rounding)					Delete																																																																											
<table border="1"> <thead> <tr> <th></th> <th>Geometry</th> <th>Wear</th> <th>Base</th> <th></th> </tr> </thead> <tbody> <tr> <td>Tool length comp.</td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>Length 1 :</td> <td>1.000</td> <td>1.000</td> <td>1.300</td> <td>mm</td> </tr> <tr> <td>Length 2 :</td> <td>2.000</td> <td>2.100</td> <td>1.400</td> <td>mm</td> </tr> <tr> <td>Length 3 :</td> <td>3.000</td> <td>3.100</td> <td>1.500</td> <td>mm</td> </tr> <tr> <td>Radius compensation</td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>Radius :</td> <td>4.000</td> <td>4.100</td> <td></td> <td>mm</td> </tr> <tr> <td>DP7,16 res:</td> <td>7.000</td> <td>16.000</td> <td></td> <td></td> </tr> <tr> <td>DP8,17 res:</td> <td>8.000</td> <td>17.000</td> <td></td> <td></td> </tr> <tr> <td>DP9,18 res:</td> <td>9.000</td> <td>18.000</td> <td></td> <td></td> </tr> <tr> <td>DP10,19 res:</td> <td>11.000</td> <td>19.000</td> <td></td> <td></td> </tr> <tr> <td>DP11,20 res:</td> <td>12.000</td> <td>20.000</td> <td></td> <td></td> </tr> <tr> <td>Technology</td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>Clear.angle:</td> <td>24.000</td> <td>Deg.</td> <td></td> <td></td> </tr> <tr> <td>DP25 res:</td> <td>25.000</td> <td></td> <td></td> <td></td> </tr> </tbody> </table>						Geometry	Wear	Base		Tool length comp.					Length 1 :	1.000	1.000	1.300	mm	Length 2 :	2.000	2.100	1.400	mm	Length 3 :	3.000	3.100	1.500	mm	Radius compensation					Radius :	4.000	4.100		mm	DP7,16 res:	7.000	16.000			DP8,17 res:	8.000	17.000			DP9,18 res:	9.000	18.000			DP10,19 res:	11.000	19.000			DP11,20 res:	12.000	20.000			Technology					Clear.angle:	24.000	Deg.			DP25 res:	25.000				Go to
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Tool offset	R variables	Setting data	Work offset	User data	Determine compensa.																																																																											



Every offset number contains up to 25 parameters depending on the tool type.

The number of parameters shown in the window is that for the tool type.

The maximum number of offset parameters (T and D numbers) can be set by means of machine data.



#### Machine manufacturer

Please note information supplied by machine tool manufacturer!

Tool  
offset

**Horizontal softkeys**

You can select different data types with the horizontal softkeys:

Selection of "Tool offset" menu

R variables

Selection of "R variables" menu

Setting  
data

Selection of "Setting data" menu

Work  
offset

Selection of "Work offset" menu

User  
data

Selection of "User data" menu

Determine  
compensa.

Support in determining tool offsets. This softkey is not required if the tool management function is available.

**Vertical softkeys**

The vertical softkeys support data input:

T No.  
+

Selection of the next tool

T No.  
-

Selection of the previous tool

D No.  
+

Selection of next higher offset number (cutting edge)

D No.  
-

Selection of next lower offset number (cutting edge)

Delete...

Deletion of a tool or cutting edge

Go to

Find any tool or the active tool

Overview

List of all available tools

New

New cutting edge or a new tool

## 5.2.2 Create new tool



New

New tool

Abort

OK

### Function

If you create a new tool, the relevant tool types are automatically pre-selected as input support when you select the tool group.

### Operating sequence

The "Tool offset" window is displayed automatically.

Press "New" and "New tool" softkey.

The "New tool" window appears on the screen.

As soon as you enter the first characters in the string for the tool group, for example

- 5xy Turning tools

all available tool types in the 5xy group are automatically displayed for you to select, i.e.

- 500 Roughing tool
- 510 Finishing tool
- 520 Plunge cutter
- 530 Parting tool
- 540 Threading tool

Enter the digits for your selections via the alphanumeric keypad or select them from the displayed list.

No new tool is set up. Input is discarded.

The new tool is created.

The window is closed and the tool list is overlaid.

### 5.2.3 Display tool



T No.  
+

T No.  
-

#### Function

You can select tools that you have set up and access their tool compensation data.

#### Operating sequence

The "Tool offset" window is displayed automatically.

If the "Parameter" area has already been selected, the window and the last tool selected when the area was exited are displayed. The tool offset data of the current tool are displayed immediately. If no tool has yet been selected, the data of the first tool are shown together with its first D number.

If no tools are available in the area, a message is output.

Select the set up tools.

#### Further information

Input of the geometry and wear data of the tool can be disabled using the key switch.

### 5.2.4 Find tool



Overview

OK

#### Function

There are two methods by which you can find tools and view their tool offset data.

#### Operating sequence

##### Find tool by selecting softkey "Overview":

The "Tool offset" window is displayed automatically.

The "Overview" softkey displays a list of all existing tools.

Position the cursor on the tool you wish to find and confirm your request by pressing the "OK" softkey.



Go to

Preselect  
T/D No.

or

Active  
T/D No.

OK

The new tool is selected and displayed in the "Tool offset" window.

#### Find tool by selecting softkey "Go to":

Softkey "Go to" opens a window in which you can enter the T or D number you wish to find or in which you can select the pre-selected or active tool using the vertical softkeys.

The tool you are searching for is positioned with "OK". Its tool offsets are then displayed.

### 5.2.5 Delete tool



T No.  
+

T No.  
-

Delete

Delete  
tool

#### Function

The tool is deleted together with all its cutting edges and the tool list updated accordingly.

#### Operating sequence

The "Tool offset data" window is displayed automatically.

Scroll until you reach the tool to be deleted.

The vertical softkey bar changes when softkey "Delete" is selected.

Press the "Delete tool" softkey.

The tool and all its edges are deleted. The tool offsets of the tool number preceding the deleted tool are displayed.

### 5.2.6 Create new cutting edge







#### Function

To help you to select a new tool edge, the associated tool types are displayed automatically when you select a tool group.

#### Operating sequence

The "Tool offset" window is displayed automatically.

Press "New ..." and "New edge" softkeys.

The window "New edge" is displayed.

As soon as you enter the first characters in the string for the tool group, for example

- 5xx Turning tools

all available tool types in the 5xx group are automatically displayed for you to select, i.e.,

- 500 Roughing tool
- 510 Finishing tool
- 520 Plunge cutter
- 530 Parting tool
- 540 Threading tool

Press "Cancel" to discard entered values.

Press "OK" to save the entered values.

### 5.2.7 Display cutting edge





#### Function

You can select and modify the edges of tools that you have set up.

The "Tool offsets" window is selected.

Select a tool of your choice and a cutting edge.

### 5.2.8 Find cutting edge



Overview

Go to

#### Function

You can use one of two search methods:

1. Overview: List of existing tools with their edges is displayed.
2. Go to: Opens a window in which you can enter the T or D number you wish to find or you can use softkeys to select the "Pre-selected T/D No." or the "Active T/D No."

### 5.2.9 Delete cutting edge



D No.  
+

D No.  
-

Delete

Delete tool  
edge

#### Function

You can delete one or several edges of a tool. The tool list is updated automatically.

Select the tool edge, press

"Delete" softkey and

the "Delete tool edge" softkey.

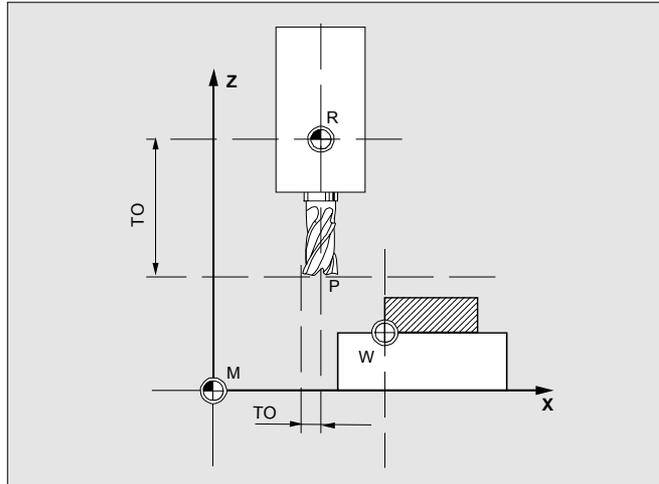
The displayed tool edge is deleted.

## 5.2.10 Determine tool offsets



## Function

The "Determine tool offsets" function allows you to change the reference values of different axes and then to calculate them.



- TO** Tool offset, absolute dimension
- R** Tool mounting point
- M** Machine zero
- W** Workpiece zero

## Operating sequence

The "Tool offset" window is displayed automatically.  
Position the cursor on the tool parameter you wish to change.  
The "Absolute dimension" window opens.

Select the appropriate axis with the "Select key". Alter the reference value if necessary using the numeric keypad.

When you press softkey "OK", the current position and corresponding reference value for the selected tool parameter are calculated.

The following equation applies: Position – reference value = input value

The window is closed.

Position – reference value is entered in the input field. The window remains open.

Determine  
compensa.



OK

Calculate



If "Jog" mode is selected, it is also possible to change the position by traversing the axes.  
The control automatically calculates the value from the reference value and the new position.

5.2.11 Tool offsets with D-numbers only (flat D no.)



Function

It is possible to specify that tools with a flat D number can only be selected via their flat D number. One D number can be assigned only once per tool, i.e. each D number represents exactly one offset data record.

Parameter	CHAN1	JOG	MPF.DIR ZZZ_STANDARDZYKLEN.MPF	
Channel reset				
Program aborted				
<b>Tool offsets</b>				
				<b>TD area</b>
	D number	1	No. of c.edges	1
Tool type	121	End mill (with corner rounding)		
	Geometry	Wear	Base	
Tool length comp.				
Length 1 :	1.000	1.000	1.300	mm
Length 2 :	2.000	2.100	1.400	mm
Length 3 :	3.000	3.100	1.500	mm
Radius compensation				
Radius :	4.000	4.100	mm	
DP7,16 res:	7.000	16.000		
DP8,17 res:	8.000	17.000		
DP9,18 res:	9.000	18.000		
DP10,19 res:	11.000	19.000		
DP11,20 res:	12.000	20.000		
Technology				
Clear.angle:	24.000	Deg.		
DP25 res:	25.000			
<b>Tool offset</b>	<b>R variables</b>	<b>Setting data</b>	<b>Work offset</b>	<b>User data</b>
				<b>Determine compensa.</b>



Machine manufacturer

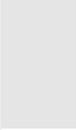
Please note information supplied by machine tool manufacturer!



References

/FB1/W1: Tool offset

### 5.2.12 Make active tool offset operative immediately



**Machine manufacturer**

**References**

#### Function

The machine data can be set to specify that the active tool offset can be activated immediately if the part program switches to the "Reset" or "Stop" state.

#### Further information

When the function is used in the Reset state, the machine data must be set such that the offset is not reset when the program switches to Reset.

Please note information supplied by machine tool manufacturer!

/FB1/K2: Axes/Coordinate Systems etc.

#### Caution

The offset is applied in the next programmed axis motion in the part program after "Cycle Start" in Reset.

### 5.3 Tool management

		The tool management system is organized by means of various configurable lists which show different views of the tools used.
	<b>Magazine list</b>	In the "Magazine list", the tools of a magazine are displayed in order of ascending magazine location numbers.  You can find, display and, in the majority of cases, modify the data.
		This list is mainly used to load and unload tools during setup, and to move tools between magazines.
	<b>Tool list</b>	In the "Tool list", the tools are displayed in the order of ascending T numbers.
		You use this list if you are working with small tool magazines and know the exact location of each tool in each of the magazines.
	<b>ShopMill tool management</b>	You can use the ShopMill tool management as an alternative to the standard tool management. It uses workshop-compatible tool management for <b>milling machines</b> . You can select it via an MD.
	<b>ShopTurn tool management</b>	You can use the ShopTurn tool management as an alternative to the standard tool management. It uses workshop-compatible tool management for <b>turning machines</b> . You can select it via an MD.
		<b>Machine manufacturer</b> For details of the functionality of your tool management system, please refer to the machine manufacturer's instruction manual.
		<b>References</b> /IAM/IM2/Installation & Start-Up Guide HMI Embedded /FBW/Description of Functions Tool Management or /FBSP/Description of Functions ShopMill /FBT/Description of Functions ShopTurn

## 5.3.1 Tool management basic display

You can manage your tool magazines in the "Magazine list" basic display.

The tool management offers the most commonly used tools as tool types. You can assign geometric and technological data to the tool types in order to set up your master tool data. There can still be several versions of each tool. You can assign the actual data of the tool used (particular tool data) to these versions.

Parameter	CHAN1	JOG	\MPF.DIR CMM_SINGLE.MPF				
Channel reset							Maglist1
Program aborted							
Magazine list			Magazine No. 1			Maglist2	
Magazine name			No. of loc. 30			Maglist3	
Loc No.	Tool ident.	Duplo No.	Tool status	Length1	Geometry Length2	Radius	Tool details
1	Zent1	2	PA	10.000	0.000	2.500	
2		0		0.000	0.000	0.000	
3	Zent3	1	P_	30.000	0.000	7.500	
4	Bohr1	1	P_	40.000	0.000	2.250	
5	Bohr2	1	U_PA	50.000	0.000	4.500	
6	Bohr3	1	P_	60.000	0.000	6.750	
7	Gewinde1	1	P_	70.000	0.000	2.500	
Buffer							Buffer off
1	Zent2	2	PA	20.000	0.000	5.000	Find & position
2		0		0.000	0.000	0.000	
3		0		0.000	0.000	0.000	
Magazine list							Next magazine
Magazine list			Tool list	Load	Unload	Relocate	

The tool management basic display contains the current "magazine list" with the following information:

**Loc. No.**

Location number

**Tool designation**

Name of tool

Other displays configured by the machine manufacturer, e.g.



**Duplo no.**

Number of spare tool (replacement tool)

**Tool status**

Tool status

No display = Replacement tool

A = Active tool

F = Tool enabled

G = Tool disabled

M = Measured tool

V = Warning limit reached

W = Tool is being changed

P = Fixed-location-coded tool

E = Tool was in use

**WZ type**

Tool type

Depending on the tool type, only certain tool offsets are enabled for selection when the tool is loaded. All other tool types are preset with the value "0".

**T number**

Internal T numbers which may be needed for reloading tool data.

**Geo - L1 ... Radius ...**

Tool offsets such as length, radius, wear, monitoring data, etc.

Magazine  
list**Horizontal softkeys**

The "Magazine list" basic display shows all the tools that are already assigned to a magazine location ("loaded").

Tool  
list

All tools which are stored as a set of data on the NC are displayed (irrespective of whether or not they have been assigned to a magazine location).

Load

A magazine location is assigned to the tool.

Unload

The tool is deleted from the current magazine location.

Relocate

The tool is moved from the current magazine location to another location.

(Names assigned by user)

Maglist 1

Maglist 2

Maglist 3

Tool details

Buffer on

or

Buffer off

Find & position

Next magazine

### Vertical softkeys

Selection of user-specific windows (if configured), e.g.

- General data
- Geometry tool data
- Wear data

Display and edit the tool offset data for a tool.

Display and skip the buffer window in the magazine list. The display shows spindles, grippers, etc., i.e. locations which can accommodate tools but which are not magazine locations.

You can use this softkey to find a tool or tool location in the active tool magazine and position the tool. The tool is moved to the loading point.

Advance to the next magazine.

### 5.3.2 Select new tool



#### Function

If you want to load or unload a tool to/from a magazine, alter or re-edit the current tool data or create a new tool edge, you must first select the appropriate tool in the "Magazine list" or "Tool list".



#### Operating sequence

Tool management

Select softkey "Tool management".

The horizontal and vertical softkey bars change.

Select the menu via the softkey

Magazine list

or

Tool list

"Magazine list" or "Tool list".

Next magazine

Select the appropriate magazine.



Position the cursor bar on the appropriate tool.  
The tool is now selected for editing.

### 5.3.3 Display and modify tool data



#### Function

You can view and edit the tool data of the tool selected in the "Magazine list" or "Tool list".



You can edit the following tool edge data:

- offset values
- Monitoring data



#### Operating sequence

"Magazine list" or "Tool list".

Position the cursor bar on the appropriate tool.  
The appropriate tool is selected.

Select the "Tool details" softkey.  
The "Tool data" menu is displayed.  
The vertical softkey bar changes again.

#### Display/edit tool data:

You can display and edit tool data in menus:

- "Magazine list" (if the tool data, edge data and tool user data are configured in the magazine list)

Switches forward by one edge.

Switches back by one edge.

Creates new edge.  
Edit compensation data of new edge.

Abort input.

Confirm and accept input.

Magazine  
list

or

Tool list

Tool details

D No.  
+

D No.  
-

New  
edge

Abort

OK



A new cutting edge can be attached to a tool at any time (even if the corresponding tool is already in the magazine). Here you enter the cutting edge data.

### 5.3.4 Load tool



#### Function

A tool is loaded to a magazine at the magazine location on which the cursor bar is positioned in the "Magazine list" or "Tool list" menu. You can load a tool to a magazine in one of the following ways:

- **Loading from the "Magazine list"**  
You can load all tools in the magazine. The associated tool data can be loaded from the master data catalog or code carrier (if available) or entered manually as required.
- **Load from "Tool list"**  
You can load magazines whose data are already stored in the TO memory (if available).



#### Operating sequence

The "Magazine list" menu is displayed.  
The horizontal and vertical softkey bars change.

##### Load from "Magazine list":

The "Magazine list" menu is selected.  
The appropriate magazine is selected.

Magazine  
list

Load

Press the "Load" softkey.  
The vertical softkey bar changes.

There are three ways to search the empty location according to different tool sizes in conjunction with location types:

1. Find an empty location
2. Current location
3. Load location

1.

Find empty location

Enter the "Tool size" and "Location type" in the dialog box.

If more than one loading point is configured, select the desired loading point from a query window.

The system searches for a suitable empty location.

The cursor bar is automatically positioned on the magazine location found in the "Magazine list".

2.

Current location

You have found an empty location in front of the current loading point.

When you select "current location," the tool is loaded to the empty location in front of the loading point.

The cursor bar is automatically positioned in the "Magazine list" on the magazine location found in front of the loading point.

3.

Load location

Position the cursor on the location of your choice in the magazine list.



"Load directly to spindle" is possible if the cursor is positioned on the spindle magazine location.



Use the input key to accept the entries for the tool identifier, duplo No. etc.

Abort

Abort the loading operation.

OK

Confirm your inputs with "OK".

Tool list

Load from "**Tool list**":

The "Tool list" menu is selected.

The appropriate tool is selected.

Load

Press the "Load" softkey.

The vertical softkey bar changes.

Find empty location

After pressing the "Find empty location" softkey, the system searches for a suitable location and displays it.

Abort

Abort the loading operation.

OK

Initiate the loading operation.

**The location found is entered under the location number.**

If data are still missing, the tool data display is opened with the missing data set to their defaults. You can start the loading operation again.



## 5.3.5 Unloading of a tool

**Function**

This function allows you to unload a selected tool and to save its data.

**Operating sequence****Unload from "Magazine list":**

The "Magazine list" menu is selected.

The appropriate magazine is selected.

The appropriate tool is selected.

When you press the "Unload" softkey, the magazine number and load point are displayed in the "Unload" window.

If more than one load point is configured, select the appropriate load point from the selection window.

When you press "OK," the tool is unloaded.

Press "Abort" to stop the "Unload" process.

"Unload directly from spindle" is possible only if the buffer is selected and the cursor is positioned on the location of the spindle.

Tool list

Unload

OK

Abort



Tool list

Unload

OK

Abort

Delete  
tool

**Unload from "Tool list":**

The "Tool list" menu is selected.

The appropriate tool is selected.

When you press the "Unload" softkey, the "Unload" window opens and the magazine number and load point are displayed.

If more than one loading point is configured, select the appropriate loading point from the selection window.

Click "OK" to begin the unloading process or

Click on "Abort" to abort the process.

The tool data of the selected tool is deleted from the TO memory. You can do this only if the tool is not currently stored in a magazine location.

### 5.3.6 Relocating a tool



Magazine list

Relocate

Or

Find empty location

OK

Abort



#### Function

This function allows you to move a selected tool from one location to another.

#### Operating sequence

The "Magazine list" menu is displayed.

Position the cursor on the tool to be relocated in the magazine list. When you select the "Relocate" key, the "Relocate tool" window opens.

There are 2 methods by which you can select the new empty location for the tool:

1. Enter the magazine and location numbers in the "Relocate tool" window.
2. Select softkey "Find empty location" and an appropriate empty location is suggested.

Press "OK" to save the tool to the new empty location,

and the relocation operation is aborted with "Abort".

Use magazine number 9998 to move a tool to or from the spindle.

### 5.3.7 Finding and positioning tools



Magazine list

Next magazine

or

Maglist x

#### Function

You can find a tool or tool location in the active tool magazine and position the tool.

The "Magazine list" menu is displayed.

#### Operating sequence

Select the required magazine.

### 5.3 Tool management

Find/  
position

Press the "Find/position" softkey.

A dialog box is overlaid. Enter the tool identifier e.g. T501, duplo No. e.g. 2, as well as the load point.

OK

Press "OK" to execute.

A message appears: e.g. "location 1 found".

Find/  
position

Continue to press the "Find/position" softkey.

The vertical softkey bar changes.

Find  
location

Press the "Find location" softkey. The system suggests the location.

Position

Press the "Position" softkey.

The tool/location is moved to the load point. If there are several load points, a window opens in which you can select the appropriate point with the cursor.

## 5.4 ShopMill tool management



### Function

ShopMill tool management allows workshop-compatible tool management of milling machines.

The following lists are available to you for this function:

- Tool list
- Tool wear list
- Magazine list

You enter the tools and their offset data in the tool list/tool wear list. You can see from the magazine list which magazine locations are disabled or not.

### Tool list

The tool list displays all tools and their offset data stored as a tool data block in the NC, irrespective of whether they are assigned to a magazine location. The tool list offers the current tool types for which geometric and technological data can be assigned.

### Load/Unload

When a tool is loaded, it is taken to a magazine location. Unloading removes the tool from the magazine.

### Sorting

The tools in the tool list and tool wear list can be sorted according to magazine location, name, and type.



### Machine manufacturer

Machine data can be set to hide the "Load," "Unload" and "Sort" softkeys.

### Manual tools

Manual tools are included in the tool list, but not stored in the magazine. They must be attached to the spindle by hand.

### Tool wear list

This list specifies which wear data (length and radius/diameter) are to be taken into account. The following types of monitoring can also be defined for a tool:

- Monitoring of the effective operating time (tool life)
- Monitoring of number of tool load operations
- Additional tool status data (disable tool, tool in fixed location, oversized tool)

**Fixed/flexible assignment of locations**

You can define via a machine data whether all tools are fixed or variable location coded.

- With fixed location coding, the tool is permanently assigned to a magazine location. This concept can be used for machines with disk-type magazine.
- With variable location coding, a tool can also be conveyed to a magazine location other than the original location. This concept can be used for machines with chain magazine. Individual tools can be set to fixed-location-coded in the tool wear screen display at the operator interface.

**Magazine**

The magazine locations are listed with their tools, magazine locations are indicated as disabled/not disabled, and the properties assigned to the active tool (e.g. oversize) are displayed in the magazine list.

**References**

/FBW/ Description of Functions Tool Management or  
 /FBS/ Description of Functions ShopMill  
 /BAS/ Operation/Programming ShopMill

**5.4.1 Function scope****Tool types****Function**

ShopMill tool management supports the following tool types, tool parameters and magazine parameters:

- 120 End mill
- 200 Twist drill
- 220 Center drill
- 710 3D probe
- 711 Edge probe
- 110 Cylindrical die sinker
- 111 Ballhead cutter
- 121 End mill with corner rounding
- 155 Bevel cutter
- 156 Bevel cutter with fillet
- 157 Conical die sinker



	CUTTER
	DRILL
	CENTERDRILL
	EDGE_FINDER
	3D_PROBE
	DIEMILL_CYL
	BALL_END_MILL
	MILL_CORN_RAD.
	MILL_TAPER
	MILL_TAPER_CRAD
	DIEMILL_TAPER

### Operating sequence

Select the "Tool list" softkey.

Press the "New tool" softkey.

The vertical bar changes and you can select different tools via the softkey.

Select the tool location of your choice with the cursor keys

and select the softkey for the desired tool type.

Additional tool types are available via the "More" softkey.

The new tool is created.

In the case of 3D tools, you must define parameters in addition to the geometry data in the tool list.

Tool list

New tool



Cutter

3D tools

More

### 3D tools

Type	Name	Additional parameters
110	Cylindrical die mill	-
111	Ball end mill	Smoothing radius
121	End mill with corner rounding	Smoothing radius
155	Truncated cone mill	Angle for conical tools
156	Bevel cutter with corner rounding	Rounding radius, angle of conic. tools
157	Tapered die mill	Angle for conical tools

Details

Press the softkey "Details" and enter the fillet radius and angle for the conical milling tools.

#### 5.4.4 Set up more than one edge for each tool



In the case of tools with more than one cutting edge, a separate set of offset data is assigned to each cutting edge. You can create up to 9 cutting edges for each tool.

In the case of ISO programs (e.g. ISO dialect 1) you must specify an H number. This corresponds to a particular tool offset set.

#### Operating sequence

Follow the instructions given above to set up tools with more than one edge in the tool list and enter the offset data for the 1<sup>st</sup> edge.

Then select the "Edges" and "New edge" softkeys.

Instead of the input fields for the first cutting edge, the offset data input fields for the second cutting edge are displayed.

Enter the offset data for the second cutting edge.

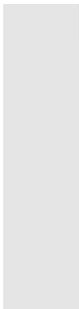
Repeat this process if you wish to create more tool edge offset data.

Select the "Delete edge" softkey if you want to delete the tool edge offset data for an edge.

You can only delete the data for the edge with the highest edge number.

By selecting softkey "D No. +" or "D No. -", you can display the offset data for the edge with the next higher or next lower edge number respectively.

#### 5.4.5 Changing a tool name

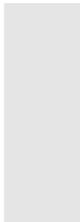


A tool that has just been created in the tool list is automatically assigned the name of the selected tool group. You can change this name as often as you want to

- A tool name, e.g. "plain mill\_120mm" or
- A tool number, e.g. "1".

The tool name must not exceed 17 characters in length. You can use letters, digits, the underscore symbol ( ), periods (".") and slashes ("/").

### 5.4.6 Creating duplo/replacement tools



The duplo/replacement tool is a tool that can be used for the same machining operations as a tool that already exists (e.g. for use after a tool breakage).

When you create a replacement tool, you must use the same name as is used for a comparable tool.

#### Operating sequence

Create the replacement tool as a new tool. See Subsection "Create new tool"

Assign the same name as the original tool to the replacement tool. Confirm the name with the "input" key and the duplo number of the replacement tool is automatically incremented by 1.

The sequence for inserting a replacement tool is determined by the duplo number **DP**.

### 5.4.7 Manual tools



#### Machine manufacturer

The "Manual tool" function must be set up by the machine manufacturer.

Manual tools are tools which are required during machining, but are only available in the tool list but not in the tool-holding magazine. These tools must be attached/detached manually to/from the spindle.

Please note information supplied by machine tool manufacturer!

### 5.4.8 Enter tool wear data



Tool wear

Tools that are in use for long periods are subject to wear. You can measure this wear and enter it in the tool wear list. ShopMill then takes this information into account when calculating the tool length or radius compensation. This ensures a consistent accuracy in workpiece machining.

You enter the wear data for a tool that you have created in the tool wear list.

The upper limits are set in a machine data code.

#### Operating sequence

Select the "Tool wear" softkey.

Parameter	CHAN1	JOG	\MPF_DIR CMM_SINGLE.MPF					
Channel reset								
Program aborted								
Tool wear								
Loc	Typ	Tool name	DP	1st cutting edge	$\Delta$ Length $\Delta s$	T	C	
#	U	Zent2	2	0.000	0.00000			
>								
<								
1	U	Zent1	2	0.000	0.00000			
2								
3	U	Zent3	1	0.000	0.00000			
4	B	Bohr1	1	0.000	0.00000			
5	B	Bohr2	1	0.000	0.00000			
6	U	Bohr3	1	0.000	0.00000			
7	B	Gewinde1	1	0.000	0.00000			
8	B	Gewinde2	1	0.000	0.00000			
Tool list					Tool wear	Magazine	Work offset	R variables

Example of a tool wear list with variable location allocation

Place the cursor on the tool whose wear data you want to enter.



Enter the differences for length ( $\Delta$ Length X,  $\Delta$ Length Z) and radius/diameter ( $\Delta$ Radius/ $\Delta\varnothing$ ) in the appropriate columns.

The wear data entered is added to the radius but subtracted from the tool length. A positive differential value for the radius therefore corresponds to an oversize (e.g. for subsequent grinding).

Please note information supplied by machine tool manufacturer!



Machine manufacturer

### 5.4.9 Activate tool monitoring

ShopMill allows you to monitor the tool life of the tools automatically to ensure constant machining quality.

You can also disable tools that you no longer want to use or identify them as oversize or assign them to a magazine location.

In the tool wear list you can assign each tool the following tool monitoring and properties:

- Tool life
- Number of workpieces
- Other tool properties
  - Lock tool
  - Tool in fixed location
  - Oversized tool

The tool monitoring functions are activated via machine data.



#### Machine manufacturer

Please follow the machine manufacturer's instructions!



#### Operating sequence

Select "Tool wear" via softkey

Tool wear

Tool life (T)

The tool life is used to monitor the service life of a tool with machining feedrate in minutes. When the remaining tool life is  $\leq 0$ , the tool is set to "disabled". The tool is not put into operation on the next tool change. If a replacement tool is available, it is inserted in its place. The tool life monitoring function always refers to the selected tool edge.

Count (C)

With the count C, however, the number of tool changes is counted in the spindle. The tool is also disabled in this case, when the remainder reaches "0".

Wear (W)

With wear W, the greatest value in the wear parameters  $\Delta$  Length X,  $\Delta$  Length Z or  $\Delta$  Radius or  $\Delta \Delta$  in the wear list is monitored. Here too the tool is disabled if one of the wear parameters reaches the value for wear W.



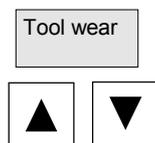
#### Machine manufacturer

Please follow the machine manufacturer's instructions!

Prewarning limit	The pre-warning limit specifies the tool life, workpiece count or wear at which the first warning is displayed.
Disabled (G)	Individual tools can also be disabled manually if you no longer want to use them for workpiece machining.
Oversize (U)	In the case of oversize tools, neighboring magazine locations (left and right adjacent location) are only reserved alternately, i.e. you can only insert the next tool in the next magazine location but one (this can also contain an oversize tool).
Coded for fixed location (P)	You can assign tools a fixed location, i.e., the tool can only be used at the current magazine location. The tool returns to the old magazine location when switching back.



### Monitoring tool use



Select the "Tool wear" softkey.

Position the cursor on the tool that you want to monitor.

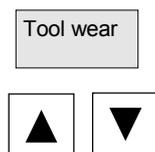
In the column "T/C" select the parameter that you wish to monitor (T = Tool life, C = Count, W = Wear).

Enter a pre-warning limit for tool life, count or wear.

Enter the scheduled service life for the tool, the scheduled number of workpieces to be machined or the maximum permissible wear.

The tool is disabled when the tool life, count or wear is reached.

### Enter tool status



Select the "Tool wear" softkey

Place the cursor on a tool.

Option G

Select the option "G" in the first field of the last column if you want to disable the tool for machining.

-or-

Option U

Select the option "U" in the second field of the last column if you want to mark the tool as oversize.

Option P

-or-

Select the option "P" in the third field of the last column if you want to assign the tool to a fixed magazine location.

The set tool properties are immediately active.

### 5.4.10 Managing magazine locations

The magazine locations are listed with their tools, magazine locations are indicated as disabled/not disabled, and the properties assigned to the active tool (e.g. oversize) are displayed in the magazine list.

#### Operating sequence

Select the "Magazine" softkey.

Magazine

#### Disabling a magazine location



#### Tool status

Magazine locations can be reserved or disabled for specific tools, e.g. in the case of an oversized tool.

Selecting the required magazine location.

Toggle in column "Disable location" with the softkey "Alternative" until a "G" (= disabled) appears in the field in question. The location is now disabled. A tool can no longer be loaded into this magazine location.

In the "Tool status" column you can see which properties have been assigned to the active tool:

- G: Tool is disabled
- U: Tool oversized
- P: Tool at a fixed location

#### Enabling a magazine location



Position the cursor on the disabled field.

Deselect option G in the "Location disable" column.  
The magazine location is enabled again.

### 5.4.11 Delete tools



Tool list



Delete tool

Delete

Abort

#### Function

Tools can be deleted from the tool list.

#### Operating sequence

Select the "Tool list" softkey.

Select the tool of your choice.

Press the "Delete tool" softkey and confirm with "Delete".

The tool data of the selected tool are deleted, and the magazine location in which the deleted tool was located is enabled.

The tool is not deleted with "Abort".

### 5.4.12 Change tool type



Tool list



Alternative

#### Function

In the tool list you can change a tool type into another tool type.

#### Operating sequence

Select the "Tool list" softkey.

Select the desired tool and position the cursor on input field "Type".

You can switch to the tool type you want with the "Alternative" key. The input fields for the new tool type are displayed.

## 5.4.13 Load or unload tool in magazine



## Machine manufacturer



## Load a tool into the magazine



Load

Spindle

Loading and unloading of tools into and out of magazine locations must be enabled in a machine data code.

**Function**

You can unload tools in the magazine that you are not using at present. ShopMill then automatically saves the tool data in the tool list outside the magazine. If you want to use the tool again later, simply load the tool with the tool data into the corresponding magazine location again. Then the same tool data does not have to be entered more than once.

Please follow the machine manufacturer's instructions!

**Operating sequence**

Place the cursor on the tool that you want to load into the magazine (if the tools are sorted according to magazine location number you will find it at the end of the tool list).

Press the "Load" softkey.

The "Empty location" window appears. The "Location" field is initialized with the number of the first empty magazine location.

Press the "OK" softkey to load the tool into the suggested location.

-or-

Enter the location number you require and press the "OK" softkey.

-or-

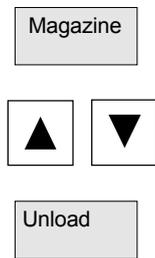
Enter the location number you require and press the "OK" softkey.

-or-

Press the "Spindle" and "OK" softkeys to load a tool into the spindle.

The tool is loaded into the specified magazine location.

### Unload an individual tool from the magazine



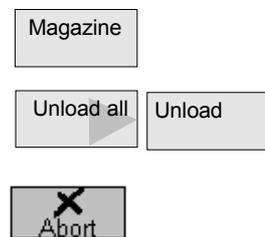
Select the "Magazine" softkey.

Position the cursor on the tool that you want to unload.

Press the "Unload" softkey.

The tool is unloaded from the magazine.

### Unload all tools from the magazine



Select the "Magazine" softkey

Press the "Unload all" and "Unload" softkeys.

All tools are unloaded from the magazine.

You can abort the unloading process at any time by pressing the "Abort" softkey. The current tool is still unloaded, but then the process is aborted.

The unloading process is also aborted if you exit the magazine list.

## 5.4.14 Relocating tools



Tools can be relocated within magazines or between different magazines, which means that you do not have to unload tools from the magazine in order to load them into a different location.



ShopMill automatically suggests an empty location to which you can relocate the tool. The magazine in which ShopMill searches for an empty location first is stored in a machine data code.

You can also specify an empty magazine location directly or define the magazine ShopMill should search for an empty location.

If your machine has only one magazine, you simply need to enter the location number you require, not the magazine number.

If a spindle location is shown in the tool list, you can also load or unload a tool directly into or out of the spindle.



### Machine manufacturer

Please follow the machine manufacturer's instructions!



### Specify an empty location

Tool list

Select the "Tool list" softkey.

Place the cursor on the tool that you wish to relocate to a different magazine location.

Relocate

Press the "Relocate" softkey.

The "Empty location" window appears. The "Location" field is initialized with the number of the first empty magazine location.

Press the "OK" softkey to relocate the tool to the suggested location.

-or-

Enter the location number you require and press the "OK" softkey.

-or-

Spindle

Press the "Spindle" and "OK" softkeys to load a tool into the spindle.

The tool is relocated to the specified magazine location.

### Find an empty location

Relocate

Press the "Relocate" softkey.

The "Empty location" window appears. The "Location" field is initialized with the number of the first empty magazine location.

Enter the magazine number and a "0" for the location number if you wish to search for an empty location in a particular magazine.

-or-

Enter a "0" for the magazine number and location number if you wish to search for an empty location in all magazines.

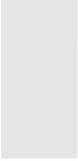
Press the "OK" softkey.

An empty location is suggested.

Press the "OK" softkey.

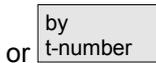
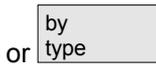
The tool is relocated to the suggested magazine location.

### 5.4.15 Sorting tools in the tool list



#### Function

The tools can be sorted according to magazine location, tool name (alphabetical), or tool type in the tool list. When you sort according to magazine assignment, the empty locations in the magazine are also displayed.



#### Operating sequence

Select the "Tool list" or "Tool wear" softkey.

Press the "Sort" softkey.

Activate one of the softkeys to choose the sort criteria.

The tools are listed in the new order.

## 5.5 Tool management ShopTurn

**Function**

ShopTurn is an operating and programming software program for turning machines that makes it easy for you to operate the machine and to program workpieces.

Various tools are used for machining workpieces. The geometry and technological data of these tools must be known to ShopTurn before you execute your program.

ShopTurn provides the "Tool list", "Tool wear list" and "Magazine list" screen forms for managing your tools,

**Tool list**

You must enter all the tools that you want to use on the turning machine in the tools list. The tools that are in the tool turret must be assigned to specific magazine locations. You can also sort and delete tools.

**Load/Unload** When a tool is loaded, it is taken to a magazine location. Unloading removes the tool from the magazine.

**Sorting** Tools can be sorted in the tool and tool wear lists according to magazine location, name and type.

**Machine manufacturer**

Machine data can be set to hide "Load", "Unload" and "Sort" softkeys.

**Manual tools**

Manual tools are included in the tool list, but not stored in the magazine. They must be attached to the spindle by hand.

**Tool wear list**

You must enter the wear data for your tools in the tool wear list. ShopTurn takes this data into account on machining the workpiece. You can also activate tool monitoring here as well as disable tools or identify them as oversized.

**Magazine list**

The magazine locations are listed with their tools; magazine locations are indicated as disabled (G) / not disabled ( ), and the properties assigned to the active tool (e.g. oversize (U)) are displayed in the magazine list.



## References

/BAT/ Operator's Guide ShopTurn/Tool Management  
 /FBW/ Description of Functions Tool Management or  
 /FBT/ Description of Functions ShopTurn

### 5.5.1 Function Scope



#### Function

ShopTurn tool management supports the following tool types, tool parameters and magazine parameters:

You can create up to 250 tools under PCU 20.

You can create up to 98 replacement tools for each tool.

#### Tool types

- Roughing tool
- Finishing tool
- Recessing tool
- Milling tool
- Drill
- Button
- Limit stop
- Threading tool
- Rotary drill
- 3D\_probe

#### Tool parameters

- Magazine location/magazine number
- Tool type
- Tool name
- Duplo number
- Tool length compensation in the X direction
- Tool length compensation in the Z direction
- Wear radius
- Tip length of a cutting tool or a grooving cutter
- Tip width of a grooving tool
- Angle of teeth for a milling cutter
- Angle of tool tip on a drill
- Type of tool monitoring: optionally according to tool life or tool change in relation cutting edge.
- Tool state: Tool disabled
- Tool state: Tool oversized (right and left half locations)

#### Magazine parameters

- Magazine location disabled

## 5.5 Tool management ShopTurn

### Additional functionality

- You can use circular magazines that are hidden via display machine data.
- Loading station for loading and unloading tools via display machine data
- Display tools (milling tool/drill) in diameter or radius via display machine data

### 5.5.2 Select tool list



Tool list

### Operating sequence

When you call up the "Parameters" operating area for the first time, the "Tool list" menu is automatically displayed. Otherwise you can call it via softkey.

### 5.3 Create new tool



When you want to create a new tool, ShopTurn offers a range of generally available tool types. The tool type determines what geometry data you have to enter and how it is calculated.

	ROUGHING TOOL
	FINISHING TOOL
	PLUNGE-CUTTER
	CUTTER
	DRILL
	THREADING TOOL
	BUTTON TOOL
	STOCK_STOP
	3D_PROBE

*Possible tool types*

The rotary drill can be used for centric drilling and turning.





Tool list



New tool

Roughing tool

3D\_Probe

More

Edges

More



## Operating sequence

Install the new tool in the tool turret.

Select the "Tool list" softkey.

In the tool list, position the cursor on the location that the tool is to occupy in the turret.

The location must still be empty in the tool list.

Press the "New tool" softkey.

Use the softkeys to select the tool type of your choice. Additional tool types are available via the "More" softkey.

Select the required cutting edge position.

Additional cutting edge positions are available via the "More" softkey.

The new tool is created and automatically assumes the name of the selected tool type.

Enter a unique tool name.

You can edit the tool name as required. A tool name may contain a maximum of 17 characters. You can use letters, digits, the underscore symbol (`_`), periods (`.`) and slashes (`/`).

Enter the offset data of the tool.

If you would like to change the tool's cutting edge position later,

Place the cursor in the "Type" column.

Use the "Alternative" softkey or the "Select" key to select one of the specified options.

### 5.5.4 Setting up more than one cutting edge for each tool



In the case of tools with more than one cutting edge, a separate set of offset data is assigned to each cutting edge. You can set up a total of 9 edges for each tool.

#### Operating sequence

Follow the instructions given above to set up tools with more than one edge in the tool list and enter the offset data for the 1st edge.

- Then select the "Edges" and "New edge" softkeys.

Instead of the input fields for the first cutting edge, the offset data input fields for the second cutting edge are displayed.

- Select another cutting edge position if appropriate.
- Enter the offset data for the second cutting edge.
- Repeat this process if you wish to create more tool edge offset data.
- Select the "Delete edge" softkey if you want to delete the tool edge offset data for an edge.

You can only delete the data for the edge with the highest edge number.

By selecting softkey "D No. +" or "D No. -", you can display the offset data for the edge with the next higher or next lower edge number respectively.

### 5.5.5 Creating duplo/replacement tools



A replacement tool is one that can be employed to perform the same machining operation as a tool that has already been entered. You can use it, for example, to replace a broken tool.

For each tool in the tool list, you can create several replacement tools. The duplo number 1 is always assigned to the original tool and duplo numbers 2, 3, etc. are assigned to the replacement tools.



### Operating sequence

Create the replacement tool as a new tool. See Section "Create new tool"

Assign the same name as the original tool to the replacement tool.

Confirm the name with the "input" key and the duplo number of the replacement tool is automatically incremented by 1.

The sequence for inserting a replacement tool is determined by the duplo number **DP**.

### 5.5.6 Sort tools



When you are working with large magazines or several magazines, it is useful to display the tools sorted according to different criteria. Then you will be able to find a specific tool more easily in the lists.

### Operating sequence

Select the "Tool list" or "Tool wear" softkey.

Press the "Sort" softkey.

Activate one of the softkeys to choose the sort criteria.

The tools are listed in the new order.

### 5.5.7 Delete tools



Tools that are no longer in use can be deleted from the tool list for a clearer overview.

### Operating sequence

Select the "Tool list" softkey.

Select the tool of your choice.

Press the "Delete tool" softkey and confirm with "Delete".



The tool data of the selected tool are deleted, the magazine location in which the deleted tool was located is enabled.



The tool is not deleted with "Abort".

## 5.8 Load or unload tool in magazine



The tool list has more locations than magazine locations. This means you can unload tools you currently do not need in the magazine and save the tool data in the tool list outside the magazine. If you want to use the tool again at a later point in time, simply load the tool data back to the magazine location. Then the same tool data does not have to be entered more than once.

Loading and unloading of tool data into and out of magazine locations must be enabled in a machine data code.



### Machine manufacturer

Please follow the machine manufacturer's instructions!



### Operating sequence

#### Load a tool into the magazine



Place the cursor on the tool that you want to load into the magazine (if the tools are sorted according to magazine location number you will find it at the end of the tool list).



Press the "Load" softkey.

The "Empty location" window appears. The "Location" field is initialized with the number of the first empty magazine location.

Press the "OK" softkey to load the tool into the suggested location.

-or-

Enter the desired location number and press the "OK" softkey.

The data relating to your tool are now displayed in the specified magazine location.

### Unload an individual tool from the magazine



Select the "Magazine" softkey



Position the cursor on the tool that you want to unload.



Press the "Unload" softkey.

The tool data are removed from the magazine and stored in the tool list in a position without a number.

### Unload all tools from the magazine



Select the "Magazine" softkey



Press the "Unload all" and "Unload" softkeys.

All tools are unloaded from the magazine.



You can abort the unloading process at any time by pressing the "Abort" softkey. The current tool is still unloaded, but then the process is aborted.

The unloading process is also aborted if you exit the magazine list.

## 5.5.9 Relocating tools



Tools can be relocated within magazines or between different magazines, which means that you do not have to unload tools from the magazine in order to load them into a different location.

ShopTurn automatically suggests an empty location to which you can relocate the tool. The magazine in which ShopTurn searches for an empty location first is stored in a machine data code.

You can also specify an empty magazine location directly or define the magazine ShopTurn should search for an empty location.

If your machine has only one magazine, you simply need to enter the location number you require, not the magazine number.

If a spindle location is shown in the tool list, you can also load or unload a tool directly into or out of the spindle.



### Machine manufacturer

Please follow the machine manufacturer's instructions!



### Specify an empty location

Tool list

Select the "Tool list" softkey.

Place the cursor on the tool that you wish to relocate to a different magazine location.

Relocate

Press the "Relocate" softkey.

The "Empty location" window appears. The "Location" field is initialized with the number of the first empty magazine location.

Press the "OK" softkey to relocate the tool to the suggested location.

-or-

Enter the desired location number and press the "OK" softkey.

-or-

Spindle

Press the "Spindle" and "OK" softkeys to load a tool into the spindle.

The tool is relocated to the specified magazine location.

### Find an empty location

Relocate

Press the "Relocate" softkey.

The "Empty location" window appears. The "Location" field is initialized with the number of the first empty magazine location.

Enter the magazine number and a "0" for the location number if you wish to search for an empty location in a particular magazine.

-or-

Enter a "0" for the magazine number and location number if you wish to search for an empty location in all magazines.

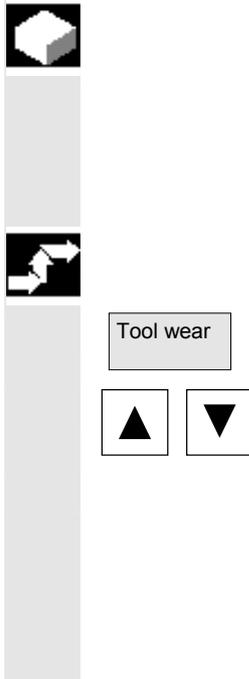
Press the "OK" softkey.

An empty location is suggested.

Press the "OK" softkey.

The tool is relocated to the suggested magazine location.

### 5.5.10 Enter tool wear data



Tools that are in use for long periods are subject to wear. You can measure this wear and enter it in the tool wear list. ShopTurn then takes this information into account when calculating the tool length or radius compensation. This ensures a consistent accuracy in workpiece machining.

#### Operating sequence

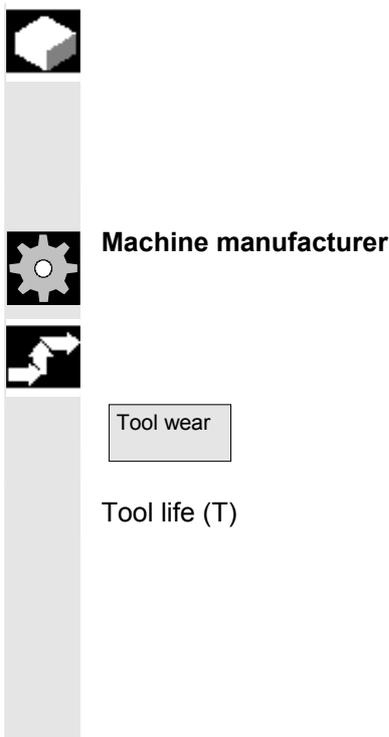
Select "Tool wear" via softkey

Place the cursor on the tool whose wear data you want to enter.

Enter the differences for length ( $\Delta\text{Length } X$ ,  $\Delta\text{Length } Z$ ) and radius/diameter ( $\Delta\text{Radius}/\Delta\varnothing$ ) in the appropriate columns.

The wear data entered is added to the radius but subtracted from the tool length. A positive differential value for the radius therefore corresponds to an oversize (e.g. for subsequent grinding).

### 5.11 Activate tool monitoring



ShopTurn allows you to monitor the tool life of the tools automatically to ensure constant machining quality.

You can also disable tools that you no longer want to use or identify them as oversize.

The tool monitoring functions are activated via display machine data. Please follow the machine manufacturer's instructions!

#### Operating sequence

Select "Tool wear" via softkey

With the tool life T (Time), the service life for a tool with machining feedrate is monitored in minutes. When the remaining tool life is = 0, the tool is set to "disabled". The tool is not put into operation on the next tool change. If a replacement tool is available, it is inserted in its place.

Tool life is monitored on the basis of the selected tool cutting edge.

**5.5 Tool management ShopTurn**

Count (C)

With the count C, the number of workpieces machined by the tool is counted. The tool is also disabled in this case, when the remainder reaches "0".

Wear (W)

With wear W, the greatest value in the wear parameters  $\Delta$  Length X,  $\Delta$  Length Z or  $\Delta$  Radius or  $\Delta \varnothing$  in the wear list is monitored. Here too the tool is disabled if one of the wear parameters reaches the value for wear W.

**Machine manufacturer**

Please follow the machine manufacturer's instructions!

Prewarning limit

The pre-warning limit specifies a tool life or quantity at which an initial warning is output.

Disabled (G)

Individual tools can also be disabled manually if you no longer want to use them for workpiece machining.

Oversize (U)

In the case of oversize tools, neighboring magazine locations are only reserved alternately, i.e. you can only insert the next tool in the next magazine location but one (this can also contain an oversize tool).

Coded for fixed location (P)

You can assign tools a fixed location, i.e., the tool can only be used at the current magazine location. The tool returns to the old magazine location when switching back.

**Monitor tool use**

Tool wear

Select "Tool wear" via softkey



Position the cursor on the tool that you want to monitor.



### Enter tool status

#### Option G

In column "T/C", select option "T" if you want to monitor the tool life.  
(T = Tool life, C = Count, W = Wear).

Enter a pre-warning limit for tool life, count or wear in minutes.

Enter the scheduled service life for the tool, the scheduled number of workpieces to be machined or the maximum permissible wear.

The tool is disabled when the tool life, count or wear is reached.

If you wish to monitor the count, you must also insert the following G code commands before the end of the program in every program that calls the tools to be monitored:

```
SETPIECE (1)           ; increase count by 1
SETPIECE (0)           ; delete T no.
```

Place the cursor on a tool.

Select the option "G" in the first field of the last column if you want to disable the tool for machining.

-or-

#### Option U

Select the option "U" in the second field of the last column if you want to mark the tool as oversize.

The tool disable or location disable for neighboring magazine locations is now active.

### 5.5.12 Manage magazine locations

The magazine locations are listed with their tools, magazine locations are indicated as disabled/not disabled, and the properties assigned to the active tool (e.g. oversize) are displayed in the magazine list.

#### Disable magazine location

If a magazine location is defective, or when an oversize tool requires more than half a neighboring location, you can disable the magazine location.

#### Operating sequence

Select with the "Magazine" softkey

Place the cursor on the relevant empty magazine location in the "Location disable" column.

Use the "Alternative" softkey to toggle the setting until a "G" (=disabled) appears in the field.

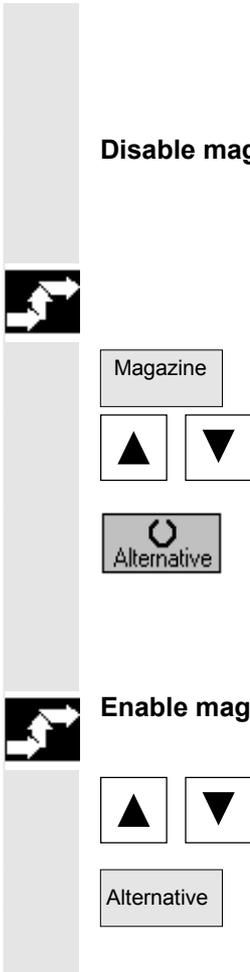
The location disable is now active and you can no longer assign tool data to this magazine location.

#### Enable magazine location

Place the cursor on an empty magazine location in the "Location disable" column.

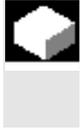
Press the "Alternative" softkey until the letter "G" no longer appears.

The magazine location is enabled again.



## 5.6 R parameters

### 5.6.1 Function



#### Function

Parameters are read and written by programs.  
In this operating area, parameters can be altered manually.

### 5.6.2 Editing/deleting/finding R variables



#### Function

The number of channel-specific R variables is defined in machine data.

#### Range:

R0–999 (dependent on machine data).  
There are no gaps in the numbering within the range.

#### Operating sequence

The "R variables" window appears.  
The channel-specific parameters are displayed.  
The vertical softkey bar changes.

#### Change parameters:

Position the cursor bar on the appropriate input field and enter the new values.

#### Delete parameters:

Displays a marker in which the Rx to Ry parameter range to be deleted must be entered.

The complete R variable range is deleted after a safety query and "OK", i.e. all values are set to 0.

You cannot delete using "Abort".



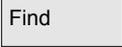
R variables

Delete area

Delete all

OK

Abort

A rectangular button with the word "Find" centered inside.**Finding parameters:**

An input window for a parameter number appears when you press the "Find" softkey.

Enter the R variable number you wish to find via the numeric keypad. When you press the "Input key", the cursor is automatically positioned on this parameter if it exists.

**Further information**

Input and deletion of parameters can be disabled via the key switch.

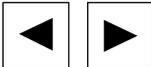
## 5.7 Setting data

### 5.7.1 Working area limitation



Setting  
data

Working  
area limitat.



#### Function

The "Working area limitation" function can be used to limit the range within which a tool can traverse in all channel axes. These commands allow you to set up protection zones in the working area which are out of bounds for tool movements.

#### Operating sequence

Select softkey "Setting data".  
The vertical softkey bar changes.

Select softkey "Working area limitation".  
The "Working area limitation" window opens.

#### Alter working area limitation:

Position the cursor on the desired field.

Enter the new values on the numeric keypad.

The upper or lower limit of the protection zone changes according to your input.

Activate the appropriate working area limitation with the "Select key".

In "MDA" and "Automatic" modes, the working area limitation is not activated according to setting data within the current NC program until a "WALIMON" command is set.

#### Further information

The "Working area limitation" function can be disabled by means of the key switch.

## 5.7.2 Jog data

**Function**

The feedrates must be specified in the unit determined by the G function.

**G function**

G94 Feedrate in mm (inch)/min  
G95 Rotational feedrate in mm (inch)/rev

**Jogfeedrate**

Feedrate value in Jog mode

**Jogcontinuous**

- Jog mode: Axis moves as long as key is pressed.
- Continuous mode: Axis moves after pressing key once, until
  - the key is pressed again,
  - NC Stop,
  - Reset,
  - SW/HW limit switches.

**Variable increment**

Increment value for Jog variable increment

**Jog spindle speed**

The following data are displayed only if a spindle is configured:  
Spindle speed in Jog mode

**Spindle**

Jog data for the master spindle:

- Spindle no.                      Name of master spindle
- Direction of rotation:        Direction of rotation of master spindle
- Spindle speed:                Speed of the master spindle in Jog mode



Setting  
data

Select softkey "Setting data".  
The vertical softkey bar changes.

Jog data

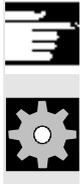
Select softkey "Jog data".  
The "Jog data" window is opened.

**Change jog data:**

Position the cursor bar on the appropriate input field and enter a new value or

Select a new value using the "Select" key.





### Further information

The limit values for the maximum and minimum permissible values are defined in the machine data.

### 5.7.3 Spindle data

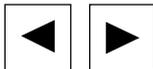


Max./min.



Setting  
data

Spindle  
data



### Function

The value entered for the spindle speed in the fields max./min. must be within the limit values defined in the machine data. In addition, a further spindle speed limitation can be active in the program on account of the SIMS command.

### Operating sequence

Select softkey "Setting data".  
The vertical softkey bar changes.

Select softkey "Spindle data".  
The "Spindle data" window is opened.

### Change spindle data:

Position the cursor bar on the appropriate input field and enter a new value or

select a new value using the "Select" key.

### Further information

- The limit values for the maximum and minimum permissible values are defined in the machine data.
- The "Spindle data" function is displayed only if a spindle is configured.

### 5.7.4 Dry run feedrate for DRY mode



#### Function

The feedrate entered here is used in the active program instead of the programmed feedrate when the function "Dry run feedrate" (program control) is selected in "Automatic" mode.



#### Operating sequence

Setting  
data

Select softkey "Setting data".  
The vertical softkey bar changes.

Feedrate  
DRY

Select "Feedrate DRY" softkey.  
The "Dry run feedrate" window is opened.

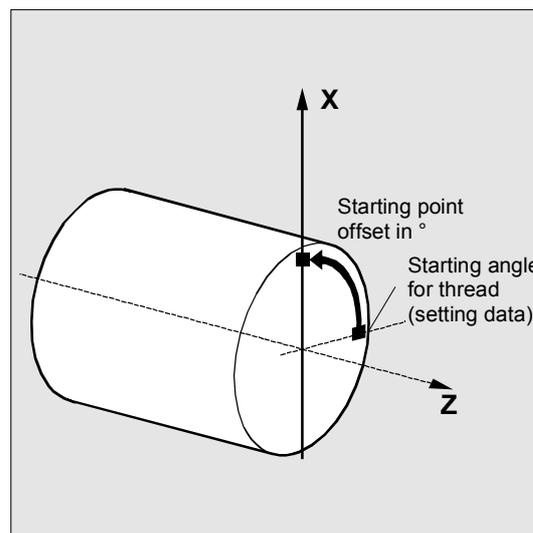
Change the dry run feedrate:  
Enter a new value.

### 5.7.5 Starting angle for thread cutting



#### Function

For thread cutting, a starting position for the master spindle is displayed as the starting angle. A multiple thread can be cut by changing the angle when the thread cutting operation is repeated.





Setting data

Starting angle

### Operating sequence

Select softkey "Setting data".  
The vertical softkey bar changes.

#### Change starting angle:

Select softkey "Starting angle".  
The "Starting angle for thread" window opens.

Enter a new value.

### 5.7.6 Other types of setting data



### Function

All the setting data in the control are displayed in tabular form sorted according to general (i.e. NCK-specific), channel-specific and axis-specific setting data. The table contains both the setting data on the vertical softkeys such as working area limitation, Jog data etc., as well as special setting data such as software cam, oscillation, compensation etc.



Setting data

Misc.

General SD

Channel-specific SD

Axis-specific SD

### Operating sequence

Select softkey "Setting data".  
The vertical softkey bar changes.

#### Display setting data:

Select softkey "Misc.".  
The horizontal and vertical softkey bars change.

Select the type:

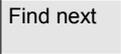
- The "General setting data (\$SN\_)" window is opened.
- The "Channel-specific setting data (\$SC\_)" window is opened.
- The "Axis-specific setting data (\$SA\_)" window is opened.

The current setting data of the corresponding type \$SN\_, \$SC\_ or \$SA\_ are displayed.

#### Find setting data:

In the "Find setting data" window enter the name or number you are looking for (initial identifier is enough).

Find



Find next

If several setting data have the same initial identifier, you can display other setting data by selecting softkey "Find next".

#### Change setting data:

Position the cursor bar on the appropriate input field and enter a new value.

#### Further information

Data can be edited or not depending on the active access protection level.

### 5.7.7 Protection zones



#### Function

The "Protection zones" function allows you to protect various elements on the machine, your equipment or the machined workpiece against incorrect axis motions. You can view up to 10 programmed protection zones in levels G17, G18 and G19.



#### References

/PGA/ Programming Guide, Advanced



#### Operating sequence



Setting data

Select softkey "Setting data".



Protection zones

The vertical softkey bar changes.

Select softkey "Protection zones".



Protection zone +

The "Working area limitations and protection zones" window opens.

The vertical softkey bar changes again.



Protection zone -

Select softkey "Protection zone +" or "Protection zone -".

Up to 10 protection zones are displayed in succession.



G17

Select the plane in which the relevant protection zone is located:



G18

- Plane G17 (X,Y; positioning direction Z)



G19

- Plane G18 (Z,X; positioning direction Y)

- Plane G19 (Y,Z; positioning direction X)

## 5.8 Zero offset

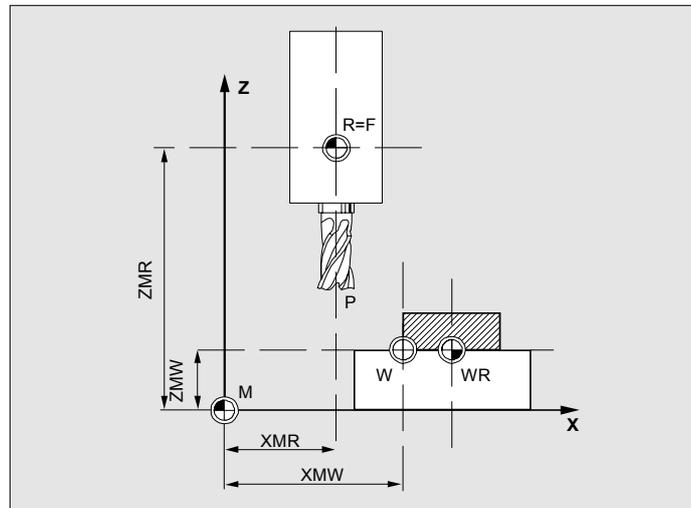
### 5.8.1 Function

#### Machine/tool zero

The actual values are referred to the machine zero after reference point approach. The machining program of the workpiece refers to the workpiece zero.

The machine zero and workpiece zero are not necessarily identical. Depending on the type of workpiece and the way it is clamped, the distance between the machine zero and workpiece zero can vary. In part program processing this is compensated for by the work offset.

#### Work offset on a milling machine



<b>P</b>	Tool setting point
<b>W</b>	Workpiece zero
<b>F</b>	Slide reference point
<b>XMR, ZMR</b>	Reference point coordinates
<b>XMW, ZMW</b>	Zero point offset
<b>M</b>	Machine zero
<b>R</b>	Machine reference point
<b>WR</b>	Workpiece reference point

#### Effective WO

The work offset effective in an axis

$\$P\_ACTFRAME=...$  is calculated from the **sum** of the following zero offsets:

**Settable WO**

You can activate a settable zero offset in the program you have called with G54 to G57 and other G functions or with `$P_IFRAME=...`

**Basic zero offset** (basic frame): Is displayed like a settable WO.

**Programmable WO**

You can use the programmable zero offset `$P_PFRAME=...` to program an additional work offset for geometry and special axes in the part program you have called.

The values of the programmed work offsets are deleted with end of program or reset.

**External WO**

In addition to all the offsets which define the position of the workpiece zero point, an external zero offset can be overlaid by means of the handwheel (DRF offset) or from the PLC.

**DRF offset**

Differential Resolver Function: An NC function which generates an incremental zero offset in automatic mode in conjunction with an electronic handwheel.

**Frame**

Frame is the conventional term for a geometrical expression that describes an arithmetic rule, such as translation or rotation.

Frames are used to describe the position of a destination coordinate system by specifying coordinates or angles starting from the current workpiece coordinate system.

Possible frames

- Basic frame (basic offset)
- Settable frames (G54...G599)
- Programmable frames

**References**

/PGA/ Programming Guide Advanced

**Frame components****Frame components**

A frame can consist of the following arithmetic rules:

- Zero point offset, TRANS, ATRANS
- Rotation, ROT, AROT
- Scale, SCALE, ASCALE
- Mirroring, MIRROR, AMIRROR

In the part program, all work offsets can be deselected non-modally with G53.



### 5.8.2 Display zero/work offsets



Zero offset

Overview

Axis +

Axis -

Offsets

Rotation  
scal., mirr.

#### Function

In the overview, all existing settable work offsets are listed. The number of possible work offsets is defined by a machine datum. The first settable work offsets G54 to G57 are permanently assigned the identifiers \$P\_UIFR[1] to \$P\_UIFR[4].

#### Operating sequence

Press the "Zero offset" softkey.  
The vertical softkey bar changes.

Select the "Overview" softkey and the following overview appears:

Parameter	CHAN1	Jog	MPF.DIR	CHIRON.MPF	
Channel RESET					Axis +
Program aborted					
ROV					FST
Work offset (WO) overview					Axis -
	Axis	X1	Y1	Z1	
Settable WO	Rotation (in °)	0.000	0.000	1.000	Offset
	Scale	1.000	1.000		
	Mirroring				
Programmed WO	Rotation (in °)	0.000	0.000	1.000	Basic WO
	Scale	1.000	1.000		
	Mirroring				
Total basic WO	Rotation (in °)	0.000	0.000	1.000	Settable work offsets
	Scale	1.000	1.000		
	Mirroring				
Resulting WO	Rotation (in °)	0.000	0.000	1.000	Overview
	Scale	1.000	1.000		
	Mirroring				
External WO	Rotation (in °)	0.000	0.000	1.000	
	Scale	1.000	1.000		
	Mirroring				
Total WO	Rotation (in °)	0.000	0.000	1.000	
	Scale	1.000	1.000		
	Mirroring				
Set WO	Rotation (in °)	0.000	1.000	1.000	
	Scale	1.000			
	Mirroring				
Tool offset	R variable	Setting data	Work offset	User data	

#### Select work offsets:

- The display switches to the defined work offsets of the next axis.
- The display switches to the defined work offsets of the previous axis.

You can use these softkeys to change the display mode of the currently displayed work offsets.

For example:

- either the absolute offsets (coarse and fine) with reference to the coordinate axes
- or the individual values split into the components rotation, scaling and mirroring.

You can select and, if necessary, change the individual values of the work offsets in both display modes.

Basic  
WO

**Display other work offsets:**

All defined basic work offsets (global and channel-specific) are displayed in a table.

Settable  
work offsets

All defined settable work offsets are displayed in a table where they can be edited if necessary (select and edit).

**5.8.3 Changing the settable work/zero offset (G54 ...)****Function**

\$P\_UIFR[]

This identifier can be used to change a settable zero offset in the program.

**Coarse offset**

The value of the coarse offset is defined for the relevant axis.

**Fine offset**

The data limits (absolute) are set for the fine work offset via the machine data. The fine offset is displayed in the "Settable work offset" screen.

The work offset is activated via MD.



**Machine manufacturer**

The basic work offset is activated by MD.

Please follow the machine tool manufacturer's instructions!

**Rotation**

The value of the rotation around the respective geometry axis (e.g. X, Y, Z) can be entered.

Rotation can only be programmed around geometry axes.

**Scale**

The scale factor can be defined for the respective axis.

**Mirroring**

Mirroring of the relevant axis around the coordinate zero can be activated and deactivated.

**Operating sequence**

Work  
offset

Select softkey "Work offset".

The vertical softkey bar changes.

Settable  
work offsets

The "Settable work offsets" window opens.

Parameter	CHAN1	AUTO	MPF.DIR	CHIRON.MPF	
Channel RESET					Axis +
Program aborted			ROV		Axis -
Settable work offset					
	Axis		X	Y	Z
G54	coarse		0.000	0.000	0.000
	fine		0.000	0.000	0.000
G55	coarse		0.000	0.000	0.000
	fine		0.000	0.000	0.000
G56	coarse		0.000	0.000	0.000
	fine		0.000	0.000	0.000
G57	coarse		0.000	0.000	0.000
	fine		0.000	0.000	0.000
Tool offset	R variable	Setting data	Work offset	User data	

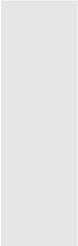


You can choose a work offset selectively from the overview of work offsets. Select the appropriate fields with the cursor and overwrite the fields you want to change with the new value.

Select a new value via the "Select" key (with mirroring).

The work offsets are saved, i.e. transferred to the NC.

#### 5.8.4 Activate work/zero offset and basic frame immediately



Machine manufacturer



References

#### Function

The machine data can be set to specify that the work offset and basic frame can be activated immediately if the part program switches to the "Reset" state. This also occurs if the part program was first switched to JOG status.

If the channel is in the "Reset" state, active work offset and basic frame are not activated until the part program is continued.

#### Further information

When the function is used in the Reset state, the machine data must be set such that the settable work offset or basic frame is not reset when the program switches to Reset.

Please follow the machine tool manufacturer's instructions!

/FB/ K2: Axis Types, Coordinate Systems, Frames

**Danger**

The offset is applied the next time the parts program is started.

**5.8.5 Global work/zero offset/frame (Basic WO)****Function**

In addition to the settable, the programmable and the external work offsets, it is possible to define up to 16 **global** work offsets/frames (basic WO). This allows offsets, scales and mirrors to be defined simultaneously for all channel and machine axes.

The global work offsets (NCU-global frames) apply uniformly to all channels. They can be read and written from all channels. The activation is performed in the relevant channel.

**Basic WO  
(total basic frame)**

In addition, 16 channel-specific basic work offsets can be defined in each channel. The global and channel-specific frames are combined to produce a total basic frame (basic WO).

**Machine manufacturer****Recommendation:**

Use the 3rd basic offset onwards for your own applications. The 1st and 2nd basic offsets are reserved for setting the actual value and the external work offset.



With global frames there is no geometrical relationship between the axes. It is therefore not possible to perform rotations or program geometry axis identifiers.

In SW 5 and higher, the settable work offset and the basic work offset are represented in **one** table. You can edit the values in this table. You can switch between the values of the individual axes.

For **all** work offsets, you can display either the defined offsets (coarse and fine) or the specified rotations, scales and mirrors for each value.

**References**

/FB/ K2: Axis Types, Coordinate Systems, Frames



Work offset

Basic WO

### Operating sequence

Select softkey "Work offset".  
The vertical softkey bar changes.

All defined basic work offsets (global and channel-specific) are displayed in a table.

The display mode can be changed by softkey (see above).

You can edit the values directly in the table.

Rotations are not possible with global frames, since no geometrical relationship exists between the axes in this case.

### Further information

The work offset must be changed only when the NC program is stopped. Changes are updated immediately. The work offset values in the display are updated cyclically.



## 5.9 User data/user variables (GUD, PUD, LUD)

### 5.9.1 General



#### Function

User data (UD) can be defined by means of a variety of variables:

- GUD – global variables which are valid in all programs.
- LUD – local variables which are valid only in the program or subroutine in which they have been defined.
- PUD-Program-global user data.

The display of global user data (GUD) can be locked by means of the keyswitch or a password.



### 5.9.2 Changing/finding user data/user variables



#### Operating sequence

Press softkey "User data".

The "Global user data" window is displayed.

The vertical softkey bar changes.

You can toggle between windows

- "Global user data" (GUD)
- "Channel specific user data" and
- "Program user data" or "Local user data"

Program-global variables (PUD) and local variables (LUD) are displayed.

You can scroll up and down in the list using the "Page" keys.

Global  
user data

Channel-  
spec. u. d.

Program  
user data

Local  
user data



or



#### Changing user data

Position the cursor on the user data that you wish to edit and enter a new value or

Select a new value using the "Select" key.

New values are automatically accepted.

GUD +

GUD -

GUD:

Find

Find next



### Searching for user data

Press softkeys "GUD +" and "GUD - " to scroll through user data from GUD 1 to GUD 9.

The "Select global user data" window is opened. The following values are permissible:

- 1 = SGUD (Siemens)
- 2 = MGUD (Machine manufacturer)
- 3 = UGUD (Machine user data)
- 4 ... 9 = GD4 ... GD9 (other, e.g. grinding cycles, etc.)

The selected data are displayed in the "Global user data" window.

Select "Find" softkey.

Dialog window "Find user data" appears on the screen.

The data name or a character string within the name can be entered as the search target. The cursor must be positioned on the user data to be found.

The next user data with the initial identifier searched for is displayed.

User data of types `AXIS` and `FRAME` are not displayed.

Only those local user data that still exist in the execution chain of the control are displayed.

The list of local user data for the display is updated on every "Cycle Stop", but the values are updated continuously.

Before global user data definitions can be made operative in the control, it may be necessary to set machine data.

### Further information

How to define and activate user data is described in Chapter 6: Program operating Area.

**5.9 User data/user variables (GUD, PUD, LUD)**

## Program Operating Area

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## 6.1 Program types

### 6.1.1 Part program



A part program consists of a sequence of instructions to the NC control. In its entirety, this sequence affects the production of a specific workpiece or a particular machining process on a given blank.

### 6.1.2 Subprogram



A subprogram is a sequence of instructions in a part program which can be called repeatedly with different defining parameters. Cycles are a form of subprogram.

### 6.1.3 Workpiece



- A workpiece is a part to be produced/machined by the machine tool.
- In the HMI, a workpiece is a directory in which programs and other data for machining a particular workpiece are stored.

### 6.1.4 Cycles



Cycles are subprograms for the execution of a recurring machining process on the workpiece.

## 6.2 Storing of programs



Programs are saved in the NC memory. The size of this memory is dependent on settings made during start-up. (See Chapter 6 "Memory info")

### 6.3 Program basic display

The Program basic display contains a complete overview of all workpiece and program directories.

Program		CHAN1	Jog				
<input checked="" type="checkbox"/>	Channel reset				New		
	Program aborted				Copy		
<b>Workpiece overview</b>							
Name	Type	Length	Date	Enable			
G_CODE_EN	WPD		04.08.04	X	Insert		
G_CODE_GR	WPD		04.08.04	X	Delete		
LOAD 1	WPD		04.08.04	X	Rename		
LOAD 2	MPF	183	04.08.04		Change enable		
LOAD 3	MPF	183	04.08.04	X	Workpiece selection		
Workpieces	Dir	0	04.08.04		Back		
Press INPUT key to edit program! Free memory: 2.059 MByte							
Work-pieces	Parts programs	Sub-routines	Standard cycles	User cycles	Manufact. cycles	OEM softkey	Memory info



Additional softkeys are available via the Expand key:

Program		CHAN1	Jog		MPF.DIR CHIRON.MPF	
<input checked="" type="checkbox"/>	Chanal reset					New
	Program aborted					Copy
<b>System files</b>						
Name	Type	Length	Date	Enabel		
Press the INPUT key to edit program! Free Memory: 0 Byte						
System files	Definition files	Operating data				Clipboard

Work-pieces

Parts programs

#### Horizontal softkeys

This key displays an overview of all the workpieces you have created with their part programs.

An overview of all part programs (main programs) stored in the selected directory is displayed.

Sub-routines

(子程序)

An overview of all subprograms stored in the selected directory is displayed.

Subprograms are processed in the same way as described for "Process main programs".

Disk  
Compact Flash Card

Network drive

These four softkeys (logical drive 1–3 and the OEM softkey) appear only if the "network and disk drive management" option has been enabled, e.g. as "Disk", "Network drive", "Compact Flash Card" (see Chap. 9) or

OEM softkey

e.g. OEM softkey (expand operator interface)

Standard cycles

The standard cycles appear on the screen when you press the softkey "Standard cycles".

Manufact. cycles

Select softkey "Manufacturer cycles" to display a list of the cycles that have been integrated by the manufacturer.

User cycles

Select softkey "User cycles" to display a list of the user cycles that you have added.

Memory info

The total available/used memory is displayed.



You can access the following softkeys by pressing the ETC key:

System files

"System files" (e.g. OSTORE1\_SYF),

Definition files

"Definition files" (e.g. GUD4\_DEF),

Operating data

"Operating files" (e.g. BD\_TEA).

Clipboard

By pressing the softkey "Clipboard" you can display a list of the programs/data stored in the clipboard.

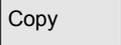


### Machine manufacturer

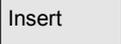
These softkeys can be disabled in display machine data. Please note information supplied by machine tool manufacturer!


**Vertical softkeys**

Creates a new file for a workpiece/part program.



The current file name including the directory is marked and copied to the clipboard. If you delete the copied file from the clipboard, you will not be able to paste it again.



Pastes a file copied to the clipboard into the current directory; the file name must be altered and confirmed beforehand.



Deletes a file (workpiece/part program).



Overwrites the file name/type of a workpiece/part program.

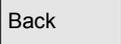


Sets/resets the enable for a workpiece/part program.

The enable must be set (X) for a workpiece/part program to be selected.




Selects a workpiece/part program for execution in the currently active channel.



When you branch to a workpiece, the "Back" softkey is displayed to allow you to return to the workpiece overview.

## 6.4 Edit programs

### 6.4.1 Text editor



The ASCII editor provides you with the following functions:

- Switch between insert and overwrite mode.
- Mark, copy, delete block.
- Paste block.
- Position cursor/find/replace text.
- Create contour (programming support).
- Configure cycle parameters (drilling, milling, turning).
- Start simulation.
- Recompile (cycles, free contour programming).
- Renumber blocks.
- Change settings.

For a detailed description, please refer to:  
Chapter 2, "General operating sequences".

## 6.4.2 Selective program protection: RO



### Function

In programs written with program templates or when using the programming support functions, certain machine-specific code lines may be protected against changes.

A read-only identifier (";\*RO\*") is tagged onto the code blocks as a comment. The ASCII editor recognizes these blocks, hides them or displays them in the read-only text color (gray), and prevents changes to these blocks.

```

Program editor: \MPF.DIR\TEST_PROGRAMM.MPF 1
; Test program
; 141197
G90 G94 G60 G17 G500
M100 G01 X50 F200
M120 X100 ;*RO*
M130 X90 ;*RO*
M140 X70 ;*RO*
M150 X40 ;*RO*
M200 X120
M210 X150
Y100
Y120
G00 Z300
G01 X200
Y150
G00 Z200
  
```

The read-only identifier (";\*RO\*") shows you which part of the program is protected.

Any attempt to change a program part protected by the read-only identifier is denied with the message "Block cannot be written."

### Further information

When creating a program template, please make sure that the read-only identifier appears immediately at the end of the block.

### 6.4.3 Hidden program lines: Display HD



Settings



**Machine manufacturer**

#### Function

To display hidden, write-protected text (with the identifier;\*HD) in the editor, press the Etc key and the "Settings" softkey.

This function must be set up by the machine manufacturer. Please note the information supplied by the machine tool manufacturer!

### 6.4.4 Reserved character string



#### Function

Reserved character strings occur in part program code lines that arise by calling cycles and contour programming. They become visible when activated if the "Display hidden lines" setting is active in the editor.

The following character strings must not be used in part program lines that are input directly:

```

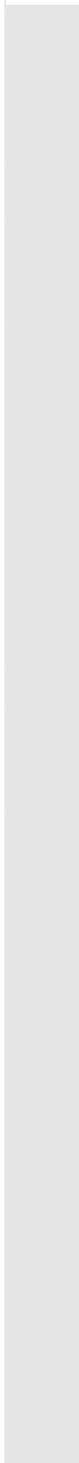
;#
;#END
;NCG
;*RO*
;*HD*

```

#### Further information

See Section:    Selective Program Protection RO  
                   Hidden program lines: display HD

### 6.4.5 Defining and activating user data (GUD, LUD)



Definition files

New

Copy

Delete

Rename

Change enable

Activate

No

Yes

Yes

No

#### Function

#### Defining user data (GUD)

By editing a DEF/MAC file, you can alter or delete existing definition macro files or add new ones.

In the "Program" operating area, select the "ETC key" and then "Definition files"; an overview of the files appears.

You can alter the definitions by selecting the "New," "Copy" and "Delete" softkeys. These alterations are stored in the current file.

You can create a new definition file, e.g. from a backup file (SGUD.BAK), by selecting the "Rename" softkey and changing the extension.

#### Activating user data (GUD)

To activate an edited definition file, select the "Change enable" softkey.

Activate definition file:

Position the cursor on the definition file and press the "Activate" softkey.

The following message appears in the dialog line:

"Do you want to activate the definitions in this file?"

"No" The modified data remains in the file. The changes are not saved.

"Yes" The modified data is activated. Another question is displayed: "Should the previous definition data be retained?"

"Yes" The screen form is closed, the definitions are activated and the previous definition data is retained.

"No" The screen form is closed, the definitions are activated and assigned to the file with the predefined values.

**Error messages:**

The following error messages appear in the dialog line:  
"Error occurred during activation of file"

**Output of NC alarms:**

Once the maximum number of files on the NC has been reached, no more backup files can be created. The following acknowledgeable NC alarms appear: "Too many part programs in the NC memory"  
"NC memory full"

The same applies when activating macro files (.MAC).

**6.4.6 Defining and activating user data (GUD, LUD) via RS-232 C****Function****1. Save `_N_INITIAL_INI` block via RS-232 C.**

Create a definition file for user data in the Program operating area:

- Predefined file names are used:

`_N_GUD1_DEF` (global Siemens data),

`_N_GUD2_DEF` (global machine manufacturer data),

`_N_GUD3_DEF` (global user data),

`_N_GUD4_DEF` to `_N_GUD9_DEF` (additional global data,  
e.g. grinding cycles, etc.)

- Files with these names can contain definitions of GUD variables.  
The same rules apply to these as to LUD variable definitions.

**2. Load definition file to main memory via RS-232 C.**

The control system always creates a directory named

`_N_DEF_DIR`. This name is entered in the header of the GUD  
definition file as a path:

**Example:**

```
_N_GUD1_DEF
$PATH=/_N_DEF_DIR
DEF NCK REAL NCKVAR
DEF CHAN INT CHANVAR
M17
```

- 3. Load "Init files":** User definition files are active.



## References

### 4. Data backup

The modified GUD data contents are saved when block `_N_INITIAL_INI` is read out via "Data out" in the Services operating area. These data can only be reloaded into the control if it has first been ensured that the required definition files are in the control.

Definition and creation of user data

Data is only saved for variable definition files, not for macros.

/PGA/Programming Guide, Advanced

## 6.5 Free contour programming

### 6.5.1 General



#### Function

The free contour programming is a support tool for the editor.

The contour programming function enables you to create simple or complex contours.

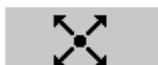
An integrated contour calculator calculates any missing parameters for you, provided that they can be computed from other parameters.

A contour comprises separate contour elements, whereby at least two and up to 250 elements result in a defined contour. You can also program undercut, radii, chamfer or tangential transitions between the contour elements.

The programmed contours are transferred to the edited part program.

The following contour elements are available for the definition of a contour:

- Vertical line
- Straight line (planar, longitudinal, inclined) horizontal
- Diagonal line
- Arc/circle



#### Further information

1. The valid geometry axes in the first channel are determined and used in the part program.
2. The contour elements of the contour chain are displayed by symbols or text. The mode of representation can be set via the "Setting contour" function in the editor.

Setting  
contour

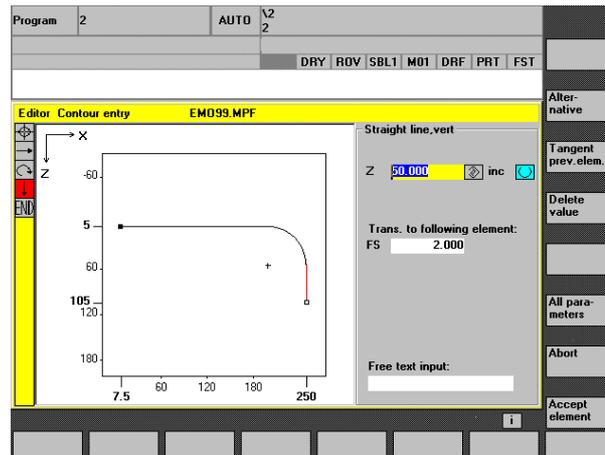
## 6.5.2 Graphic representation of the contour



### Function

The graphics window displays the progress of the contour chain as you parameterize the contour elements.

The currently selected element is displayed in orange in the graphics window.



The created contour element can be displayed in various line types and colors depending on its status:

HMI Embedded	Meaning
Black	Programmed contour
Orange	Current contour element
Yellow	Alternative element
Black continuous line	Defined element
Dotted line	Partially defined element
Dashed line	Alternative element

The current status of the contour is displayed insofar as it can be interpreted by the control on the basis of parameter inputs. If the contour is still not displayed in the programming graphic, further values still need to be entered. Check the contour elements you have already programmed. You may have forgotten to enter all the data you know.

The coordinate system scaling is automatically adapted to changes in the complete contour.

The position of the coordinate system is displayed in the graphics window.



### 6.5.3 Create contour



#### Function

For each contour that you want to cut, you must create a new contour. The first step in creating a contour is to specify a starting point.

You have the option of beginning the contour with a transition element to the blank. You can also enter any additional commands (up to 40 characters) in G code format for the start point.

If you want to create a contour that is similar to an existing contour, you can copy the existing one, rename it and just alter selected contour elements. However, if you want to use an identical contour at another place in the program, you must not rename the copy.

Changes to the one contour will then automatically be applied to the other contour with the same name.



#### Sequence

To select an existing program via the "Workpiece" and "Part program" softkeys or create a new part program with the "New" softkey.

Enter a name and confirm with "OK".

You are now back in the ASCII editor.

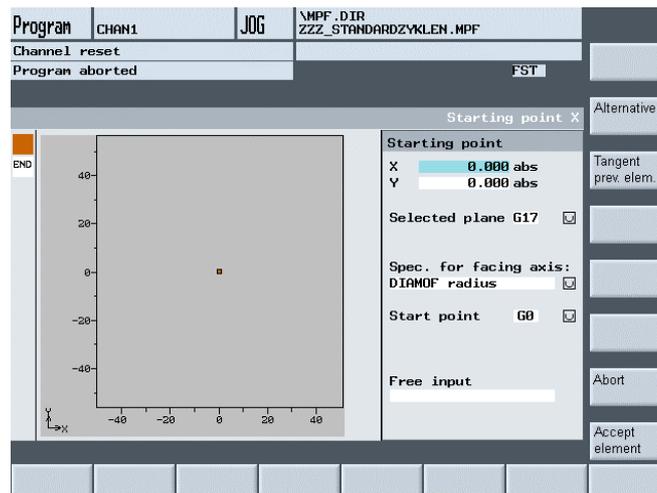
You can access the following softkeys by pressing the ETC key:



Open the contour editor by pressing the "Support" and "New contour" softkeys.

#### Define the start point

The input form for the start point of the contour appears.



When entering a contour, begin at a position which you know and enter it as the starting point. You can enter Cartesian or polar coordinates.

To define the geometry axes, choose from the planes G17, G18 and G19 with the Select Key in the field behind "Plane selection". The coordinate system changes accordingly.

The default tool axis (defined in the machine data) can be changed for machines with more than two axes. The associated start point axes are automatically adjusted.

Position the cursor on the "Facing axis dimension" field and click on the field using softkey "Alternative" (or with the "Selection" key) repeatedly until the dimension you require is displayed.

The approach motion to the starting point can now be changed from G0 (rapid traverse) to G1 (linear interpolation) via the new field "Approach starting point".

You can define a specific feed rate for G1 via the "Free text input" field,

e.g. G95 F0,3.

Select softkey "Accept element" to store the starting point.

With the "Abort" softkey, your settings are discarded and you arrive at the previous screen form.

Select the machining plane.

Enter the starting point for the contour.

Enter any additional commands in G code format, as required.

Press the "Accept element" softkey.

Enter the individual contour elements (see Section "Create contour elements").

Alter-  
native

Accept  
element

Abort

### Cartesian start point

Accept  
element

**Polar start point**

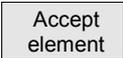
 Pole

Select the machining plane.

Press the "Pole" softkey.

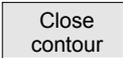
Enter the starting point for the contour in polar coordinates.

Enter any additional commands in G code format, as required.


 Accept  
element

Press the "Accept element" softkey.

Enter the individual contour elements (see Section "Create contour elements").

**Close the contour**

 Close  
contour

A contour always has to be closed.

If you do not wish to create all contour elements from starting point to starting point, you can close the contour from the current position to the starting point.

Press the "Close contour" softkey.

A line from the current point to the start point is created.

**Recompile contour**

 Recompile

You can edit an existing contour by selecting the softkey "Recompile". The editor cursor must be positioned inside the contour first.

**Notice**

During recompiling, only the contour elements that have been created with free contour programming are created again. In addition, only the texts that were added via the input field "free text input" are recompiled. Any changes you made directly in the program text are lost. However, you can still insert and edit free texts afterwards, which will not be lost.

**Further information**

The NC code generated by the contour programming in the part program must never be altered manually. Otherwise recompilation is no longer possible.

Exception: Insertion of block numbers and masking blocks.

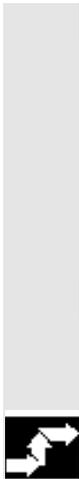
**Saving a contour element**

 Accept

If all contour elements and transition elements have been generated, save the contour by pressing the "Accept" softkey



### 6.5.4 Changing a contour



#### Alter a contour element



Accept  
element

You can change a previously created contour later.

Individual contour elements can be

- appended
- changed
- deleted

If your program contains two contours of the same name, changes to the one contour are automatically applied to the second contour with the same name.

#### Sequence

Select the contour.

Press the "Cursor Right" key.

Position the cursor on the contour element that you want to modify.

Press "INPUT" key

The associated input form is opened and an enlarged view of the selected element appears in the programming graphic.

After inputting the changes, press the "Accept element" softkey.

## 6.5.5 Contour elements general



## Contour chain

## Function

The elements of the contour are displayed symbolically in the sequence in which they were programmed in a contour chain next to the graphic window.

## Symbolic representation

Contour element	Abbreviation	Symbol	Meaning
Start point	SP		Start point of contour
Straight line to the left	SL		Straight lines in 90° grid
Right	SR		Straight lines in 90° grid
Left/right	SLR		Straight lines in 90° grid
Top	SU		Straight lines in 90° grid
Bottom	SD		Straight lines in 90° grid
Above/below	SUD		Straight lines in 90° grid
Straight line in any direction	SA		Straight line with any pitch
Arc to the left	CL		Circle
Right	CR		Circle
Contour termination	END	END	End of contour

## Color of symbols

The different color of the symbols indicates their status:

Foreground	Background	Meaning
-	Black	Cursor on new element
White	Black	Cursor on current element
Black	White	Normal (undefined) element
White	Black	Element currently detached (residual model)

### 6.5.6 Create, change, delete contour elements



When you have created a new contour and specified the start point, you can define the individual elements that the contour comprises.

If you leave any parameter input fields blank, the control assumes that you do not know the right values and attempts to calculate them from the settings of other parameters.

The contour is always machined in the programmed direction.

As soon as you have entered an element, the input focus is moved to the contour chain on the left of the graphic display. The input focus has a yellow border. You can navigate within the contour chain using the cursor keys.



You can select an existing contour element with "INPUT". A new contour element is inserted after the cursor when you select one of the contour elements on the horizontal softkey menu; the input focus is then switched to the parameter input on the right of the graphic display. You can navigate around the contour chain again after selecting "Accept element" or "Abort". The following contour elements (example for turning: G18) are available for the definition of contours.



#### Entering a contour element



Select a contour element via softkey.

Enter all the data available from the workpiece drawing in the input form (e.g. length of straight line, target position, transition to next element, angle of lead, etc.).

Press the "Accept element" softkey to accept all values.



The contour element is added to the contour. Repeat the procedure until the contour is complete.

#### Append a contour element

Select the contour.

The individual contour elements are listed. Use the cursor keys to select the element in front of the end marker.



Select the required contour element via softkey.



Press the "Accept element" softkey.

The required contour element is appended to the contour.

#### Insert contour element

Use the cursor keys to select the contour element **behind** which you wish to insert another element.

### Selecting a contour element



Position the cursor on the desired contour element in the contour chain, and select it with the "Input" key.

The parameters for the selected element will then be displayed. The name of the element appears at the top of the parameterization window.

Once the contour element can be displayed geometrically, it is highlighted accordingly in the graphic display area, i.e. its color changes from black to orange.



### Displaying additional parameters



If your drawing contains further data (dimensions) for a contour element, select softkey "All parameters" to extend the range of input options for the element.

The softkey "Alternative" is displayed only in cases where the cursor is positioned on an input field with several selectable settings.

### Define pole



If you wish to enter the contour elements Diagonal line and Circle/arc in polar coordinates, you must first define a pole.

Press the "Continue" and "Pole" softkeys.

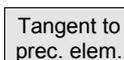
Enter the coordinates of the pole.



Press the "Accept element" softkey.

The pole is defined. You can now choose between "Cartesian" and "Polar" in the input screen form for the Diagonal line and Circle/Arc contour elements.

### Tangent to preceding element

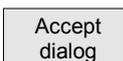
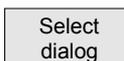
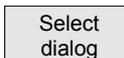


When entering data for a contour element you can program the transition to the preceding element as a tangent.

Press the "Tangent to prec. elem." softkey.

The angle to the preceding element  $\alpha_2$  is set to  $0^\circ$ . The "tangential" selection appears in the parameter input field.

### Make a dialog selection



Some constellations of parameters can produce several different contour characteristics. In such cases, you will be asked to select a dialog. When you select the "Select dialog" softkey, the existing selection options are listed in the graphic display area.

Select the appropriate dialog (black continuous line) with "Select dialog" softkey and confirm by selecting "Accept dialog" softkey.

**Changing a selected dialog** If you want to change an existing dialog selection, you must select the contour element in which the dialog was originally chosen. Both alternatives are displayed again when you select softkey "Change selection".

Change selection

Select dialog

Accept dialog

You can select another dialog.

If the selection has become unnecessary as a result of other input values, you will no longer be requested to select a dialog!

**Transition element at contour end**

A transition element can be used whenever there is a point of intersection between two neighboring elements which can be calculated from the input values.

You can choose among Radius **R**, a chamfer **FS**, and an **undercut** (thread, thread DIN, Form E, or Form F) as a transition element between any two contour elements. The transition is always appended to the end of a contour element. You select transition elements in the parameter input screen form for the relevant contour element.



Place the cursor on the last contour element.

Press the "Cursor Right" key.

The associated input screen form opens.

Enter a transition element.

Accept element

Abort

Press the "Accept element" softkey.

When you select "Abort", the contour element values are discarded and you return to the basic display. The input focus switches back to the contour chain.

Delete value

The values of the parameter are deleted.

**Delete a contour element**

Select the contour.



Press the "Cursor Right" key.

The individual contour elements are listed.

Delete element

OK

Place the cursor on the contour element to be deleted.

Press the "Delete element" softkey and confirm with "OK".

The contour element is deleted.

Accept

To save the contour, press the "Accept" softkey.

**Saving a contour element**

If you have entered the available data for a contour element or selected the desired contour by means of softkey "Select dialog", select softkey "Accept element" to store the contour element and return to the basic display.

Accept element

You can then program the next contour element.



### Further information

The NC code generated by the contour programming in the part program must never be altered manually. Otherwise recompilation is no longer possible.

Exception: Insertion of block numbers and masking blocks.

### Parameters on gray background

These parameters have been calculated by the control system. You cannot alter them.

When the programmed parameter input fields (white background) are altered, the control calculates new data, which are then immediately displayed again in the input screen form.

### Input value is already calculated

With some contours, the control system may already have calculated an input value from other settings.

Problems may then arise if the control-calculated value does not tally with the workshop drawing. In this case, you must delete the settings from which the control has automatically calculated the input value.

You can then enter the setting exactly from the workshop drawing.

Settings

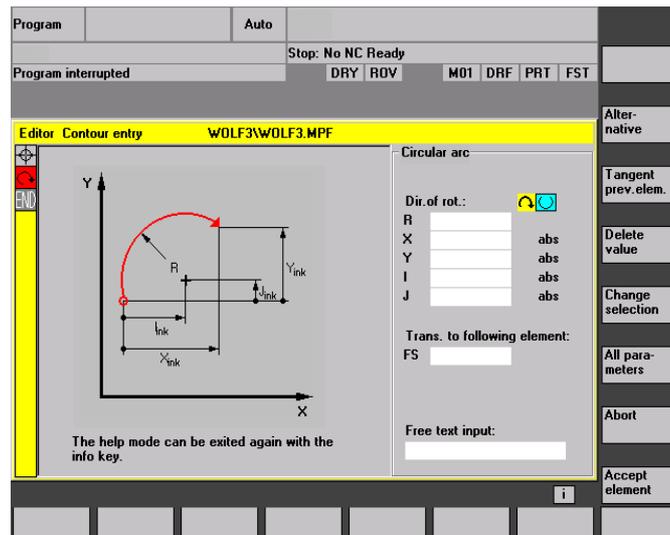
The technology (turning/milling) and the position of the coordinate system are read from the appropriate machine data. You can see the selected configuration with "Settings".

### 6.5.7 Help



When you enter parameters you can call up a help screen with the Info key which graphically represents the parameters you are entering. The help screen that appears depends on the cursor position in the parameter display.

The help screen is displayed on top of the parameter screen.



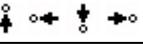
If you press the Info key again the help screen is closed and the display graphic is activated again. The help screens displayed correspond to the selected coordinate system. The axis names are derived from the current geometry axis names.

Help screens are displayed for the following entries:

- Start point
- Vertical line
- Straight vertical line, angle entry field
- Horizontal line
- Straight horizontal line, angle entry field
- Straight line in any direction
- Straight line any, angle entry field
- Circle
- Circle, angle entry field
- Radius/chamfer

## 6.5 Free contour programming

## 6.5.8 Parameter description of the contour elements line/circle and pole

Parameters	Contour element "Straight line"	Unit
X absolute	Absolute end position in X direction	mm
X incremental	Incremental end position in X direction	mm
Y absolute	Absolute end position in Y direction	
Y incremental	Incremental end position in Y direction	
L	Length of line	mm
$\alpha 1$	Pitch angle referred to X axis	Degr.
$\alpha 2$	Angle to preceding element; tangential transition: $\alpha 2=0$	Degr.
FB	Feedrate for contour element "Straight line"	mm/rev
Transition at contour start	FS: Chamfer as transition element at contour start R: Radius as transition element at contour start FS=0 or R=0: No transition element	mm mm
	Location of transition element relative to contour start point 	
Undercut size	Undercut size acc. to DIN table (for forms E and F only): Radius/depth, e.g.: E1.0x0.4 (undercut form E) or F0.6x0.3 (undercut form F)	
FRC	Feedrate for transition element chamfer or radius	mm/rev
CA	Allowance for subsequent grinding	mm
	Grinding allowance to right of contour (viewed from starting point)	
	Grinding allowance to left of contour (viewed from starting point)	
Additional command	Any additional command in G code format	

Parameters	Contour element "Circle"	Unit
Direction of rotation	 Clockwise rotation	
	 Counterclockwise rotation	
X absolute	Absolute end position in X direction	mm
X incremental	Incremental end position in X direction	mm
Y absolute	Absolute end position in Y direction	
Y incremental	Incremental end position in Y direction	
Z	Target position in the Z direction (abs. or inc.) Incremental dimensions: The plus/minus sign is evaluated.	mm
$\alpha 1$	Starting angle referred to X axis	Degr.
$\alpha 2$	Angle to preceding element; tangential transition: $\alpha 2=0$	Degr.
$\beta 1$	End angle referred to X axis	Degr.
$\beta 2$	Angle of aperture of circle	Degr.
FB	Feedrate for circle contour element	mm/rev
R	Radius of circle	mm
I	Position of arc center point in X direction (abs. or incr.)	mm
K	Position of circle center point in Z direction (abs. or inc.) Incremental dimensions: The plus/minus sign is evaluated.	mm

J	Position of arc center point in Y direction (abs. or incr.)	mm
Transition to following element	Transition element to next contour is a chamfer (FS)	mm
	Transition element to next contour is a radius (R) FS=0 or R=0 means no transition element	mm
FRC	Feedrate for transition element chamfer or radius	mm/rev
CA	Allowance for subsequent grinding	mm
	Grinding allowance to right of contour (viewed from starting point)	
	Grinding allowance to left of contour (viewed from starting point)	
Additional command	Any additional command in G code format	



### Machine manufacturer

The names of the identifiers (X or Y ...) are defined in the machine data where they can also be changed.

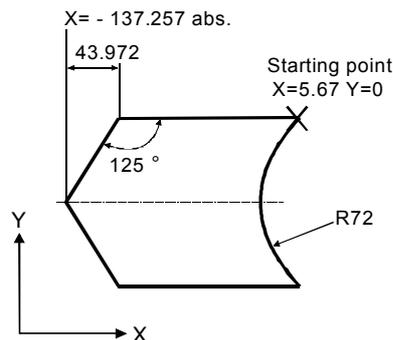
## 6.5.9 Programming example of free contour programming



### Example 1

Starting point: X=5.67 abs., Y=0 abs., machining plane G17  
The contour is programmed in a counter-clockwise direction.

Workpiece drawing of contour



Element	Softkey	Parameters	Remarks
1		All parameters, $\alpha 1=180$ degrees	Observe angles in help screen!
2		X=-43.972 inc, all parameters X=-137.257 abs $\alpha 1=-125$ degrees	Definition of coordinates in X in "abs" and in "inc" Observe angles in help screen!
3		X=43.972 inc $\alpha 1=-55$ degrees	Definition of coordinates in X in "inc" Observe angles in help screen!
4		X=5.67 abs	
5		CW direction of rotation, R=72, X=5.67 abs., Y=0 abs., Make a dialog selection	

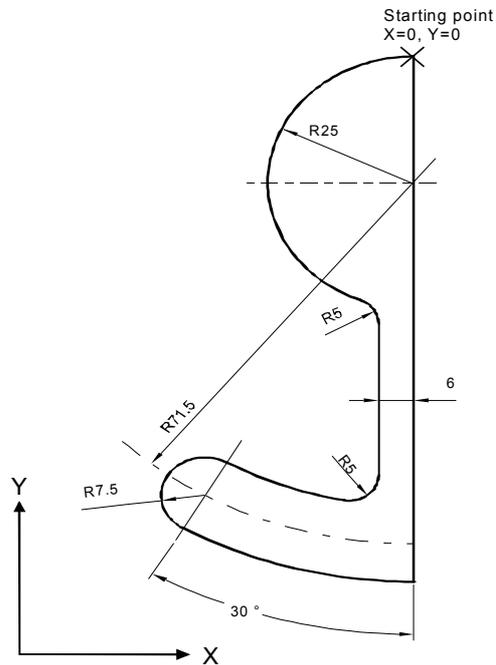


### Example 2

Starting point: X=0 abs., Y=0 abs., machining plane G17

The contour is programmed in the clockwise direction with dialog selection. For this contour it is advisable to display all parameters via the softkey "All parameters".

Workpiece drawing of contour



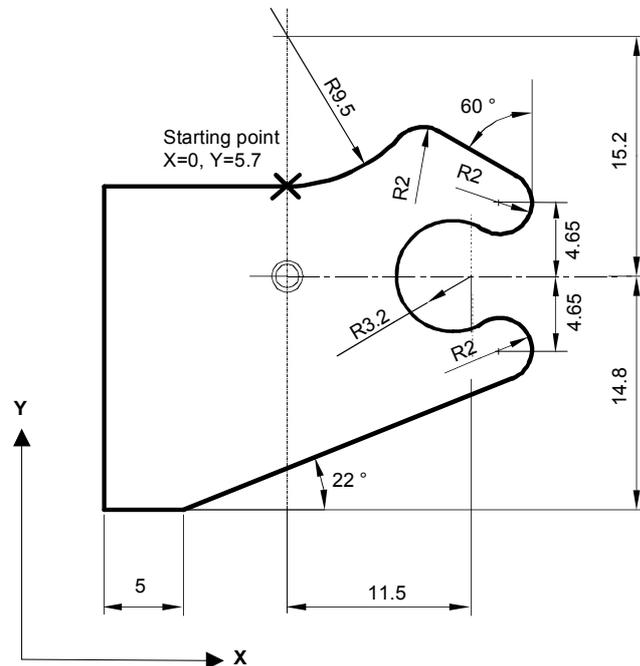
Element	Softkey	Parameters	Remarks
1		Y=-104 abs.	
2		Direction of rotation right, R=79, I=0 abs., Select dialog, all parameters, $\beta_2=30$ degrees	
3		CW direction of rotation, tangent to preced. R=7.5, all parameters, $\beta_2=180$ degrees	
4		CCW direction of rotation, R = 64, X =-6 abs., I=0 abs., Make dialog selection, make dialog selection Transition to following element: R=5	
5		All parameters, $\alpha_1=90$ degrees, Transition to following element: R=5	Observe angles in help screen!
6		Direction of rotation right, R=25, X=0 abs., Y=0 abs. I=0 abs Make dialog selection, make dialog selection.	



### Example 3

Starting point: X=0 abs., Y=5.7 abs., machining plane G17  
The contour is programmed in a clockwise direction.

Workpiece drawing of contour



Element	Softkey	Parameters	Remarks
1		Direction of rotation left, R=9.5, I=0 abs., make dialog selection, Transition to following element: R=2	
2		$\alpha 1 = -30$ degrees	Observe angles in help screen!
3		CW direction of rotation, tangent to preced. R=2, J=4.65 abs.	
4		CCW direction of rotation, tangent to preced. R=3.2, I=11.5 abs., J=0 abs., make dialog selection, make dialog selection	
5		CW direction of rotation, tangent to preced. R=2, J=-4.65 abs., select dialog	
6		Tangent to previous element $\alpha 1 = -158$ degrees, Y=-14.8 abs., $\alpha 2 = 0$ degrees	Observe angles in help screen!
7		All parameters, L=5, select dialog	
8		Y=5.7 abs.	
9		X=0 abs.	

## 6.6 Program simulation

### 6.6.1 Turning simulation



#### Function

The "Simulation" function operates in conjunction with turning technology.

With the "Simulation" function you can

- represent axis motions in graphic displays and
- trace the machining result on the screen as the workpiece is actually machined.

By activating Simulation, you can execute a contour on the screen in graphic form with or without machine axis motions (can be disabled by the PLC).

#### Display elements

The colors in the graphic display area signify the following:

- **Red** = Traversing path in the feed rate
- **Green** = Traversing path in rapid traverse
- **Yellow** = Cross-hair  
Polymarker (cutting edge),  
Workpiece symmetry axis

#### Cross-hair

Using the cross-hair, you can

- select the zoom center point and
- set the measuring points (for viewport).

#### Tool cutting edge

The position of the cutting edge corresponds to the definitions in the "Tool compensation" menu under softkey "Tool".

The tool path in the program block you are currently editing is simulated. The cutting edge is represented by a polymarker. The starting point of the polymarker corresponds to the starting point of the machine tool axes.

#### Coordinate system

The alignment of axes (coordinate system) is defined in machine data.



#### Machine manufacturer

Please see information supplied by machine tool manufacturer.

The display machine data are described in:



#### References

/FB1/K1: Mode Group, Program Operation, Chapter 4



Simulation



Auto-zoom

To origin

Display all

Zoom +

Zoom -

Delete window

Cursor fine

or

Cursor coarse

Close



## Operating sequence

Select a program, open it, and press the "Simulation" softkey.

The graphic simulation function is started when you press the "Cycle Start" key on the machine control panel.

The following softkey functions are provided:

This softkey automatically adjusts the display area to the displayed traversing motions.

You return to the initial display (size of the viewport when you select simulation). The viewport can be defined by the machine manufacturer in the machine data.

Optimizes the window for simulation purposes.

The current contents of the screen are displayed in a larger or smaller resolution when you press softkeys "ZOOM+" or "ZOOM-". Using the cursor keys, you can move the cross-hair to the selected center point of the window display.

The current screen contents are deleted.

You can alter the increments of the cursor key movements with the softkey "Cursor fine".

- Softkey is selected:  
Cursor moves in "fine" increments.
- Softkey is not selected:  
The cursor moves in "coarse" increments.

Softkey "Close" ends the simulation.

Simulation is also aborted when you select a horizontal softkey.

## 6.6.2 Milling simulation before machining



### Simulation graphic

#### Function

In automatic mode you can display your program graphically in the "Program test" function before machining, without traversing the machine axes.

The simulation graphic shows a representation of a workpiece being machined by a cylindrical tool. You can select different views via softkey, e.g.

- Top view
- Representation in three planes
- 3D representation (volume model)

### Status displays

The status displays in the simulation graphic contain information

- about the actual axis coordinates and
- the block currently being processed.



### Option

This function is an option and is only available with a color display. Milling simulation is only possible in the 1st channel.



### Prerequisite

#### Operating sequence

- You select the program in automatic mode "Auto".
- In the Machine operating area under "Program control," the functions "Dry run feedrate" and "Program testing" (the machine is not moved while the program is run) are selected. If the "Dry run feedrate" function is active, the programmed feedrate is replaced by a defined dry run feedrate.
- Tool T0: Tool displayed in the graphics.
- Tool not identical with T0: An associated tool cutting edge must be selected.

Select a program of your choice and open it.

Press the "3D sim" softkey.

The program is started.

You can follow program execution on the screen.

3D sim.



Cycle Start

### 6.6.3 Milling simulation during machining



#### Function

The current machining operation on the machine tool is simulated on the monitor of the control at the same time.



#### Option

This function is an option and is only available with a color display. Milling simulation is only possible in the 1st channel.



#### Prerequisite



#### Operating sequence

See previous section

Press the area switchover key and

the "3D sim." softkey.

The program is started.

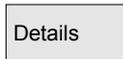
You can follow program execution on the screen.

You can start simulation at any time during the machining operation. Simulation is closed when you exit the graphic.

If you switch to another operating area, the current content of the graphic simulation is deleted.



#### Blank definition via input form



Select softkeys "Details" and "Settings" to open the blank definition window.

You can enter values for corner point 1 (front top left) and corner point 2 (back bottom left) of the blank (cube).

With the softkey "Alternative" you can display/hide the view of the blank. If the view of the blank is disabled, the traversing paths are represented by broken-line graphics.

#### Define a blank via the NC program

As an alternative, you can define a blank in the NC program to be simulated.

Syntax:

```
WRTPR("<String>")
```

The following statements can be used in the "String":

- Rectangle: BLOCK(p1x, p1y, p1z, p2x, p2y, p2z)

The positions correspond to the axis values of corner P1 (front top left) and P2 (back bottom right) of the rectangular blank.

P1x = X value of corner P1

p1y = Y value of corner P1

p1z = Z value of corner P1

p2x = X value of corner P2  
 p2y = Y value of corner P2  
 p2z = Z value of corner P2

- Moving/rotating the graphic  
 FRAME (pv1, pv2, pv3, pd1, pd2, pd3)  
 pv1 = Moving the first axis  
 pv2 = Moving the second axis  
 pv3 = Moving the third axis  
 pd1 = Rotating around the first axis  
 pd2 = Rotating around the second axis  
 pd3 = Rotating around the third axis
- Switching off the graphic: END()
- Restoring the unmachined blank: CLEAN()

### Example

```
...
; DEFINITION of the blank
N100 WRTPR("BLOCK(0,0,0,80,100,-30)")
N110 ...
...
;DELETING the blank
N1000 WRTPR("CLEAN()")
...
```

### References

For additional procedures, please refer to the following documentation:  
 /BAS/ ShopMill Operator's Guide

## 6.7 Manage programs

### 6.7.1 Overview

#### Program management

To allow you to handle data and programs flexibly, you can organize, store and display them according to different criteria.

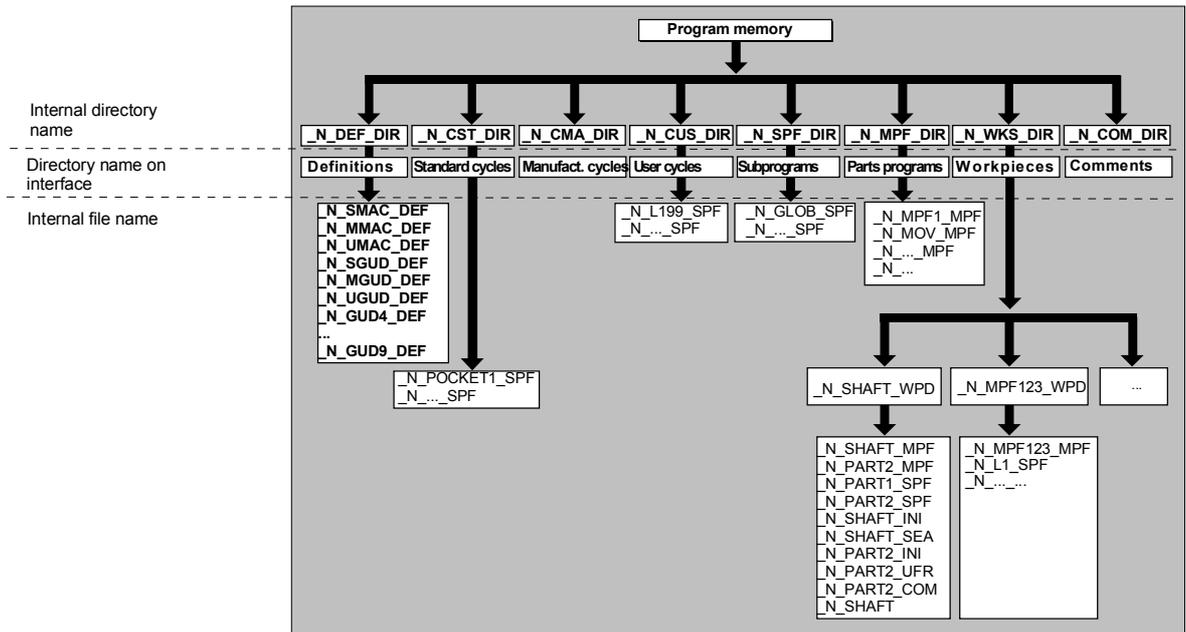
The data/programs are stored in the NC memory by default. These programs are read in and out and executed via the RS-232-C interface.

In addition, further storage devices are available such as network drives, Compact Flash Cards and PCMCIA cards.

Programs and files are stored in different directories:

- Subroutines
- Parts programs
- Workpieces
- Definitions
- Comments
- Standard cycles
- Manufacturer cycles
- User Cycles

The following diagram shows an example of directory contents:



## 6.7.2 File types, blocks and directories

### File types

File types can be identified by the file name extension (e.g. .MPF).

name .MPF	Main program
name .SPF	Subroutine
name .TEA	Machine data
name .SEA	Setting data
name .TOA	Tool offsets
name .UFR	Zero offsets/frames
name .INI	Initialization files
name .COM	Comment
name .DEF	Definition of global user data and macros

### Block

"Block" is the term given to any files required for creating and processing programs.

### Program block

Program blocks contain the main and subprograms of the part programs.

<b>Data block</b>	NC data unit: Data blocks contain data definitions for global user data. These data can be initialized directly when they are defined.
<b>Initialization block</b>	Initialization blocks contain the default settings for data. The initial block is an ".ini" file. It contains values for initializing, for example, machine, user and system data, etc.
<b>Macro block</b>	Macro blocks are used to program one or more instructions with a single new name. Macro definitions are stored in the following files in directory Definitions:
	<pre> _N_SMAC_DEF  Siemens macro definitions _N_MMAC_DEF  Machine manufacturer macro definitions _N_UMAC_DEF  User macro definitions </pre>
<b>Reserved definition names for macros</b>	The following macro definitions can be stored as standard:
	<pre> _N_SMAC_DEF  Macro definitions (Siemens) _N_MMAC_DEF  Macro definitions (machine manufacturer) _N_UMAC_DEF  Macro definitions (user) _N_GUD1_DEF  Definitions for global data (Siemens) _N_GUD2_DEF  Definitions for global data                (machine manufacturer) _N_GUD3_DEF  Definitions for global data (user) </pre>
<b>Directory types</b>	In addition to files, some directories may also have extensions:
	<pre> name.DIR      General directory containing program and data                and blocks, workpiece directories and                other directories with identifier DIR.  name.WPD      Workpiece directories which contain                program and data blocks that belong                to a workpiece. (It must not contain another                directory with the extension DIR or WPD.)  name.CLP      Clipboard directory: Files and directories of                any type may be stored in here. </pre>
<b>Workpiece directory</b>	Workpiece directories (with extension .WPD) are set up in directory WCS.DIR. A workpiece directory contains all files required for machining a workpiece. These can be main programs, subprograms, any initialization programs and comment files.

**Example:**

Creation of a workpiece directory `SHAFT.WPD` that contains the following files:

<code>SHAFT.MPF</code>	Main program
<code>PART2.MPF</code>	Main program
<code>PART1.SPF</code>	Subroutine
<code>PART2.SPF</code>	Subroutine
<code>SHAFT.INI</code>	General initialization program of data for the workpiece
<code>SHAFT.SEA</code>	Setting data initialization program
<code>PART2.INI</code>	General initialization program of data for program part 2
<code>PART2.UFR</code>	Initialization program for frame data for program part 2
<code>SHAFT.COM</code>	Comment file

### 6.7.3 Handling files

#### Assigning values to data

A series of modules/data is permanently installed in the control during start-up.



#### References

The structure and handling of these files is described in the following documentation.

IAM/BE1: Expand the Operator Interface

#### Reading out data

You can save files via interfaces to external devices (programming device, diskette).

When saving files in punched tape/ASCII format, the entire path from which the file was saved is entered in the backup file.

The source path is specified in the second line:

File `SHAFT.MPF` was saved from the workpiece directory (`WCS.DIR`) under workpiece `SHAFT.WPD`.

Example:

```
%_N_SHAFT.MPF
; $PATH=/_N_WKS_DIR/_N_SHAFT_WPD
N10 G0 X... Z...
M2
```

The internal name of the file directories is e.g. `_N_WCS_DIR`.

For a complete backup of all data in a directory, the identifier COMPLETE is used for saving.

The complete backup of all data from all directories (INITIAL over all areas) is saved in the INI file `_N_INITIAL_INI`.

### Import data

When you read in a file, the path entered when you saved the file is used. The system tries to read the file into the directory from which it was saved. If the path is missing, then files with file type `SPF` are stored in `/SPF.DIR`, files with extension `.INI` in the active working memory and all other files in `/MPF.DIR`. Files are immediately effective after import.

### Activating data

Data can be activated/edited by loading files into the working memory. The exact time of activation depends on the type of data activated in the file.

### References

/LIS/ Lists

For example, machine data can take effect (depending on type) either

1. Immediately or
2. on "RESET" or
3. on "Cycle-Start" or
4. on "Power ON" – when the control is switched on again.

### Selecting a workpiece

A workpiece can be selected for machining in a channel. see Section: "Select a Program on the NC for Execution", "Execute Program from Network Drive, Compact Flash Card, Disk".

If a main program of the same name exists in the workpiece directory, it is automatically selected for execution. If you choose workpiece `SHAFT.WPD`, then the main program `SHAFT.MPF` is automatically selected.

If an `.INI` file of the same name exists, it is executed immediately (i.e. it is loaded into the working memory of the NC). Main programs with other names must be selected explicitly.

If a control has several channels, programs can be selected for processing and started from one part program for another channel.

Selection

### Find path for program call

#### Example:

The workpiece directory

/WCS.DIR/SHAFT.WPD

contains files

SHAFT.SPF and SHAFT.MPF.

When you select workpiece directory SHAFT.WPD you implicitly select program SHAFT.MPF.

If the call path is not explicitly specified in the part program when a subroutine (or an initialization file) is called, the called program is located according to the predefined search strategy.

#### Case 1:

When a subprogram is called by

name **with specification of the file type** ("identifier" or "extension"), e.g. SHAFT.MPF,

the system searches through directories in the following order:

- |                                 |                                      |
|---------------------------------|--------------------------------------|
| 1. Current directory / name.typ | Workpiece/standard directory MPF.DIR |
| 2. /SPF.DIR / name.typ          | Global subprograms                   |
| 3. /CUS.DIR / name.typ          | User cycles                          |
| 4. /CMA.DIR / name.typ          | Manufacturer cycles                  |
| 5. /CST.DIR / name.typ          | Standard cycles                      |

#### Case 2:

When a subprogram is called by

name **without specifying the file type** ("identifier" or "extension"), e.g. SHAFT1,

the system searches through directories in the following order:

- |                                 |                                      |
|---------------------------------|--------------------------------------|
| 1. Current directory / name     | Workpiece/standard Directory MPF.DIR |
| 2. Current directory / name.SPF |                                      |
| 3. Current directory / name.MPF |                                      |
| 4. /SPF.DIR / name.SPF          | Subroutines                          |
| 5. /CUS.DIR / name.SPF          | User cycles                          |
| 6. /CMA.DIR / name.SPF          | Manufacturer cycles                  |
| 7. /CST.DIR / name.SPF          | Standard cycles                      |

/PGA/ Programming Guide, Advanced



### 6.7.4 Create new workpiece/part program



#### Selecting a workpiece/part program

The following subsection describes how you can select workpieces and part programs in a directory. A selected file can then be called and edited in the text editor.



#### Operating sequence

##### Select workpiece/part program:

- Workpieces
- Parts programs
- Subroutines

If "Logical drives" is configured, cycle softkeys are displayed after you press the ETC key.

- Standard cycles
- User cycles
- Manufacturer cycles

Workpieces

Parts programs

Sub-routines

Standard cycles

User cycles

Manufact. cycles



Position the cursor in the directory on the desired file.

For each file, the file name, file type, length, date of creation/last change are displayed.

The file display properties can be set.

(See Chapter "Start-Up", "Settings" menu)

##### Call a part program:

Use the cursor to select a program in the program overview and press the "Input" key.

The text editor is displayed with the file you have selected.

You can now edit the part program.

##### Open a workpiece:

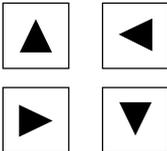
The workpiece directory is opened and the programs it contains displayed on the screen.





Workpieces

New



New

OK

### Create workpiece directory

You can set up various types of files such as main programs, initialization files, tool offsets, etc. in the new workpiece directory.

### Operating sequence

The current overview of all workpiece directories appears on the screen.

Input window "New" is opened.

The cursor is located in the input field for the name of the new workpiece directory.

Enter the name of the new directory on the alphanumeric keyboard. A new directory is set up in the workpiece overview.

### Set up programs/data in a workpiece directory

This section explains how you can set up a new file for a part program or workpiece.

### Operating sequence

The current overview of the workpiece directories stored on the NC appears.

Position the cursor on the required workpiece directory and open it.

An overview of the data and programs that have already been set up in the workpiece directory is displayed. If no data exists, an empty program overview appears.

A dialog box appears when you select softkey "New".

Enter the new file name. Program names may be a maximum of 24 characters in length. You can use any letters, digits or the underscore symbol (\_). The file type is set by default.

Then press the "OK" softkey.

The following file types can be entered:

File type	Meaning
.MPF	Main Program File
.SPF	Sub Program File
.TOA	Tool Offset Active
.INI	Initializing data
.COM	Comment file
.GUD	User data (global)
.TEA	NC-Machine data (Testing Data Active)
.SEA	Addresses with value assignment (Setting Data Active)
.LUD	User data (local)
.UFR	Zero point offset (User Frame)
.EEC	Spindle pitch/ sender error compensation.
.QEC	Quadrant error compensation
.CEC	Sag/angularity compensation

Parts  
programs

or

Sub-  
routines

New

#### Creating part programs in part program/subprogram directory:

You can set up main programs and subprograms by opening directories "Part programs" and "Subroutines".

Select softkey "New" to display a dialog window in which you can enter the names of the new main programs and subprograms. The matching file type is automatically assigned in this case.



or

OK

Then press the "OK" softkey or the "Input" key.

### 6.7.5 Execute a program on the NC for execution



Parts  
programs



Program  
selection

Workpieces



Workpiece  
selection



**Machine manufacturer**



**References**

#### Function

Workpieces and part programs must be selected for execution before you press the Cycle Start key.

#### Operating sequence

##### Select a program:

Use the cursor keys to select a program in the program overview, e.g. part programs, and

then press softkey "Selection".

The program name is displayed in the "Program name" window at the top right.

##### Select a workpiece:

A workpiece directory can be selected for machining in the currently active channel.

Use the cursor keys to select the workpiece

in the workpiece overview and then

press "Selection" softkey.

Once you have selected the workpiece, change back to the "Machine" "Automatic" operating area and select "Cycle start" to start machining. If you start machining in the "Program" operating area, you cannot track the cycle on the screen.

Please note information supplied by machine tool manufacturer!

/IAM/IM2/ Installation & Start-Up Guide: HMI Embedded

### 6.7.6 Execute Program from network drive, compact flash card, disk



#### Function

If the "Network and disk drive management on PCU 20" option is enabled, you can connect the control to an external network drive connected to the PCU or another computer and select and run programs from there.

The function is also available in the "Services" operating area.

#### Precondition:

- The computer you want to connect is accessible/enabled.
- The connection is set up to the computer.
- The softkeys for linking computers have been configured via the machine data.

#### References

/IAM/IM2, Installation & Start-Up Guide HMI Embedded

#### Operating sequence

When you select one of the configured softkeys, e.g. "Network drive", "Compact flash card" or "Disk", the Explorer appears on the screen with the files and programs of the external drive.

Select the program that you want to execute with the cursor and then press the "Execution from ext." softkey.

#### Further information

Direct execution from a network drive is not recommended, as the stability and dynamic response of all networks cannot be guaranteed.

#### Recommendation:

Copy the programs from the network onto the compact flash card on the PCU20 and run them from there.




Network drive

Compact flash card

Disk

Execution from ext.



### 6.7.7 Storing a program



Save file



#### Function

You can save the changes in a program that you have unloaded with the function "Save file".

#### Operating sequence

Changes are saved in the file loaded in the editor.

#### Further information

Please note that the changes to programs stored in the NC memory take immediate effect.

### 6.7.8 Enable workpiece/program



Change enable

#### Function

The program overview indicates whether a workpiece or part program is enabled.

This means that it may be executed by the control (because it has already been debugged) when you select softkeys "Select program" and "Cycle Start".

When a new program is created, it can be enabled automatically. You can select this in the editor settings.

#### Operating sequence

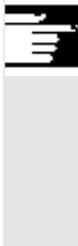
To set the enable for a program or abort it, position the cursor on the desired workpiece or part program in the program overview.

Select softkey "Change enable".

A cross indicating "Enable issued" appears behind the workpiece or part program.

Enable issued (program is executable)

No enabling (program must not be executed)



### Further information

- The system checks whether a program may be executed when the program is called (after selection via operator input or from part program). If you want it to be enabled, you must enable it beforehand.

### 6.7.9 Copy file and insert



### Function

This subsection explains how files can be copied.

### Operating sequence

Position the cursor on the file that you want to copy and press the softkey "Copy".

The file is marked as the source for copying.

Press the softkey "Insert", enter a new name and confirm with "OK".

When you insert a file in a workpiece directory, you can change its file type with the "Select" key. The file types are automatically adjusted in the global part program and the global subroutine directory.

### Further information

- Only files can be stored in a workpiece directory, not other workpiece directories.
- If the target specified is incorrect an error message is output.
- If a workpiece directory is copied, all the files that it contains are copied at the same time.

### 6.7.10 Rename file



Rename



#### Function

As regards files, you can alter their name as well as the associated file type.

#### Operating sequence

Position the cursor on the file you want to rename.

The "Rename" dialog window opens.

Enter the new name.

Only the workpiece is renamed, not the files it contains with the same name.

There are two ways of renaming files:

- Renaming the workpiece directory
- Renaming a file in the workpiece directory

#### Renaming a workpiece directory:

When you rename a workpiece directory, all the workpiece files under that directory that have the same name as the directory are renamed. If a job list with the name of the directory exists, the instructions in that job list are also renamed.

Comment lines remain unchanged.

#### Example:

Workpiece directory `A.WPD` is renamed `B.WPD`:

All files with the name `A.XXX` are renamed to `B.XXX`, i.e. the extension is not altered.

#### Renaming a file in the workpiece directory:

If you rename the files in the workpiece directory, all files with the same name but a different extension are renamed.

### 6.7.11 Delete file



#### Function

This section explains how you can delete workpieces or files.

#### Operating sequence

Position the cursor on the workpiece or the file you want to delete.

Delete several files:

If you want to select several files, position the cursor on the first file, press the "Select" key and then place the cursor on the last file.

The files you have selected are highlighted.

The prompt "Do you really want to delete the file?" appears.

Confirm your input.

#### Further information

- You can only delete programs that are not currently running.
- If you want to delete a workpiece directory, make sure that none of the programs it contains is currently selected.
- If a workpiece directory is deleted, all the files that it contains are deleted at the same time.

### 6.7.12 "Workpiece template" function



If no `_TEMPL_` exists for a workpiece, then you must create a workpiece named `_TEMPL_`. The files to be used as `_TEMPL_` template files must be set up accordingly.

#### Operating sequence

If the workpiece already exists, it will be copied and renamed when you select "New". All files in this directory are also copied into the new directory.

TEST.MPF

#### Example:

Workpiece:

`_TEMPL_`  
`_TEMPL_.MPF`

DATA.INI

TEST.MPF

Select softkey "New"

Name: Define "AXIS"

The new "Axis" workpiece is set up with the following files:

AXIS.MPF

DATA.INI

## 6.8 Memory info



Memory  
info

### Function

You can call a display showing the total available NC memory space.

### Operating sequence

When you press the "Memory info" softkey, the total free/used memory is displayed for

- NC memory
- Directories
- Files

in Mbytes.

## 6.9 EXTCALL

You can use the EXTCALL command to access files on network drives from a part program.

See:

PG/ Programming Guide Advanced, Chapter 2

### References

### Supplementary conditions

The following secondary conditions must be taken into account with EXTCALL calls:

- With EXTCALL you can only call files with the MPF or SPF extension from a network drive.
- The files and paths must adhere to the following NCK conventions: max. 25 characters for the name, 3 characters for the extension name.
- A program unit is found on a network drive with the EXTCALL command if
  - The search path points to the network drive with \$SC\_EXT\_PROG\_PATH - or to a directory on it. The program must be stored there directly; no other files must be located there. Any subdirectories are not searched. If you did not specify a drive, the call will be acknowledged negative.
  - The correct location of the program is specified in the EXTCALL call itself by means of a fully qualified path that can also point to a subdirectory of the network drive. If there is no file extension (MPF, SPF...), the HMI system will automatically add SPF.

### Further information

Direct execution from a network drive is not recommended, as the stability and dynamic response of all networks cannot be guaranteed.

### Recommendation:

Copy the programs from the network onto the compact flash card on the PCU20 and run them from there.



## Services Operating Area

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## 7.1 Function



### Function

The "Services" Operating Area provides the following functions:

- Read data in/out
- Manage data
- Series start-up
- Error logging output

## 7.2 Directory structure

All files are organized in a directory structure.

Files in the NC memory are sorted according to keywords.

### 7.2.1 NC active data

NC-active data can be displayed and selected in the "Data" menu. They can be transferred, e.g. to a PC, via the RS-232 interface.

### 7.2.2 Directories

The following directories contain special files:

#### 1. **Clipboard:**

Files and directories of any type may be created/stored in the clipboard.

They can also be selected for processing here.

Files must be transferred for storage on an external computer by means of a data transfer program such as PCIN.

#### 2. **Workpiece:**

All files (tool programs, tool data) needed to machine a workpiece can be stored in the "Workpieces" (.WPD) directory.

Like a part program, a workpiece can be selected in the NC for machining.



When a workpiece is selected for machining, an INI file (if available) of the same name as the workpiece is loaded to the NC and the main part program with the same name as the workpiece is automatically selected.

If there is no part program/MPF with the same name, an error message is issued and the previously selected part program remains active.

If an INI block of the same name (e.g. for the activation of tool data), other initialization blocks can be executed.

Example:

SHAFT.WPD	is selected
SHAFT.MPF	is displayed as the selected program
SHAFT.INI	is loaded in the working memory of the NC and processed

### 7.2.3 Data selection

You can read the following selection of file types in or out via the RS-232 interface:

File type	Meaning
.MPF	Part Program (Main Program File)
.SPF	Subroutine (Sub Program File)
.TOA	Tool offset (Tool Offset Active)
.UFR	Zero point offset (User Frame)
.TEA	NC machine data (Testing Data Active)
.RPA	R parameter with value assignment (R Parameter Active)
.SEA	Addresses with value assignments (Setting Data Active)
.COM	Comment file
.INI	Initializing data
.GUD	User data (global)
.LUD	User data (local)
.WPD	Workpiece directory
.SYF	System files
.OPT	Options
.BOT	Booting files 611D
.DIR	Directory
.DEF	Definitions data
.CEC	Sag/angularity
.QEC	Quadrant error compensation
.EEC	Measuring system error compensation

#### Keywords/directories in the tree file structure

The different files are made available for transmission under the following headings:

- Data (general):
  - Option data
  - Machine data (all, NC-MD, channel MD, Axis MD)
  - Setting data
  - Tool offsets
  - Work offsets
  - Global user data
  - R parameters
- Start up data
  - NCK data
  - PLC data

- Display machine data
- Workpieces
- Parts programs
- Subroutines
- User cycles
- Manufacturer cycles
- Standard cycles
- Comments
- Definitions
- Feed drive
- Main Spindle Drive
- OEM
  
- System Data
  - ASUP1
  - ASUP2
  - IBN
  - OSTORE1
  - OSTORE2
  - Versions
  
- Log book
- Communications fault log
- Texts
- Machine configuration

If your control includes additional directories, these can be found in the file tree.

### 7.3 Formats for saving and importing data

#### Path name

The path name is automatically entered when files are saved (archived).

The path is named in the first line of a file:

```
;$PATH=/_N_WKS_DIR/_N_SHAFT_WPD
```

When the file is re-imported into the control, it is stored in this path.

If no path is specified, the files are read in to the currently active, selected directory or to the clipboard.

#### Example of file with path name:

```
%_N_SHAFT_MPF
;$PATH=/_N_WKS_DIR/_N_SHAFT_WPD
N10 G0 X... Z...
...
M2
```

#### Formats

Files can be saved to archive files in three different formats:

- Punched tape/ASCII format
- PC/binary format
- Punched tape/ISO format

#### 7.3.1 Punched tape format

1. Only files with characters that can be displayed, i.e. files created in the text editor, can be saved. No binary data, however, can be saved.
2. Files in punched tape format can be edited with the text editor.
3. Files can be set up externally in punched tape format provided that they are formatted in compliance with the format specified below.
4. If a file is set up manually, it must begin with %<name>. "%" must be typed in the first column of the first line. An archive in punched tape format may contain several files, each of which must begin with %<name>.

The structure of archive files in punched tape format is as follows:

```

<leader>          ;can be included
%1st file name
;$PATH=1st path name ;can be included
1st block          NL          ;contents of file 1
2nd block         NL
...                NL
last block         NL

%2nd file name
;$PATH=2nd path name;can be included
1st block          NL          ;contents of file 2
...                NL
last block         NL

...                ;contents of file n
last block         NL
<trailer>         ;can be included

```

<leader>

Information of any type (characters with ANSI values < ANSI value 32 (blank)) which is not part of the useful data on the punched tape. They might be positioned at the beginning of the tape so that it can be inserted into the punched tape reader.



When the archive file is read, a check is made to determine whether it was saved with a leader. If it was, then it is read in again with a leader.

NL

Character for block end/new line; ANSI value 10 (0x0A)

%

Identifier positioned in front of a file name.  
The identifier must be positioned in the first column of the relevant line (at beginning of block).

File names

1. File names can contain the characters 0...9, A...Z, a...z or \_ and must not exceed 24 characters in total.
2. File names must have a 3-character extension (\_xxx).
3. Data in punch tape format can be generated externally or processed with an editor. The file name of a file stored internally in the NC memory starts with "\_N\_".  
A file in punched tape format begins with %<name>, "%" must appear in the first column of the first line.

## 7.3 Formats for saving and importing data

Examples:	<pre>%_N_SHAFT123_MPF = parts program SHAFT123 or %flange3_MPF      = parts program flange3</pre>
;\$PATH=	<p>Path statement; Identifier in front of a path name. The path statement must always be programmed as the next block after the file name. The ";" character in the path statement must be positioned in the first column of the relevant line (at beginning of block).</p>
Path names	<ol style="list-style-type: none"> <li>1. Path names end with <code>_DIR</code> (directory) or <code>_WPD</code> (workpiece).</li> <li>2. Path names can contain the characters <code>0...9</code>, <code>A...Z</code>, <code>a...z</code> or <code>_</code>.</li> <li>3. Paths must be specified in full (beginning with <code>"/"</code>). The separator for the directory hierarchy is <code>"/"</code>.</li> <li>4. A path name in punched tape format begins with <code>;\$PATH=&lt;path name&gt;</code> in the first column of the program. Path names in punched tape format start with <code>_N_</code> and end in <code>_DIR</code> (any directory) or <code>_WPD</code> (workpieces directory).</li> </ol>
Example:	<pre>;\$PATH=/_N_WCS_DIR/_N_PIVOT_WPD Workpiece directory PIVOT in directory Workpieces</pre>
	<p>The data listed after the file name/path name belong to the file with the name specified after <code>"%"</code> in the directory specified after <code>";\$PATH="</code>.</p>
<trailer>	<p>Any information (characters with ANSI values <code>&lt; ANSI value 32 (blank)</code> and not equal to ANSI value <code>10 (0x0A)</code>) which is not part of the useful tape data.</p>
<b>Search strategy when no path is indicated</b>	<p>If no path is entered in the punched tape format, the specified file name must be interpreted when the file is read into the control so that the file can be stored in a suitable position in the file tree.</p>

Files are stored in the file tree according to the following strategy:

File name in tape format	Converted internal file name	Interpreted internal path	Stored in directory
%*_INI	_N*_INI	/_N_NC_ACT_DIR	NC active data
%_N*_XXX	_N*_XXX	/_N_XXX_DIR /_N_NC_ACT_DIR	XXX /_N_NC_DIR
%MPFn	_N_MPFn_MPF	/_N_MPF_DIR	Parts programs
%SPFn	_N_SPFn_SPF	/_N_SPF_DIR	Subroutines
%Ln	_N_SPFn_MPF	/_N_SPF_DIR	Subroutines
%*	_N*_MPF	/_N_CLIP_DIR	Clipboard

\* = any file name

n = any program number (e.g. MPF123)

- The search strategy is applied only if no path has been named. Paths detected using the search strategy are otherwise overwritten by the "; \$PATH=" statement.
- Spaces in the name are ignored.

### Examples

#### 1. \*.MPF files

- PC format:  
Part program    Directory: Part program  
%MPF123        (/\_N\_MPF\_DIR)
- Punched tape format:  
Part program    Directory: Part program  
%\_N\_MPF\_MPF        ;\$PATH=/\_N\_MPF\_DIR

#### 2. \*.INI files

- PC format:  
Part program    Directory: NC active data  
%COMPLETE\_TEA\_INI (/\_N\_NC\_ACT\_DIR)
- Punched tape format:  
Part program    Directory: NC-active data  
%\_N\_COMPLETE\_TEA\_INI        ;\$PATH=/\_N\_NC\_ACT\_DIR

#### 3. Part programs with names that cannot be assigned

- PC format:  
Part program    Directory: Clipboard  
%HUGO (/\_N\_CLIP\_DIR)
- Punched tape format:  
Part program    Directory: Clipboard  
%\_N\_HUGO\_MPF        ;\$PATH=/\_N\_CLIP\_DIR

### 7.3.2 PC format binary format

Files which contain non-displayable characters/binary format can only be saved in PC format.



#### References

/IAD/Start-up: Section "Line checksum".



- If you save files in PC format and then edit them with a text editor, you will not be able to re-import them again. The file cannot be edited because the checksum will then no longer be correct.
- Start-up and update data must always be saved in PC format.

## 7.4 RS-232 C interface parameters

### Protocol

The following protocols are supported for transmission via RS-232-C:

- XON/XOFF and RTS/CTS,
- Software Flow Control and Hardware Flow Control

#### XON/XOFF

It is possible to set the two modes on the user interface for RS-232-C transmissions, i.e. Wait for Xon for data receive and Send Xon for data transmission. The default setting is H11 or H13.

**Input:** Is done by selecting in "Interface" display with the cursor keys and the "Input" key.

One possible way of controlling transfer is to use control characters XON (DC1, DEVICE CONTROL 1) and XOFF (DC3). If the buffer of the peripheral device is full, it sends XOFF and XON as soon as it can receive data again (= default).

#### RTS/CTS

The signal RTS (Request To Send) controls the transmission of the data transmission equipment.

**Active:** Data can be transmitted.

**Passive:** The signal CTS (Clear to send) is an acknowledgement signal for RTS that the Data transmission equipment is ready to transmit.

**Baud rate**

**Input:** By selecting in the "Interface" display under "baud rate" with the selection key

300 Baud  
 600 Baud  
 1200 Baud  
 2400 Baud  
 4800 Baud  
 9600 Baud (default)  
 19200 Baud

:

**Data bits**

Number of data bits for asynchronous transmission.

**Input:** By selecting in the "Interface" display under "Data bits"

- 7 data bits
- 8 data bits (default)

**Parity**

Parity bits are used to detect errors:

The parity bits are added to the coded characters to make the number of places set to "1" an odd number (odd parity) or an even number (even parity).

**Input:** Selected in the "Interface" display under "Parity"

- No parity (= default)
- Even parity
- Odd parity

**Stop bits**

Number of stop bits for asynchronous transmission.

**Input:** Selected in the "Interface" display under "Stop bits"

- 1 Stop bit (= default)
- 2 Stop bits

**Special functions**

The following special functions are also provided. These can be activated in the "Interface" display.

A checkbox with a cross in it means: special function active.

**Overwrite with confirmation only**

- |                                     |           |                                                                                        |
|-------------------------------------|-----------|----------------------------------------------------------------------------------------|
| <input checked="" type="checkbox"/> | Active:   | On reading in, a check is made to determine whether the file in the NC already exists. |
| <input type="checkbox"/>            | Inactive: | Existing files are overwritten without query.                                          |

**Block end with CR LF**

- Active: During output in punched tape format A CR character (carriage return, hexadecimal 0D) is inserted after every LF (Linefeed).
- Inactive: No CR inserted.

**Stop with end of transmission character**

- Active: Text mode: The end of transmission character is active.
- Inactive: Binary mode The end of transmission is not evaluated.  
The standard value for the transmission end character is hexadecimal 1A.

**Evaluate DSR signal**

- Active: Transmission is interrupted if DSR signal (connection 6 on X6) is missing.
- Inactive: DSR signal has no effect.

**Leader and trailer**

- Active: Leader ignored during input.  
During output 120x0(Hex) is displayed.  
(Feed before and after the data)
- Inactive: Both lead and trailer are read in.  
No leader 0(hex) on output.  
Read in is automatically recognized for all MMCs.

**Cycle watchdog**

- Active: During transmission problems or end of transmission (without transmission end character) the transmission is terminated after 5 seconds. The time monitoring function is controlled by a time emitter that is started with the first character and reset with every transmitted character.
- Inactive: Transmission is not aborted.

**Punch tape format**

Instead of binary format you can choose punched tape or punched tape/ISO format, i.e. programs are output in accordance with DIN 66025

e.g. SINUMERIK 840D programs: Start activated by % <file name>, %**MPF**<xxx> or %**SPF**<xxx>.

### 7.4.1 Interface parameterization

#### Parameters for serial printer

**Default:** RS-232-C printer

A printer with a serial interface is connected with a suitable cable (cable check to CTS).

Interface	COM 1	Selection of interface: COM 1 or COM 2
Device type	RTS-CTS	Start with XON
Baud rate	9600	Program start with LF
Stop bits	1	X Block end with CR LF
Parity	None	X Stop with end of transmission end character
Data bits	8	Evaluate DSR signal
XON	11 (H)	Leader and trailer
XOFF	13 (H)	X Punch tape format
Transmission end	0C (FormFeed)	Cycle watchdog

#### Parameters for archiving with PG/PC

**Default:** RS-232-C PG/PC

Interface	COM 1	Selection of interface: COM 1 or COM 2
Device type	RTS-CTS	Start with XON
Baud rate	9600	Program start with LF
Stop bits	1	Block end with CR LF
Parity	None	Stop with end of transmission end character
Data bits	8	X Evaluate DSR signal
XON	11 (H)	Leader and trailer
XOFF	13 (H)	Punch tape format
Transmission end	1A	X Cycle watchdog

This setting allows files in SINUMERIK 840D PC format to be archived and imported.

"Stop with end of transmission character" must not be selected for transmission of MSD and FDD files.

Other settings are possible with ASCII data. They must match the settings on the programming device. Cable 6FX 2002-1AA01- is used for this purpose.

## 7.4 RS-232 C interface parameters

**Parameters for DIN programs****Default:** RS-232-C user

Interface	COM 1		Selection of interface: COM 1 or COM 2
Device type	RTS-CTS		Start with XON
Baud rate	9600		Program start with LF
Stop bits	1	X	Block end with CR LF
Parity	None	X	Stop with end of transmission end character
Data bits	8	X	Evaluate DSR signal
XON	11		Leader and trailer
XOFF	13	X	Punch tape format
Transmission	1A		Cycle watchdog end

With this setting, programs are read in conforming to DIN (beginning with %).

**Punched tape input/output**

The "with leader and trailer" checkbox must be activated for tape readers and punches.

If the punched tape reader is controlled by CTS, the "Stop with end of transmission character" checkbox must also be activated.

Device type	RTS-CTS		Start with XON
Baud rate	9600		Program start with LF
Stop bits	2		Block end with CR LF
Parity	None	X	Stop with end of transmission end character
Data bits	8	X	Evaluate DSR signal
XON	00		Leader and trailer
XOFF	00	X	Punch tape format
Transmission	00	X	Cycle watchdog end

**References**

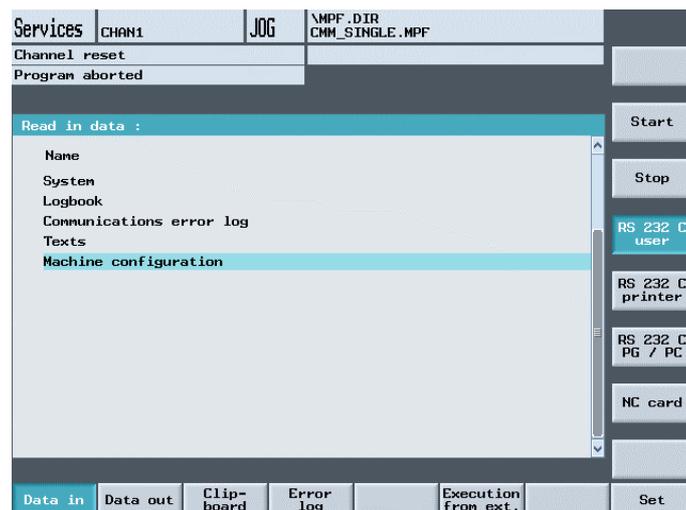
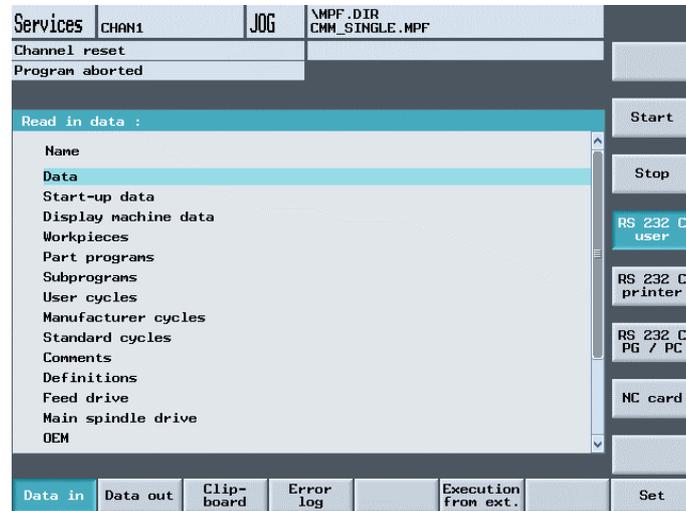
/FB1/K4/ Description of Functions, Basic Machine: Communication

**Reading in binary data (FDD, MSD)**

Device type	RTS-CTS		Start with XON
Baud rate	9600		Program start with LF
Stop bits	1		Block end with CR LF
Parity	None		Stop with end of transmission end character
Data bits	8		Evaluate DSR signal
XON			Leader and trailer
XOFF			Punch tape format
Transmission	00		Cycle watchdog end

## 7.5 Main services screen

All transferable data/programs are displayed in the "Services" basic display.



Data in

Data out

Clipboard

Error log

Execution from ext.

### Horizontal softkeys

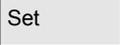
The "Read in data" menu is opened.

The "Read out data" menu is opened.

The "Clipboard" menu is opened.

You obtain information about the data transmission which has taken place.

Step-by-step loading and execution of external programs can be initiated in this screen.



Set

The interface parameters of the currently selected interface can be changed.



Start

#### Vertical softkeys

Data read-out is started.



Stop

The data output operation is aborted.



RS 232 C  
user

You can select the RS-232 interface via

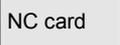
- RS-232-C user
- RS-232-C printer
- RS-232-C PG/PC
- is selected.



RS 232 C  
printer



RS 232 C  
PG/PC



NC card

Data can be created, imported or deleted on the NC card.



additional

If the "logical drives" option is set up, the softkeys are displayed (max of 4 drive connections) via the softkey "additional".

#### The following applies in the "Services" operating area:

- Changes resulting from data transmissions are accepted and stored. Any modifications are thus retained when the NC powers up again.
- The selected window is closed. The next data tree display is displayed in the selected view.

### 7.5.1 Setting the interface



RS 232 C  
user

RS 232 C  
printer

RS 232 C  
PG/PC

Set



#### Function

You can output files to an external data storage device or read them in from there via the RS-232 interface. The RS-232 interface and your data backup device must be compatible. The control provides you with an input screen form for this purpose in which you can define the specific data for your device.

You have the option of selecting three different RS-232 interface parameter sets:

1. RS-232-C user
2. RS-232-C printer
3. RS-232-C PG/PC

#### Operating sequence

Select one of the three softkeys for the RS-232 interface. The softkey remains marked so that you can see what you have selected.

- RS-232-C user
- RS-232-C printer
- RS-232-C PG/PC

Press softkey "Set" if you wish to alter the interface parameters for the currently selected interface (softkey is highlighted). The name of the interface to be set up is displayed in the title.

Position the cursor on the input fields and enter the required values.

The values of parameters "Device type", "Baud rate", "Stop bits", "Parity" and "Data bits" are selected with the "Select key".

You can also activate and deactivate special functions with the "Select key".



Save  
settings

Close the parameter setting display by pressing the "Save settings" softkey.

The data for the interface are stored with the values you have entered.

(See also Section "Interface parameters")

## 7.5.2 Reading in data via RS-232 interface



### Function

It is possible to read data into a particular directory or into the clipboard via the RS-232 interface.



### Operating sequence

The interface for your data unit is set correctly.



Data in

When you press softkey "Data in", the currently selected RS-232-C interface parameter settings are stored.



RS 232 C  
user

Via the vertical softkey bar select the interface:

- RS-232-C user
- RS-232-C PG/PC



RS 232 C  
PG/PC



Position the cursor on the desired directory in the directory tree.




Save  
settings

You return to the overview of the higher level directory by pressing the "Save settings" softkey.



You can discard your settings by pressing the Recall key.

Start

When you press the "Start" softkey, data are read in and stored in the specified path.

Path/workpiece from archive file

To archive files using the "Data out" function, the directory paths from which the files were read are stored with the other data in archiving format.

The stored paths are interpreted on import and the files are copied back to the directories from which they were backed up (NC default `MPF.DIR`).

In punched tape format, the `;$path =` statement is applied.

Path/workpiece from archive file

Irrespective of the archived path name, all files are stored in the directory selected beforehand with the "Direction keys".

Readin to the clipboard

All archived data are stored in the clipboard regardless of the archive path name.

OK

The data are read in. The message "Transmission in progress" is displayed.

The display shows "Path/workpiece", "File" and the number of transmitted "Bytes".

Stop

You can interrupt data import at any time by pressing the "Stop" key.

Start

If you press softkey "Start" again, the data import recommences from the beginning.



### Further information

- The control system cannot call specific data for import.
- If you have selected the "Overwrite and confirm" option, existing files are overwritten after your confirmation. On rejection, reading in continues with the next file.
- Only data that have an extension known to the system can be read in.
- When importing with the setting "Without file end character" or "Without timeout," transmission must be stopped with the STOP softkey.
- Transmission is not complete until the window "RS-232-C running" is closed.
- If a program is overwritten when data are read in, the NC deletes the program at the beginning of the transmission operation and inserts the program again when all data have been transferred.

### Import of machine data

The BOOT files/`INITIAL.INI` initialization file produce the basic setting of the machine.

- The "Path from workpiece/archive" box must be checked for the RS-232 interface before the Start command is given. This applies both to data in archive format and in punched tape format.
- An "NC Reset" must then be carried out to make the machine data operative.

### 7.5.3 Inserting data from the clipboard



#### Function

You can store data from the clipboard in a new directory, copy or delete them.



#### Operating sequence

Data have been read into the "Clipboard" directory via the "Data in" interface.

Clipboard

Select softkey "Clipboard".

The vertical softkey bar changes.

The cursor is positioned on a file in the "Clipboard" window. The selected window is active.



Copy and  
paste

OK



Back

Delete



#### Select source:

Position the cursor on the file that you wish to place in the data structure of the control.

Position the cursor in the top window by selecting the "Window selection" key. The top window is then active.

#### Select target:

Position the cursor on the target directory in which you wish to place the file you have just located.

A confirmation window is displayed.

If you wish to retain the file name stored in the clipboard, confirm by pressing softkey "OK".

If you want to use another file name, enter the new name and terminate your input by pressing softkey "OK". The file is copied into the target directory and is not deleted from the clipboard.

Go back to the directory overview by pressing softkey "Back".

#### Deletion

You can only delete data from the clipboard with the "Delete" key.

Files stored in the clipboard are not automatically deleted when placed in the data structure.

You must ensure that the clipboard is cleared so that it does not take up too much memory space unnecessarily.

## 7.5.4 Reading out data via RS-232 interface



Data out

RS 232 C  
user

RS 232 C  
PG/PC

RS 232 C  
printer



Save  
settings



Start

Stop

Start

**Function**

You can read data out of the control system via the RS-232 interface to a device (e.g. PC) connected to the interface.

**Operating sequence**

The interface for your data unit is set correctly.

The "Data out" window is opened.

Via the vertical softkey bar select the interface:

- RS-232-C user
- RS-232-C PG/PC
- RS-232-C printer

Position the cursor on the desired directory in the directory tree.

You return to the overview of the higher level directory by pressing the "Save settings" softkey.

You can discard your settings by pressing the Recall key.

The data are read out. The message "Transmission in progress" is displayed.

The display shows "Path/workpiece", "File" and the number of transmitted "Bytes".

You can interrupt data export at any time by pressing the "Stop" key.

If you press softkey "Start" again, the data export recommences from the beginning.

### 7.5.5 Reading out PLC alarm texts and cycle texts



#### Function

PLC alarm texts, cycle texts and cycle alarm texts can be read out.



#### Operating sequence

The "Data out" window is opened.

Data out

A screen appears where you can select your desired language. You can choose any of the following texts from "Texts":

- PLC alarm texts (user)
- PLC alarm texts (standard)
- Standard cycles
- User cycles
- Manufacturer cycles
- Cycle alarm texts (user)
- Cycle alarm texts (standard)

### 7.5.6 Outputting error/transmission log



#### Function

A log listing data that have been imported and exported can be output in the Services operating area.

The log contains

1. for files to be output
  - the file name complete with pathname, and
  - an error acknowledgment.
2. for files to be input
  - the file names and the 1st line, which generally contains the path name ; \$PATH= . . . , and
  - an error acknowledgment.

#### Transmission messages

The following messages may appear during transmission:

"OK"

Transmission has been terminated correctly.





Error  
log

### Operating sequence

You can display information about the data transfer operation by pressing softkey "Error log".

#### 7.5.7 Execution from external source via RS-232 interface



Execution  
from ext.

Start

### Function

You can download external programs via the RS-232 interface to the NC and edit them immediately. The buffer size for the part program blocks temporarily stored in the NC depends on the NC memory and its distribution.

- H= . . . contains, as well as
- an error acknowledgment.

### Operating sequence

All downloadable data/programs are displayed.

Select a range, e.g. part program and

Press softkey "Execution from ext.".

Execution commences after "Start".

#### 7.5.8 Reading ISO programs in/out via RS-232 C



### Function

ISO programs can be read in and out in punched tape format.

### Further information

FANUC 0 control system programs can be read in and out as ISO programs.

The punched tape format for ISO programs (ISO punched tape format) is not the same as Siemens HMI Embedded punched tape format.



The first line of a punched tape in ISO format must have the following format: %<Title>LF or %<Title>CRLF.

The title can be omitted and blanks can be skipped. The title may not start with one of the following characters: 0...9, a...z, A...Z or \_.

No title is generated when a punched tape is generated in ISO format.

Siemens program headers are introduced by %<Name> and pathname ;PATH=<Path> in the next block.

ISO program headers are characterized by O<xxxx (Title)> O or :<xxxx (Title)> without pathname in the next block.

x stands for a number between 0 and 9. Between one and four digits can be specified, leading zeros can be omitted.

During export, ISO program headers are only tagged with O<...> and not with :<...>.

### Retrieving

Data in

The procedure for importing a punched tape in ISO format is the same as the procedure used to import a regular punched tape archive in the "Services" operating area with "Data in". During the import, the system detects automatically whether the archive to be imported is stored in binary/PC, punched tape or ISO punched tape format.

Imported ISO programs are stored as main programs on the NC. You must set the read-in directory every time you import programs to the "Services" area by selecting → "Data In" → "Start". If "Path from workpiece/archive" is selected, ISO programs are stored in the selected directory (e.g. workpiece xxx) or in the default NC directory (MPF.DIR); DIN programs are stored in accordance with their specified path.

ISO punched tape with two ISO programs:

```
%  
01026 (HYDRAULIC BLOCK)  
N20 G00 G80 G90 G40 G17  
N40 (NC-SPOT DRILL) T01 M06  
N50 G55 G43 Z20. H01 S1000 F100 M03  
N55 X10. Y-8. M08 T02  
(...)  
N690 Y-43.  
N700 G80 Z35.  
N710 T00 M66  
N715 G53 Y0. Z0.  
N720 M30  
:1127 (ANGLE)  
N10 (2. SPEED RANGE)  
N20 G00 G80 G90 G40 G17  
N120 (SPI-BO 11) T01 M06  
N130 G55 G43 Z20. H01 S2300 F460 M03  
(...)  
N180 Y-72.  
N190 G80 Z35.  
N195 T00 M66  
N200 G53 Y0. Z0.  
N210 M30  
%
```

This punched tape generates two programs when imported:

\_N\_1026\_MPF and \_N\_1127\_MPF; the title is retained after the program number:

**Program \_N\_1026\_MPF:**

```
(HYDRAULIC BLOCK)  
N20 G00 G80 G90 G40 G17  
N40 (NC-SPOT DRILL) T01 M06  
(...)  
N710 T00 M66  
N715 G53 Y0. Z0.  
N720 M30
```

**Program \_N\_1127\_MPF:**

```
(ANGLE)  
N10 (2nd SPEED RANGE)  
N20 G00 G80 G90 G40 G17  
(...)  
N200 G53 Y0. Z0.  
N210 M30
```

**Export**

Data out

The procedure for generating a punched tape in ISO format is the same as the procedure used to generate a regular punched tape archive in the "Services" operating area with "Data out". The current output format determines whether the archive is created in binary/PC, punched tape or ISO punched tape format.

The output format can be modified in the "Services" operating area with "Set".

A Select field offers the setting options

Punched Tape Format, Punched Tape Format/ISO or Binary Format (PC format).

If both ISO programs and Siemens programs are selected for the creation of an ISO punched tape archive, an ISO punched tape is generated without an alarm or message output; the punched tape contains Siemens program headers in addition to the ISO program headers.

If a Siemens program is followed by an ISO program, an %<LF> or %<CR><LF> is inserted in front of the ISO program header, depending on the output format, because the character string O<four digits> or:<four digits> cannot uniquely be assigned to a new program in DIN-Code.

These "mixed" ISO punched tape archives can be read back in by HMI Embedded; however, reading the archives in to other types of control will result in premature termination due to the % character (% character in ISO format indicates tape end).

```
%
%_N_TEST1_MPF
;$PATH=/_N_WKS_DIR/_N_TEST_WPD
N40 G01 X150 Y150 Z150 F6000
N50 G90 G0 X0 Y0 Z0 G53
; ...
N500 G02 z100 x50 k-50 i0
N510 z50 x100 k0 i50
M30 ;Transfer from Siemens prog. to Siemens prog.
%_N_TEST2_MPF
;$PATH=/_N_WKS_DIR/_N_TEST_WPD
N40 G01 X150 Y150 Z150 F6000
```

```

; ...
M30    ;Transfer from Siemens prog. to ISO prog.
%
O1127(ANGLE)
N10(2nd SPEED RANGE)
N20 G00 G80 G90 G40 G17
(...)
N200 G53 Y0. Z0.
N210 M30
%
```

If both ISO programs and Siemens programs are selected for the creation of a Siemens punched tape archive, a conventional punched tape is generated which contains only Siemens program headers, i.e. the ISO programs contain Siemens program headers.

```

%_N_TEST1_MPF
;$PATH=/_N_WKS_DIR/_N_TEST_WPD
N40 G01 X150 Y150 Z150 F6000
N50 G90 G0 X0 Y0 Z0 G53
; ...
N500 G02 z100 x50 k-50 i0
N510 z50 x100 k0 i50
M30    ;Transfer from Siemens prog. to Siemens prog.
%_N_TEST2_MPF
;$PATH=/_N_WKS_DIR/_N_TEST_WPD
N40 G01 X150 Y150 Z150 F6000
; ...
M30    ;Transfer from Siemens prog. to ISO prog.
%_N_1127_MPF
;$PATH=/_N_WKS_DIR/_N_TEST_WPD
(ANGLE)
N10(2nd SPEED RANGE)
N20 G00 G80 G90 G40 G17
(...)
N200 G53 Y0. Z0.
N210 M30
```

The difference is irrelevant for archives in binary format.

### Further information

Binary files cannot be output in ISO punched tape format.

The display indicators differ in the use of ISO, particularly with regard to the representation of H numbers.

### 7.5.9 Execute program from network drive, Compact Flash Card, disk



#### Function

If the "Network and disk drive management on PCU 20" option is enabled, you can connect the control to an external network drive (up to a max. of 4 drives) connected to the PCU or another computer and select and run programs from there.

The function is also available in the "Program" operating area.

#### Prerequisite:

- The computer you want to connect is accessible/enabled.
- The connection is set up to the computer.
- The softkeys for linking computers have been configured via the machine data.

#### References

/IAM/IM2, Installation & Start-Up Guide HMI Embedded

#### Operating sequence

Use the "More" softkey to display the configured softkeys for the external drive or computer on a second vertical bar.

When you select one of the configured softkeys, e.g. "Network drive", "Compact Flash Card" or "Disk", the Explorer appears on the screen with the files and programs of the external drive.

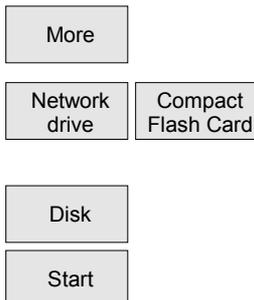
Select the program that you want to execute with the cursor and then press the "Start" softkey.

#### Further information

Direct execution from a network drive is not recommended, as the stability and dynamic response of all networks cannot be guaranteed.

#### Recommendation:

Copy the programs from the network onto the compact flash card on the PCU20 and run them from there.



### 7.5.10 Restoring the original status via NC card



#### Function

The free memory on the NC card (PCMCIA card) can be used to store a start-up archive.

The archive can be loaded onto the NC card with SINUCOPY-FFS (on an external PG/PC).

The series machine start-up archive can be stored directly with the name "Original" in HMI Embedded on the NC card (see Series machine start-up - creating a file).



**Various archives can be selected and generated**



Original state

#### Operating sequence

##### Precondition:

The start-up archive with the name `_N_ORIGINAL_ARC` is located on the NC card (in the directory `_N_NC_CARD_DIR\N_ARC_DIR`).

Select the "ETC key" in the main Services screen and then the "Original state" softkey.

When you press the softkey, the protocol window appears with the query: "Series start-up archive: Perform series start-up?". After confirmation, the data are imported.

##### Caution

All user-specific NC data (and PLC data depending on contents) will be deleted and replaced by the data from the archive.

#### Further information

Users with access authorization to level 3 and higher can access this softkey. It is displayed only if archive `_N_ORIGINAL_ARC` is stored on the NC card.



### 7.5.11 Saving data to NC card



#### Function

For saving data to NC-Card there is at least 3MB (or 8MB Memory Flash Card) available.

The files listed in the data overview ("Organize data" window) can be saved to the NC card.

Cycle alarm texts can be stored as well as start-up data, workpieces, etc.

Precondition: Directory "ARC.DIR" must already exist on the card.



#### Operating sequence

Data out

When you select the "Data out" softkey, the directories or files that you can select by paging and the cursor key are displayed; activate "Organize data" window if appropriate.



You can open the directory or file with the "Input" key.

NC card

Select softkey "NC card"

Start

When you select softkey "Start" the "Create archive" window appears. Enter a name and confirm with "OK".

OK

If you want to read these files back from the NC card, follow the same sequence in reverse order.



### 7.5.12 Series start-up



Series  
start-up

RS 232 C  
user

More

Start

Data in

#### Function

You can archive the current software on your machine and import it to other machines with series start-up.

You can choose which data you want to archive:

- NCK data with/without compensation data
- Loadable compile cycles
- PLC data

If you want to import data to other machines, you should not archive the compensation data along with other data, because compensation data is machine specific.

The drive data (contained in the NCK data) are saved in binary format; i.e. you cannot change the drive data.

You can archive data via the RS-232 interface or archive it to the NC Card or to other drives connected with the PCU (logical drives).

If you want to archive data via the RS-232 interface, you must set the "binary" format.

#### Operating sequence

Press the "ETC" key and then the "Series start-up" softkey.

You can choose which data you want to archive.

You can choose where you want to save the archive.

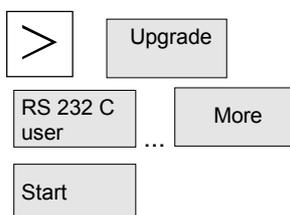
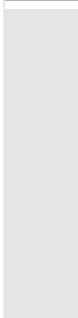
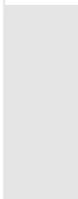
Press "Start" softkey.

Enter the archive name.

The selected data are saved in an archive file.

The archive file can be read in via the "Data in" function.

### 7.5.13 Upgrading



#### Function

If you want to upgrade your machine, you can archive the NCK data beforehand. In this way, the drive data is saved in ASCII format, i.e. you can change the drive data.

You can archive data via the RS-232 interface or archive it to the NC Card or to other drives connected with the PCU (logical drives).

#### Operating sequence

Press the "ETC" key and the "Upgrade" softkey.

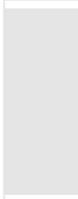
Choose where you want to save the archive.

Press the "Start" softkey, and enter the archive name.

The NCK data (including drive data) are saved in an archive file.

The archive file can be read in via the "Data in" function.

### 7.5.14 Manage programs from network and disk drives



#### Function

If the "Network and disk drive management on PCU 20" option is enabled, you can connect the control to an external network drive connected to the PCU or another computer and select and run programs from there.

This function is also available in the "Program" operating area.

#### Operating sequence

See Chapter 6: Manage Programs from Network and Disk Drives



## Diagnosis Operating Area

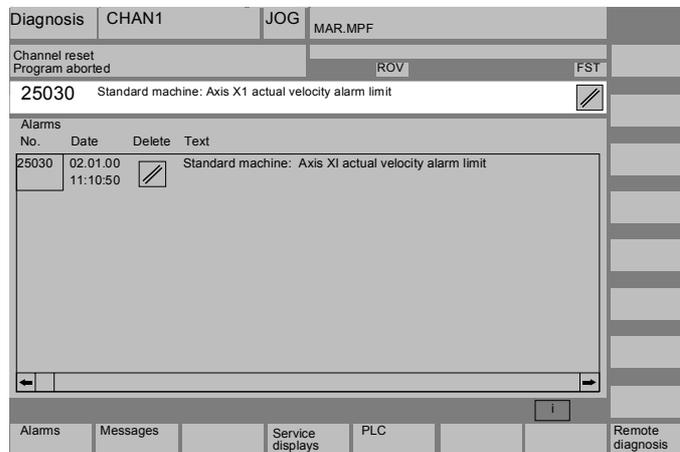
8.1	Basic display diagnosis.....	8-280
8.2	Displaying alarms and messages .....	8-281
8.3	Service display .....	8-282
8.3.1	Service axis.....	8-282
8.3.2	Service drive .....	8-283
8.3.3	Service safety integrated .....	8-284
8.3.4	Display and modify system resources .....	8-287
8.3.5	Communications fault log.....	8-287
8.3.6	Display version data.....	8-288
8.3.7	Displaying loadable compile cycles .....	8-289
8.4	PLC .....	8-290
8.4.1	General .....	8-290
8.4.2	Change/delete operand value.....	8-291
8.4.3	Selecting/creating operand forms for PLC status .....	8-292
8.4.4	Setting the time/date .....	8-293
8.5	Activate remote diagnosis.....	8-294

## 8.1 Basic display diagnosis



A display headed "Alarms" appears when you select the operating area "Diagnosis".

## Basic screen



## Explanation of display

Number

The alarm number is output under "Number". The alarms are output in chronological order.

Date

The time at which the alarm occurred is displayed with date, hour, minute, second, 100's second.

Delete criterion

The symbol denoting the alarm abort key is displayed for every alarm.

Text

The alarm text is displayed under "Text".

## Horizontal softkeys

Alarms

All active alarms are displayed in the "Alarms" display.

Messages

An overview of active messages is displayed.

Service displays

You can view updated information about axes and drives installed in your system under softkey "Service displays".

PLC

Information on the current status of the PLC memory locations is displayed.

Remote diagnosis

If this option is set, it is possible to control and influence the operation of a control from a remote PC, as well as to transmit process data.

## 8.2 Displaying alarms and messages



### Function

You can display a list of alarms and messages.



### Operating sequence

#### Alarms:

The alarm overview displays all active alarms with alarm numbers, date, clearance criteria and descriptions.

Clear the alarm by pressing the key that is displayed as a symbol:  
Switch device off and on again (main switch)  
or NCK POWER ON

Press "Reset" key.

Press "Alarm Cancel" key.

Alarm is cleared with the "Cycle Start" key.

Alarm is cleared with the "Recall" key (message box).

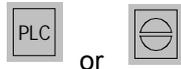
#### Messages:

PLC operational messages that do not have to be acknowledged (as standard) (configurable).

#### Acknowledgement symbols:

You can use a machine datum to set which acknowledgement symbol is to be displayed for PLC alarms.

The following symbols are available:



or

#### Display several alarms in succession:

By setting a machine datum, you can display several alarms (NCK, PLC, HMI) in succession in the alarm line. Each alarm remains visible in the set tool life until it is displaced by the next alarm.



Alarms




Messages

## 8.3 Service display

### 8.3.1 Service axis



#### Function

The information in the "Service Axis" display is used to

- check the setpoint branch (e.g. position setpoint, speed setpoint, spindle speed setpoint prog.)
- check the actual-value branch (e.g. position actual value, measuring system 1/2, actual speed value), optimize the position control of the axis (e.g. following error, control difference, servo gain factor)
- check the entire control loop of the axis (e.g. through position setpoint/actual-value comparison and speed setpoint/actual-value comparison)
- check hardware faults (e.g. encoder check: If the axis is moved mechanically, the actual position value must change)
- set and check axis monitoring functions.



#### References

/FB1/D1: Diagnostic tools



#### Operating sequence

Select the menu headed "Service displays".  
The horizontal softkey bars change.

The "Service axis" window displays information about the machine axis together with axis name and axis number.

You can page up and down with the "Page" keys.

The service values of the next (+) and the previous (-) axis are displayed.

Service displays

Service axis

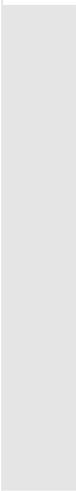


PAGE DOWN

Axis +

Axis -

### 8.3.2 Service drive



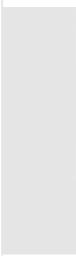
#### References

#### Function

The information contained in the "Service drive" display is used to

- check the status on enabling and control signals (e.g. pulse enable, drive enable, motor selection, setpoint parameter set), and on FDD/MSD operating modes (e.g. setup mode, parking axis)
- display temperature warnings, check the current setpoint/actual-value display (e.g. position actual-value measuring system 1/2, speed setpoint, speed actual value)
- check the drive status
- display the current ramp-up phase
- display total error messages (Message ZK1), display the status messages of the drive (e.g. threshold torque not reached, actual speed = set speed)

/FB1/D1: Diagnostic tools



Service displays

Service drive



PAGE DOWN

PAGE UP

Drive +

Drive -

#### Operating sequence

Select the menu headed "Service displays".  
The horizontal softkey bars change.

The "Service drive" window displays information about the axis drive together with axis name and number.

You can page up and down with the "Page" keys.

The service values of the next (+) and the previous (–) drive are displayed.

## 8.3.3 Service safety integrated



## Status SI

## Function

Upon activation of the "Service SI" softkey, three information blocks about SI-related data are displayed on the HMI Embedded for the selected axis:

- Status SI (selected by default)
- SGE/SGA
- SPL

**References:** FBSI/, Description of Functions Safety Integrated.

Diagnosis	Chan1	Jog	MPF.DIR		
Channel reset					Aixs +
Program aborted					
					Axis -
<b>Safety Integrated Status</b>					
Signal	NCK	Drive	Unit		
Safe actual position	0.0000	0.0000	inch		
Positional deviation NCK/drive	0.0000	-	inch		
Monitoring "Safe operational stop" active	Yes	No			
Monitoring "Safe speed" active	No	No			
Active safe speed level	None	None			
Active safe speed correction factor	None	-	%		
Safe actual speed limit	Inactive	-	inch/min		Status SI
Setpoint speed limit	Inactive	-	inch/min		
Current speed difference	0.0000	-	inch/min		
Maximum speed difference	0.0000	-	inch/min		
Active safe software limit switch	None	None			SGE/SGA
Active gear ratio	1	1			
Active stop	A/B	None			
Currently requested external stop	A	A			SPL
Stop F code value (alarm 300911)	Pulses	A			
Pulses enabled	-	-			
Traversing disable because other axis is stopped	No	-			
<div style="display: flex; justify-content: space-between;"> <span>Service axis</span> <span>Service drive</span> <span style="border: 1px solid black; padding: 2px;">Service SI</span> <span>System resources</span> <span>Comm. log</span> <span>Action log</span> <span>Version</span> </div>					

Set the required axis via the vertical softkeys "Axis +" and "Axis –".  
The active axis is displayed in the top right half of the table.

## Available signals/values

Safe actual position  
 Positional deviation NCK/drive  
 "Safe operational stop" monitoring active  
 "Safe speed" monitoring active  
 Active safe speed level  
 Active safe speed correction factor  
 Safe actual speed limit  
 Safe setpoint speed limit  
 Current speed difference  
 Maximum speed difference  
 Active safe software limit switch  
 Active gear ratio  
 Active stop  
 Currently requested external stop  
 Stop F code value (alarm 300911)  
 Pulses enabled  
 Traversing disable due to stop on other axis



Service displays

Service SI

Axis +

Axis -

SGE/SGA

SPL

### Operating sequence

Select the menu headed "Service displays".  
The horizontal softkey bars change.

The "Service SI" window displays information about Safety Integrated data together with the associated axis name and axis number.

The service values of the next (+) and the previous (-) axis are displayed.

Use this softkey to display the safety-relevant input and output signals SGE and SGA.

Use this softkey to display the safe programmable logic signals SPL.

### SGE/SGA

Diagnosis	Chan1	Jog	MPF_DIR SP25.MPF	
Channel reset				Axis +
Program aborted				
<b>Safety Integrated SGE/SGA</b>			<b>X1</b>	Axis -
<b>SGE</b>				
Safe input signals NCK bit 0...15			0000 0000 0000 0000	
Safe input signals drive bit 0...15			0000 0000 0000 0000	
Safe input signals NCK bit 16...31			0000 0000 0000 0000	
Safe input signals drive bit 16...31			0000 0000 0000 0000	
<b>SGA</b>				
Safe output signals NCK bit 0...15			0000 0000 0000 0000	Status SI
Safe output signals drive bit 0...15			0000 0000 0000 0000	
Safe output signals NCK bit 16...31			0000 0000 0000 0000	SGE/SGA
Safe output signals drive bit 16...31			0000 0000 0000 0000	
^				
Service axis	Service drive	Service SI	System resources	Comm. log
				Action log
				Version

The available signals can be seen in the above screen.  
The vertical softkey Status SI takes you to the Status SI screen,  
SPL opens the Safe Programmable Logic screen.

## SPL

Diagnosis		Chan1	Jog	MPF.DIR														
Channel reset				SP25.MPF														
Program aborted																		
Safely Integrated SPL				X1														
Variable	Bits	Area	Value															
\$A_INSE(P)	01...08	NCK	0000 0000 0000 0000															
		PLC	0000 0000 0000 0000															
\$A_OUTSE(P)	09...16	NCK	0000 0000 0000 0000															
		PLC	0000 0000 0000 0000															
\$A_INSI(P)	17...24	NCK	0000 0000 0000 0000															
		PLC	0000 0000 0000 0000															
\$A_OUTSI(P)	25...32	NCK	0000 0000 0000 0000															
		PLC	0000 0000 0000 0000															
Signal				Value														
Cross-checking fill level				0														
Cross-checking status				No errores occurred														
Cross-checking control word				IS														
SPL power up status				0000 0000 0000 0000														
SPL powered up				No														
<table border="1"> <thead> <tr> <th>Service axis</th> <th>Service drive</th> <th>Service SI</th> <th>System resources</th> <th>Comm. log</th> <th>Action log</th> <th>Version</th> </tr> </thead> <tbody> <tr> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> </tbody> </table>					Service axis	Service drive	Service SI	System resources	Comm. log	Action log	Version							
Service axis	Service drive	Service SI	System resources	Comm. log	Action log	Version												

In the "Variable" selection box, you can select:

\$A\_INSE(P) corresponds to simultaneous activation of

\$A\_INSE upper line, origin of the NCK and

\$A\_INSEP lower line, origin of the PLC

and effectively the same for the other variables:

\$A\_OUTSE(P)

\$A\_INSI(P)

\$A\_OUTSI (P)

\$A\_MARKERSI(P)

Under Bit you can request an 8-bit range from the selected signal.

## Saving

The variables that have been selected and the associated bit areas are saved and are taken into account when subsequently selecting the screen.

In addition to the current values, the origin of the displayed NCK/PLC signals is displayed.

The settings are reset the next time the control is powered up.

## Displayed signals

Cross-checking fill level (CDC Crosswise data comparison)

Cross-checking status

Cross-checking control word

SPL power up status

SPL powered up

SPL power up status: Bit0: SPL interface parameters set  
 Bit1: SPL program file SAFE.SPL loaded  
 Bit2: NCK waiting for PLC power-up  
 Bit3: PLC power-up complete  
 Bit4: Interrupt needs to be assigned for SPL start  
 Bit5: Interrupt has been assigned for SPL start



- Bit6: Interrupt processing for SPL start called
- Bit7: Interrupt processing for SPL start terminated
- Bit9: NCK cross-checking has been started
- Bit10: PLC cross-checking has been started
- Bit11: Cyclic SPL checksum checking active
- Bit12: All SPL protection features active

### 8.3.4 Display and modify system resources



#### Function

You can display the system resources currently in use for the NC and HMI Embedded areas (utilization display).



#### Further information

The display is also available in the "Start-up" operating area. The procedure is described in Chapter 9, Section entitled "Display and Change System Resources".

### 8.3.5 Communications fault log



#### Function

Errors occurring in the communication between HMI Embedded and NCK/PLC are recorded in a communication error log.

Comm.  
Log

You can display this log by pressing the "Comm. Log." key.



The error log file is principally used by the control manufacturer (Siemens) as a diagnostic tool for communication errors.

The communication error log file can be read out via the RS-232 interface in the "Services" operating area.

### 8.3.6 Display version data



#### Function

You can read the HMI and the NCU version in the version window. The HMI Embedded is also displayed in the run-up screen as well as during installation.

The complete product identifier (e.g. HMI-Embedded) also appears in front of the 8 digit version identifier.

In the "Services" operating area, the version data can be read from the (System, File "VERSION\_SYF") directory via the RS-232 C interface or via one of the logical drives (NC-card).



#### Operating sequence

Press "Service displays" softkey.  
The horizontal softkey bars change.

Service displays

Open the "Version" window. More areas are available and you can see the version data via the following horizontal softkeys:

Version

Version display of the NCU

NCU Version

Version display of the HMI Embedded.

HMI Version

Only if option selected, version display for compile cycles.  
see Chapter: "Displaying Loadable Compile Cycles"

Compile cycles

Version display for cycles

Cycles version

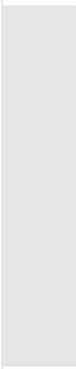
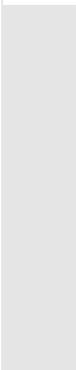
Use the "Page" keys to scroll up and down.

PAGE DOWN PAGE UP

Save versions



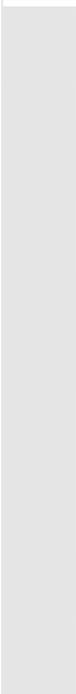
### 8.3.7 Displaying loadable compile cycles



Service displays

Version

Compile cycles



Properties

Version display

#### Function

If compile cycles are available in the NCK, you can display them in a separate version display. Besides the current version (name, extension, type, date, time, length) and the start address (path/NC-card), the access authorization for "reading, writing, enabling, listing and deleting" are displayed.

Loadable compile cycles are available for the following software versions:

- NCK SW 6.3 and higher
- HMI Embedded: (SW 6.5 and higher)

#### Operating sequence

Compile cycles are loaded when you initiate an NCU reset and can be displayed.

When you open the "Version" window in the "Service displays" menu, the "Compile cycles" softkey is displayed.

All loaded files of the type **.elf** are displayed in the "Version data compile cycles" overview.

In the "Services" operating area, you can output data via RS-232 C in the "Manage data" basic screen. Additional storage places, such as logical drives, are also possible.

Press the "Properties" softkey

The horizontal and vertical softkey menu changes and a "Properties" window, such as the one below for NC card, appears.

<b>Features</b>			
Path	:NC-Card\Loadable-Compile-Cycles		
Name	:CCMCSC	Date:	Time
Extension	:ELF	Length:	Loaded: <input type="checkbox"/>
Type	:Loadable compile cycle		
<b>Access authorization</b>			
Reading:	Write:	Enable:	List: Delete:
<b>Contents: Loadable compile cycle</b>			
Version:	MCS	Time	Date
Advance version of compile cycle (Preliminary)			
Interface: 001.001@Interfaces=002.000 @TChain=001.000			
<b>Current access level:</b>			

## 8.4 PLC

## 8.4.1 General

**Function**

The function is also available in the "Services" operating area.

You can obtain information about the current states of the following memory locations of the PLC and change them if necessary:

Inputs:	Input bit (Ex), input byte (EBx) Input word (Ewx), input double word (Edx)
Outputs:	Output bit (Ax), output byte (Abx) Output word (Awx), output double word (Adx)
Bit memories:	Memory bit (Mx), memory byte (MBx) Memory word (MWx), memory double word (MDx)
Timers:	Time (Tx)
Counters:	Counter (Cx)
Data:	Data block (DBx), data bit (DBxx), data byte (DBBx), data word (DBWx), data double word (DBDx)
Format:	B = binary H = hexadecimal D = decimal G = floating comma (for double words) C = character (ASCII character)

Operand	Example	Reading	Writing	Format	Value	Area
<b>Inputs</b>		Yes	Yes			0-127
	E 2.0			B	0	
	IB 2			B	0101 1010	
				H	5A	
				D	90	
<b>Outputs</b>		Yes	Yes			0-127
	Q20.1			B	1	
	QB 20			B	1101 0110	
				H	D6	
				D	214	
<b>Markers</b>		Yes	Yes			0-255
	M 60.7			B	1	
	MB 60			B	1101 0110	
	FW 60			H	B8	
				D	180	
				C		
<b>Timers</b>	T20	Yes	No			0-31
				B		
				H		
				D		

Operand	Example	Reading	Writing	Format	Value	Area
<b>Counters</b>	C20	Yes	Yes	B H D		0-31
<b>Data block</b>		Yes	Yes			0-255 0-255
<b>Data byte</b>	DB3.DBB9			H D B C	Q 10 000 0000 0000 1010	



A maximum of 10 operands can be displayed simultaneously.



Changes can only be made to the PLC operands with the appropriate password.



**Danger**

Changes in the states of PLC memory locations have a major impact on the machine. Incorrect parameterization can endanger lives and cause the destruction of the machine.

**8.4.2 Change/delete operand value**



**Function**

The values of operands can be changed.



**Operating sequence**

The function can also be selected in the "Services" operating area.



Press softkey "PLC".

The first operand screen form appears.

The vertical softkey bar changes.



Cyclic updating of the values is interrupted.



You can increase or decrease the address of the operand by 1 place at a time.

Delete

**Delete:**

The entries for the selected operand (formats and values) are deleted. A query window is opened.

Abort

**Undo changes:**

Press the "Abort" softkey. Cyclic updating is continued; the entered values are not transferred to the PLC.

Accept

**Accept:**

The entered values are transferred to the PLC. Cyclic updating is continued.

**Further information**

Press the "Information" key. A description of the permissible input syntax for the PLC status display is overlaid.

**8.4.3 Selecting/creating operand forms for PLC status****Function**

You can save the operands entered in the "PLC status" window to a file or read in a back-up list of operands.

The values in the PLC status are automatically discarded when the system is restarted cold (after POWER ON).

As a way of optimizing the entry of operands and formats in the PLC status, you can read in operand screen forms from DOS files (one file for each screen form).

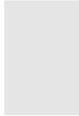
These screen forms are generated in a special syntax in ASCII format.

Naming conventions for DOS files:

name.plc      name is a screen form name of max.  
8 characters

Content of the DOS file:

[\\Comment]	e.g.//form for the PLC test
Operand/Format	DB0.DBB0/B
[Operand/Format]	DB1.DBW0/H
.	.
.	.
[Operand/Format]	T100-D



PLC

Read in  
operands

OK

You can enter as many comments and operand/format lines as you wish. In accordance with the PLC status display only the first 10 operands/format lines are read in.

### Operating sequence

The function can also be selected in the "Services" operating area.

Press softkey "PLC".

The first operand screen form appears.

The vertical softkey bar changes.

Press softkey "Read in operands" (via application diskette).

Position the cursor on the operand form you wish to find and confirm by pressing softkey "OK".

The screen form you selected is imported into the PLC status display.

#### 8.4.4 Setting the time/date



PLC

Set date/  
clock

Accept

### Function

You can set the date and time on the PLC and synchronize the date and time between the PLC and HMI Embedded.

### Operating sequence

Press the "PLC" softkey.

The horizontal and vertical softkey bars change.

Press the "Set date/clock" softkey. Open the window to enter the date and time.

Use the cursor key to move to the input fields of date (day/month/year) and time (hour/min./second).

Enter the correct values in the fields and save these with the "Input" key.

By pressing "Accept", the date and time of HMI Embedded are transferred to the PLC.

You can check the synchronization in the "Current:" output field.



### References

/IAM/ IM2: HMI Installation & Start-up Guide,

## 8.5 Activate remote diagnosis



The values set are retained when the software is rebooted.



Sync.  
manual

### Further information

You can also manually enter the time period for synchronization of the HMI and PLC clock via softkey "Sync. manual".

Sync.  
AUTO/ON

You can activate cyclic (automatic) clock synchronization via the "Sync. AUTO/ON" softkey and set the time duration for synchronization there. Enter the correct values in the input fields.

Sync.  
AUTO/OFF

Automatic synchronization is deactivated by pressing the "Sync. AUTO/OFF" softkey. The HMI and PLC then run separately again.



### Machine manufacturer

Always refer to the information and specifications provided by the machine manufacturer.

## 8.5 Activate remote diagnosis



The remote diagnosis function is an option.

If this option is set, it is possible to control and influence the operation of a PCU 20 from a remote PC, as well as to transmit data.

Remote  
diagnosis

When you select the "Remote diagnosis" softkey, the vertical "Start" and "End" softkeys appear. In this way you start or end the remote diagnosis.



### References

/IAM/ IM2: Installation & Start-up Guide HMI Embedded



### Machine manufacturer

Always refer to the information and specifications provided by the machine manufacturer.



## Start-Up Operating Area

9.1	Start-up basic display.....	9-296
9.2	Display machine data.....	9-298
9.2.1	Display options: Masking filter .....	9-300
9.3	NC settings.....	9-302
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9.8	Initiate NCK reset.....	9-307
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9.10	Display or modify system resources .....	9-308

## 9.1 Start-up basic display

**Danger**

Changes in the startup operating area have a significant influence on the machine. Incorrect parameterization can endanger lives and cause the destruction of the machine.



Access rights to certain menus in the startup operating area may be blocked by means of a keyswitch or password.

The functions described can be executed by the machine operator with his access rights.

For more detailed information on the subject of startup for

- System personnel
- Machine manufacturer
- Service personnel
- Machine users (machine setters)

Please refer to the following documentation:

/IAD/Start-up Guide, SINUMERIK 840D

/IAC/Start-up Guide, SINUMERIK 810D

/IAM/IM2, Installation & Start-Up Guide HMI Embedded

**References**

The "Machine configuration" window is displayed in the "Start-up" basic display.

Start-up	CHAN1	JOG	MPF.DIR MAR.MPF	
Channel reset				LCD brighter
Program aborted			ROV	
				LCD darker
Machine configuration				
Machine axis		Drive		Channel
Index	Name	Type	Number	Type
1	X1	Linear axis	6	VSA
2	Y1	Linear axis	7	VSA
3	Z1	Linear axis	10	VSA
4	A1	Spindle	14	HSA
Current access level manufacturer				
				Change language
				NCK Reset
				Set password
				Delete password
				Change password
Machine data		NC	PLC	HMI
				Logical drives

Machine  
data

### Horizontal softkeys

Enables you to change the machine data for all areas.

NC

Here you can look at the NC settings for NC power up, the NC address and NCU switchover and change them if necessary.

PLC

The function PLC status is available.

You can update date and time of the PLC and HMI.

HMI

Here you can enter the basic settings for the operator panel front (e.g. color settings).

Logical  
drivers

You can select the configuration screens for the new network by activating the "Logical drives" softkey.

The "Logical drives" can refer to either a network connection or an internal drive, e.g. a disk drive, a compact flash card etc.

LCD  
brighter

LCD  
darker

### Vertical softkeys

Only for OP 010 with STN display:

You can change the screen brightness.

Change  
language

You can use two languages in parallel.

When you select softkey "Change language", the screen text is displayed in the other language.



If the language is not loaded, "?" is output. When you select softkey "Change language" again, the text display reverts back to the other language.

NCK  
Reset

You can press this softkey to initiate NCK power ON/Reset.

Set  
password

You can set a password.

Delete  
password

You can delete a password.

Change  
password

You can change your password.

## 9.2 Display machine data



Access to the Machine data operating area can be controlled by key switch or password.



### Areas

#### Function

The machine data are divided into the following areas:

1. General machine data (\$MN)
2. Channel-specific machine data (\$MC)
3. Axis-specific machine data (\$MA)
4. Drive-specific machine data (\$MD)
5. Display machine data (\$MM)

A separate list display in which you can view and change machine data is provided for each of these areas.

The following information about the machine data is displayed from left to right:

- Machine data number
- Machine data name (without area identification \$MN , \$MC , \$MA , \$MD , \$MM ) , possibly with field index.
- Value of the machine datum.
- Unit of the machine datum.
- Effectiveness

If the machine data do not use units, no units are displayed.

If data is not available, the "#" symbol is displayed instead of the value.

If the value ends in an "H", it is a hexadecimal value.

The physical units of machine data are displayed on the right-hand side of the input field.

#### Examples:

$m/s^{**2}$	$m/s^2$ (meters/second squared): acceleration
$rev/s^{**3}$	$rev/s^3$ (revolution/second to power of 3): Change in rate of acceleration for rotating axis
$kg/m^{**2}$	$kg/m^2$ (kilogram/meters squared): Moment of inertia
mH	mH (millihenry): Inductance
Nm	Nm (Newton meters): Torque
us	$\mu s$ (microseconds): Time
$\mu A$	$\mu A$ (microamperes): Amperage
$\mu Vs$	$\mu Vs$ (microvolt-seconds): Magnetic flux

userdef          User-defined: The unit is defined by the user.

The abbreviation in the right-hand column indicates the activation criterion for a machine data:

- so = effective immediately
- cf = via "MD set effective" softkey activation
- re = Reset
- po = POWER ON (NCK Power On Reset)

## References

/IAD/Installation & Start-up Guide: 840D

/IAC/Installation & Start-up Guide: 810D

/IAF/Installation & Start-up Guide: FM-NC

## Operating sequence

Pressing the "machine data" softkey changes the horizontal and vertical softkey bars.

You can select the machine data area you want by pressing the following softkeys:

- General machine data (\$MN\_),
- Channel-specific machine data (\$MC\_),
- Axis-specific machine data (\$MA\_).

In the "Drive configuration" menu you can find information about the drive modules that were configured via the startup tool or change the drive configuration.

## Danger

Changes in the configuration data have a considerable influence on the machine. Incorrect parameterization can endanger lives and cause the destruction of the machine.

Drive-specific machine data (\$MD\_)

Operator panel front machine data (\$MM\_)

Machine data for the feed drive,

Machine data

General MD

Channel-spec. MD

Axis-specific MD

Drive configuration



Drive MD

Display MD

FDD

MSD

Machine data for the main spindle drive,

Find...

### Vertical softkeys

To find a specific machine datum, press the "Find..." softkey. Enter the name or number of the machine data you are looking for and press the "OK" softkey.

Keep  
searching

After pressing the "Keep searching" softkey, you move from one datum to the next in the machine data list.

### 9.2.1 Display options: Masking filter



#### Function

The purpose of masking filters is to selectively reduce the number of displayed machine data. For this function, all machine data in areas

- General machine data
- Channel-specific machine data
- Axis-specific machine data
- Drive configurations

are assigned to specific groups (e.g. configuration data, etc.).

The following applies:

1. Each area has its own group organization.
2. Each group corresponds to one bit in the filter word ("spare" bit in previous SW)
3. Each area has a maximum of 13 groups (group 14 is reserved for Expert mode (see below), bit 15 is reserved for expansions).

Display machine data do not have any group organization.

#### Filter criteria

The following table shows the criteria for displaying machine data in the order in which they are evaluated:

Criterion	Check
1. Access authorization	If the level of access authorization is not sufficient, the MD is not displayed. Otherwise criterion 2 is checked.
2. Masking filter active	The MD is always displayed when the filter is not active. Otherwise criterion 3 is checked.
3. Expert mode	The MD is not displayed if the expert mode bit is set and expert mode is not selected. Otherwise criterion 4 is checked.
4. Groups	If at least one group bit is both set and selected in the masking filter, criterion 6 is checked. Otherwise criterion 5 is checked.
5. All others	If none of the group bits is set and "All others" is selected in the masking filter, then criterion 6 is checked. If none of the group bits is set and "All others" is not selected in the masking filter, then the MD is not displayed.
6. Index from to	If the index check is selected and the index of an array is within the chosen range, then the MD is displayed. If the index check is selected and the index of an array is not within the chosen range, then the MD is not displayed.

### Initialization

When you open a machine data window, the filter setting that matches the area is automatically updated.

### Storing filter settings

Please see information supplied by machine tool manufacturer.

### Operating sequence

Press the "Machine data" softkey.  
The horizontal and vertical softkey bars change.

Press the "Display options" softkey. A list of all the ranges that can be displayed/hidden appears.

### Vertical softkeys

Press the "Select all" softkey and all areas are selected.

Press the "Deselect all" softkey and no areas are selected.



### Machine manufacturer



Machine data

Display options

Select all

Deselect all



OK

Abort

To select individual areas, jump to the individual fields with the direction key and choose these fields with the Select key.

Press "OK" to save your selection.

"Abort" takes you back to the previous screen.

### 9.3 NC settings



NC

Start up  
switchNCK  
address

OK

or

Save

Abort

#### Function

Here you can look at the NC settings for NC power up, look at and change the NC address if necessary, and carry out an NCU switchover.

Setting a key position for the startup switch with appropriate access rights.

After pressing the "Start up switch" softkey, you can choose from the following:

- Normal power-up
- Start-up with default values (Start-up mode)
- Software updates start

Look at the NCK address and change it.

In general, address changes are only necessary for M to N operation. You cannot undo an address change with general reset. The address change is not saved in an NC series startup archive.

If you press "OK" or "Save", the following safety query appears: "Do you want to change the NCK address?"

The changes will not become effective until an NCK Power on Reset has been performed".

Confirm with "Yes" or abort with "No".

"Abort" takes you back to the previous screen without saving.

## 9.4 PLC settings



PLC



### Function

The following functions are available via the "PLC" softkey.

- Setting the time and date
- Importing operands.

Changes can only be made to the PLC operands with the appropriate password.

The procedure for handling PLC operands is described in the "PLC" section in Chapter 8, Diagnosis Operating Area.

### Danger

Changes in the states of PLC memory locations have a major impact on the machine. Incorrect parameterization can endanger lives and cause the destruction of the machine.

### 9.4.1 Setting the time and date



Set date/  
time



### Function

You can set the date and time on the PLC and synchronize the date and time between the PLC and HMI Embedded.

The procedure is already described in Chapter 8, Diagnosis Operating Area, Section on "Setting Date/Time".

### 9.4.2 Import operands



Import  
operands



### Function

For optimizing the input of operands and formats in the PLC status, you can import operand screens from DOS files.

The procedure for handling PLC operands is described in the "PLC" section in Chapter 8, Diagnosis Operating Area: "Selecting/Creating Operand Forms for PLC Status".

## 9.5 Change HMI surface



### Function

You can make the following individual settings to your HMI.

- Color settings on screen
- Specify language selection
- Switch the logging process on (traverse log)
- Open ASCII editor



### Operating sequence

Pressing the "HMI" softkey changes the horizontal and vertical softkey bars.

The following **submenus** are available via the horizontal softkeys:

HMI

### 9.5.1 Setting colors

Colors

If you press the "Colors" softkey, the "Color settings" menu appears:

You can choose from the color scheme:

- Standard (cannot be changed)
- Customized.

When you select the "Customized" color setting, you can change the color settings for the HMI user interface (e.g. background, window frames, text).

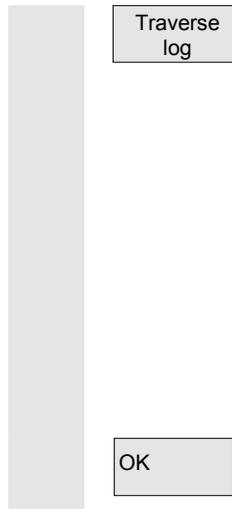
Save

Press "Save" and the current color setting is saved and you

OK

return to the menu by pressing "OK".

### 9.5.2 Traverse log

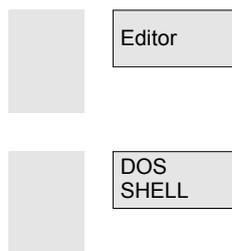


When you press the softkey, a screen is opened for setting parameters and activating the action log. You can make and save the following settings:

- Switch the logging process ON/OFF  
Log on:
- Select the data you want to log:  
Interrupts  
Keys  
channel status/override,  
Windows IDs

You can save the settings via the vertical softkeys.

### 9.5.3 Open ASCII editor



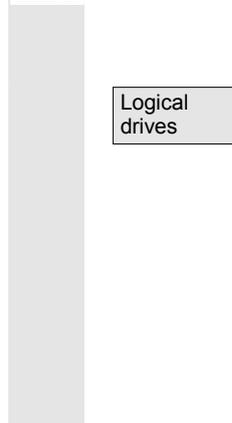
For service only!

Go to the ASCII editor to display the files at DOS level.

For service only!

Go to the DOS level.

## 9.6 Set up logical drives



### Function

Connections for a Compact Flash Card, Floppy, and network can be used on the PCU 20 by means of logical drive definitions.

This "Logical drive" function is the "Manage network/disk drive on the PCU 20" option.

In addition to the "NC" softkey, via which the NC main memory data can be displayed, a further 4 connections can be set up. These user-configured softkeys can be used to display directories and programs e.g. on disks, network drives and compact flash cards, or in the OEM memory.

These softkeys are available in the "Program" and "Services" operating areas.



## References

The procedure used to set up the additional softkeys has already been described.

/IAM/IM2, Installation Guide HMI Embedded, Chapter 3 "Network Configuration Data, Connections: Logical Drives"

## 9.7 Change language



Change  
Language

### Function

In principle, you can use two languages in parallel.

German, English, French, Italian and Spanish are available as standard. You can install even more languages via an additional Language CD.

The language switch is done with the "Change Language" softkey. However, if you want to change the two languages, proceed as follows:

### Operating sequence

#### Change the language default

With more than two installed languages, you can change the language setting via the "Languages" softkey (the standard languages are English, Spanish, French, and Italian).

Choose the two languages you require with the cursor key.

Confirm your choice with the "Select" selection key.

Confirm with "OK".

Languages



OK



## References

For installation and configuration of languages, see:  
IAM/IM2, Chapter.: Software Installation/Upgrade

Language  
Selection

If you are using more than two languages, you can select the desired language by pressing the "Language Selection" softkey.

## 9.8 Initiate NCK reset



NCK Reset

### Function

After pressing the "NCK Reset" softkey, the safety query "Do you want to initiate an NCK reset?" appears. If you press the "Yes" softkey the computer is restarted.

If you press the "No" softkey, you will return to the previous screen.

## 9.9 Setting, deleting, changing password



### Function

The control has a protection level system for enabling data areas.

There are access levels 0 to 7;

- 0 is the highest and
- 7 is the lowest.

Protection levels

- 0 to 3 is controlled by means of passwords and
- 4 to 7 by means of key switch settings.

The operator only has access to information protected by one particular level and the levels below it. The machine data is assigned different protection levels as a standard measure.

Protection level	Locked by	Area
0	Password	Siemens
1	Password	Machine manufacturer
2	Password	Installation engineer, service
3	Password	End user
4	Key switch position 3	Programmer, machine setter
5	Key switch position 2	Qualified operator
6	Key switch position 1	Trained operator
7	Key switch position 0	Semi-skilled operator

Depending on the authorization level, it will be possible to edit data such as cycles and machine data.

You can alter the set password using the "Password" function.

If one of the above passwords is set, the keyswitch position is ignored.





Set  
password

Delete  
password

Change  
password

### Operating sequence

You can set a password via the vertical softkeys, delete a password and change it.

## 9.10 Display or modify system resources



### Function

You can display the system resources currently in use for the NC and HMI Embedded areas (utilization display).



NC  
memory

### Operating sequence

By selecting the Etc key, you can access the "NC memory" softkey with the appropriate access level.

An overview of the current memory allocation appears when you press the softkey.

The "Memory overview" window shows the user memory,

- static user memory (SRAM) and
- dynamic user memory (DRAM)

with:

- Entire memory
- Used memory
- Free memory

displayed in bytes.

### Further information

Further softkeys are available for displaying more detailed information about the memory capacities.

In these individual windows, you can optimize the memory utilization by changing the machine data directly.

SRAM

or

DRAM

Details

### References

/IAM/IM2, Installation & Start-Up GuideHMI Embedded,  
Chapter 5: Displaying and Editing System Resources

**Service**

10.1	Operating data .....	10-310
10.2	Cleaning .....	10-310

## 10.1 Operating data

### Operating data

	Value
Air humidity, humidity class to DIN 40040	F
Atmospheric pressure	860 to 1080 hPa
Shock protection, Protection class to DIN VDE 0160	I
Degree of protection according to DIN 40050	
• Operator panel (front)	IP 54
• Operator panel front (rear)	IP 00
• Machine control panel (front)	IP 54
• Machine control panel (rear)	IP 00

You can find a complete summary of operating data on the appropriate supplementary sheets or in the documentation:

### References

/BH/ Operator Components, Manual

## 10.2 Cleaning

### Cleaning agents

The front of the monitor and the surface of the operator panel front can be cleaned. For dirt that is relatively easy to remove, standard household dish washing liquid, or an industrial cleaner (such as "Special Swipe") can be used. These cleaners will also remove dirt containing graphite.

Cleansing agents which contain one or more of the following ingredients can be used for a short period of time:

- Thinned mineral spirits
- Bases
- Organic hydrocarbons
- Dissolved detergents

**Plastic material used**

The plastic material used on the front of the SINUMERIK 840D is suitable for applications on machine tools.

They are resistant to

1. Grease, oil, mineral oils
2. Bases and alkalis
3. Dissolved detergents and
4. Alcohol

Solvents such as chlorinate hydrocarbons, benzene, esters and ethers should be avoided!





## Appendix



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**A Abbreviations**

<b>AS</b>	Automation System
<b>ASCII</b>	American Standard Code for Information Interchange
<b>ASIC</b>	Application-Specific Integrated Circuit
<b>ASUB</b>	Asynchronous subprogram
<b>AuxF</b>	Auxiliary Function
<b>BCD</b>	Binary Coded Decimals
<b>BCS</b>	Basic Coordinate System
<b>BIN</b>	Binary files
<b>BIOS</b>	Basic Input Output System
<b>BOT</b>	Boot Files: for SIMODRIVE 611 D
<b>BP</b>	Basic Program
<b>C1 ... C4</b>	Channel 1 to Channel 4
<b>CAD</b>	Computer-Aided Design
<b>CAM</b>	Computer-Aided Manufacturing
<b>CNC</b>	Computerized Numerical Control
<b>COM</b>	Communication
<b>COR</b>	Coordinate Rotation
<b>CP</b>	Communications Processor
<b>CPU</b>	Central Processing Unit
<b>CR</b>	Carriage Return
<b>CRC</b>	Cutter Radius Compensation

<b>CRT</b>	Cathode Ray Tube
<b>CSB</b>	Central Service Board: PLC module
<b>CSF</b>	Control System Flowchart
<b>CTS</b>	Clear To Send (serial data interfaces)
<b>CUTOM</b>	Cutter radius compensation (tool radius compensation)
<b>DAC</b>	Digital-to-Analog Converter
<b>DB</b>	Data Block in the PLC
<b>DBB</b>	Data Block Byte in the PLC
<b>DBW</b>	Data Block Word in the PLC
<b>DBX</b>	Data Block Bit in the PLC
<b>DC</b>	Direct Control: The rotary axis is moved along the shortest path to the absolute position within one revolution.
<b>DCD</b>	Data Carrier Detect
<b>DCE</b>	Data Communications Equipment
<b>DDE</b>	Dynamic Data Exchange
<b>DIN</b>	Deutsche Industrie Norm (German Industry Standard)
<b>DIO</b>	Data Input/Output: Data transfer display
<b>DIR</b>	Directory
<b>DLL</b>	Dynamic Link Library
<b>DOS</b>	Disk Operating System
<b>DPM</b>	Dual-Port Memory
<b>DPR</b>	Dual-Port RAM
<b>DRAM</b>	Dynamic Random Access Memory

<b>DRF</b>	Differential Resolver Function
<b>DRY</b>	Dry Run
<b>DSB</b>	Decoding Single Block
<b>DTE</b>	Data Terminal Equipment
<b>DW</b>	Data Word
<b>EIA Code</b>	Special tape format: Number of perforations per character is always odd
<b>ENC</b>	Encoder actual-value sensor
<b>EPROM</b>	Erasable Programmable Read Only Memory
<b>ERROR</b>	Error from printer
<b>FB</b>	Function block
<b>FBS</b>	Slimline screen
<b>FC</b>	Function Call: Function block in PLC
<b>FCI</b>	Free Contour Input
<b>FDB</b>	Product Database
<b>FDD</b>	Floppy Disk Drive
<b>FEPROM</b>	Flash EPROM Read/write memory
<b>FIFO</b>	First-In-First-Out: Memory which operates without address specification from which data are read in the same order as they are stored.
<b>FIPO</b>	Fine Interpolator
<b>FM</b>	Function Module
<b>FM-NC</b>	Function module – numerical control
<b>FPU</b>	Floating Point Unit

<b>FRA</b>	Frame Block
<b>FRAME</b>	Data block (frame)
<b>FSD</b>	Feed Spindle Drive
<b>FST</b>	Feed Stop
<b>GUD</b>	Global User Data
<b>GWPS</b>	Grinding Wheel Peripheral Speed
<b>GWRC</b>	Grinding Wheel Radius Compensation
<b>HD</b>	Hard Disk
<b>HEX</b>	Abbreviation for hexadecimal
<b>HHU</b>	Hand-Held Unit
<b>HMS</b>	High-Resolution Measuring System
<b>HW</b>	Hardware
<b>I</b>	Input
<b>I/O</b>	Input/output
<b>I/RF</b>	Infeed/Regenerative Feedback Unit (power supply) of SIMODRIVE 611(D)
<b>IBN</b>	Start-Up
<b>IC (GD)</b>	Implicit Communication (Global Data)
<b>ICA</b>	Interpolative Compensation with Absolute values
<b>IM</b>	Interface Module
<b>IMR</b>	Interface Module Receive
<b>IMS</b>	Interface Module Send
<b>INC</b>	Incremental dimension

<b>INI</b>	Initializing Data
<b>IPO</b>	Interpolator
<b>IS</b>	Interface Signal
<b>ISA</b>	International Standard Architecture
<b>ISO</b>	International Standard Organization
<b>ISO Code</b>	Special tape code, number of perforations per character is always even
<b>JOG</b>	Jog mode: Setup mode
<b>K<sub>UE</sub></b>	Transmission ratio
<b>K<sub>V</sub></b>	Servo gain factor
<b>LAD</b>	Ladder diagram (programming method for PLC)
<b>LCD</b>	Liquid-Crystal Display
<b>LEC</b>	Leadscrew Error Compensation
<b>LED</b>	Light Emitting Diode
<b>LF</b>	Line Feed
<b>LUD</b>	Local User Data
<b>MB</b>	Megabyte
<b>MC</b>	Measuring Circuit
<b>MCP</b>	Machine Control Panel
<b>MCS</b>	Machine (Machine Coordinate System)
<b>MD</b>	Machine Data
<b>MDA</b>	Manual Data Automatic: Manual input
<b>MLFB</b>	Machine-readable product designation (= Order No.)

<b>MMC</b>	Man Machine Communication: SINUMERIK operator functionality for operation, programming and simulation. MMC has the same meaning as HMI.
<b>MPF</b>	Main Program File: NC parts program
<b>MPI</b>	Multi Point Interface
<b>MS</b>	Microsoft (software manufacturer)
<b>MSD</b>	Main Spindle Drive
<b>NC</b>	Numerical Control
<b>NCK</b>	Numerical Control Kernel (with block preparation, traversing range, etc.)
<b>NCU</b>	Numerical Control Unit: Hardware unit of the NCK
<b>NRK</b>	Name for the operating system of the NCK
<b>NURBS</b>	Non-Uniform Rational B-Spline
<b>O</b>	Output
<b>OB</b>	Organization Block in PLC
<b>OEM</b>	Original Equipment Manufacturer
<b>OI</b>	Operator Interface
<b>OM</b>	Operating Mode
<b>OP</b>	Operator Panel
<b>OPI</b>	Operator Panel Interface
<b>OPT</b>	Options
<b>OSI</b>	Open System Interconnection
<b>PC</b>	Position Control
<b>PCIN</b>	Name of the software for data communication with the control

<b>PCMCIA</b>	Personal Computer Memory Card International Association: Memory card standardization
<b>PE</b>	Pulse enable for drive module
<b>PG</b>	Programming Device
<b>PLC</b>	Programmable Logic Controller
<b>PMS</b>	Position Measuring System
<b>POS</b>	Positioning
<b>RAM</b>	Random Access Memory (read-write memory)
<b>REF</b>	Reference point approach function
<b>REPOS</b>	Reposition function
<b>RISC</b>	Reduced Instruction Set Computer: Processor type with small instruction set and high-speed instruction throughput
<b>ROV</b>	Rapid Override
<b>RPA</b>	R Parameter Active Memory area in NCK for R variable numbers
<b>RPY</b>	Roll Pitch Yaw: Type of rotation of a coordinate system
<b>RS-232</b>	Serial Interface (US standard), defines transmission of serial data between DTE and DCE devices
<b>RTS</b>	Request To Send (serial data interfaces)
<b>SBL</b>	Single Block
<b>SCK</b>	Software Configuration Kit
<b>SD</b>	Setting Data
<b>SDB</b>	System Data Block
<b>SEA</b>	Setting Data Active: (file identifier for setting data)
<b>SFB</b>	System Function Block

<b>SFC</b>	System Function Call
<b>SK</b>	Softkey
<b>SKP</b>	Skip block
<b>SM</b>	Stepper Motor
<b>SPF</b>	Sub Program File: Subroutine
<b>SR</b>	Subroutine
<b>SRAM</b>	Static RAM (battery-backed)
<b>SSI</b>	Serial Synchronous Interface
<b>STL</b>	Statement list
<b>SW</b>	Software
<b>SYF</b>	System Files
<b>T</b>	Tool
<b>TC</b>	Tool Change
<b>TEA</b>	Testing Data Active: Identifier for machine data
<b>TLC</b>	Tool Length Compensation
<b>TNRC</b>	Tool Nose Radius Compensation
<b>TO</b>	Tool Offset
<b>TOA</b>	Tool Offset Active: Identifier (data type) for tool offsets
<b>TRANSMIT</b>	Transform Milling into Turning: Coordinate conversion on turning machines for milling operations
<b>TRC</b>	Tool Radius Compensation
<b>UFR</b>	User Frame: Zero offset
<b>UI</b>	User Interface

<b>WCS</b>	Work (Workpiece Coordinate System)
<b>WO</b>	Work Offset
<b>WOA</b>	Work Offset Active: Identifier (file type) for zero offset data
<b>WOP</b>	Workshop-Oriented Programming
<b>WPD</b>	Work Piece Directory
<b>μC</b>	Micro Controller

## B Terms

Key terms are given in alphabetical order. Terms which appear in the explanatory part and for which there is a separate entry are referred to with the "->" symbol.

## A

**Absolute dimensions**

A destination for an axis movement is defined by a dimension that refers to the origin of the currently active coordinate system. See also -> incremental dimension.

**Acceleration with jerk limitation**

In order to optimize the acceleration response of the machine whilst simultaneously protecting the mechanical components, it is possible to switch over in the machining program between abrupt acceleration and continuous (jerk-free) acceleration.

**Access authorization**

The CNC program blocks and data are protected via a 7-stage access authorization procedure.

- three password levels for system manufacturers, machine manufacturers and users, plus
- four keyswitch positions which can be evaluated via the PLC.

**Address**

An address is the identifier for a certain operand or operand range, e.g. input, output etc.

**Analog input/output module**

Analog input/output modules are signal transducers for analog process signals.

Analog input modules convert analog measured values into digital values which can be processed in the CPU.

Analog output modules convert digital values into analog output signals.

**Approach machine fixed-point**

Approach motion towards one of the predefined -> fixed machine points.

**Archiving**

Reading out data and/or directories to an **external** memory device.

**A-Spline**

The Akima-Spline runs under a continuous tangent through the programmed interpolation points (3rd order polynomial).

**Asynchronous subroutine**

A parts program which can be started asynchronously to (independently of) the current program status by an interrupt signal (e.g. "rapid NC input" signal).

<b>Automatic</b>	Operating mode of the control (block sequence operation according to DIN): Operating Mode in NC systems in which a -> parts program is selected and continuously executed.
<b>Auxiliary functions</b>	Auxiliary functions can be used to transfer -> parameters to the -> PLC in -> parts programs, where they trigger reactions which are defined by the machine manufacturer.
<b>Axes</b>	<p>In accordance with their functional scope, the CNC axes are subdivided into:</p> <ul style="list-style-type: none"><li>• Axes: interpolating path axes</li><li>• Auxiliary axes: non-interpolating feed and positioning axes with an axis-specific feed rate. Auxiliary axes are not involved in the actual machining, and include for example tool feeders and tool magazines.</li></ul>
<b>Axis address</b>	See -> axis identifier
<b>Axis identifier</b>	<p>Axes are labeled in accordance with DIN 66217 (for a clockwise orthogonal -&gt; coordinate system) with the letters X, Y, Z.</p> <p>-&gt; Rotary axes rotating around X, Y, Z are assigned the identifiers A, B, C. Additional axes, which are parallel to those specified, can be identified with other letters.</p>
<b>Axis name</b>	See -> axis identifier
<b>B</b>	
<b>Backlash compensation</b>	Compensation for mechanical machine backlash, e.g. backlash on reversal for feed screws. Backlash compensation can be entered separately for each axis.
<b>Backup</b>	Saving the memory contents to an external memory device.
<b>Backup battery</b>	The backup battery ensures that the -> user program is reliably backed up in the -> CPU against mains failure and that fixed data areas and markers, times and counters are kept in non-volatile memory.
<b>Back-up memory</b>	The backup memory enables buffering of memory areas of the -> CPU without a buffer battery. Buffering can be performed for a configurable number of times, counters, markers and databytes.
<b>Basic axis</b>	Axis whose setpoint or actual value position forms the basis of the calculation of a compensation value.

<b>Basic coordinate system</b>	<p>Cartesian coordinate system which is mapped by transformation onto the machine coordinate system.</p> <p>In the -&gt; parts program, the programmer uses the axis names of the basic coordinate system. The basic coordinate system exists in parallel to the -&gt; machine coordinate system when no -&gt; transformation is active. The difference between the systems relates to the axis identifiers.</p>
<b>Baud rate</b>	Rate of data transfer (Bit/s).
<b>Blank</b>	Workpiece as it is before a part is machined.
<b>Block</b>	"Block" is the term given to any files required for creating and processing programs.
<b>Block search</b>	For testing part programs or following interruption of machining, it is possible to select any point in the part program using the block search function in order to start or resume at this point.
<b>Booting</b>	Loading the system program after power on.
<b>B-spline</b>	With the B-spline, the programmed positions are not interpolation points, as they are just "control points" instead. The generated curve only runs near to the control points, not directly through them (optional 1st, 2nd or 3rd order polynomials).
<b>Bus connector</b>	A bus connector is an S7-300 accessory that is supplied with the -> I/O modules. The bus connector expands the -> S7-300 bus from the -> CPU or an I/O module to the neighboring I/O module.
<b>C</b>	
<b>C axis</b>	Axis around which the tool spindle describes a controlled rotational and positioning movement.
<b>Channel</b>	A channel is characterized by being able to run independently of other channels or a part program. A channel exclusively controls the axes and spindles assigned to it. Parts programs run on various channels can be coordinated by -> synchronization.
<b>Channel structure</b>	The channel structure enables the -> programs of the individual channels to be executed simultaneously and asynchronously.
<b>Circle interpolation</b>	The -> tool is required to travel in a circle between defined points on the contour at a specified feedrate while machining the workpiece.

<b>CNC</b>	-> NC
<b>CNC programming language</b>	The CNC programming language is based on DIN 66025 with high-level expansions. The -> high-level CNC language and programming allow, among other things, macros to be defined (groupings of individual instructions).
<b>COM</b>	Component of the NC control for the implementation and coordination of communication.
<b>Compensation axis</b>	Axis with a setpoint or actual value modified by the compensation value
<b>Compensation table</b>	Table containing interpolation points. It provides the compensation values of the compensation axis for selected positions on the basic axis.
<b>Compensation value</b>	Difference between the axis position measured by the position sensor and the desired, programmed axis position.
<b>Continuous-path mode</b>	The purpose of continuous-path mode is to prevent excessive deceleration of the -> path axes at the part program block boundaries (in terms of the control, machine and other properties of the operation and the user) and to effect the transition to the next block at as uniform a path speed as possible.
<b>Contour</b>	Outline of a -> workpiece.
<b>Contour monitoring</b>	The following error is monitored within a defined tolerance band to ensure contour precision. An impermissibly high following error might be caused by a drive overload, for example. In this case an alarm is triggered and the axes are stopped.
<b>Coordinate system</b>	See -> machine coordinate system, -> workpiece coordinate system
<b>CPU</b>	Central Processor Unit, -> Programmable Logic Controller
<b>C-spline</b>	The C-spline is the most well-known and widely used spline. The transitions at the interpolation points are continuous, both tangentially and in terms of curvature. 3rd order polynomials are used.
<b>Cutter radius compensation</b>	Contour programming assumes that the tool is pointed. Because this is not actually the case in practice, the curvature radius of the tool used must be communicated to the control which then takes it into account. The curvature center is maintained equidistantly around the contour offset by the radius of curvature.

<b>Cycle</b>	Protected subroutine for executing a repetitive machining process on the -> workpiece. An NC code generated via "Expand operator interface" or a geometry process consists of several lines.
<b>Cycle support</b>	In the "Program" operating area, the available cycles are listed under the menu "Cycle Support". After selecting the desired machining cycle the required parameters for the value assignment are displayed in clear text.
<b>D</b>	
<b>Data block</b>	<ol style="list-style-type: none"><li>1. Data unit of the -&gt; PLC, which the -&gt; HIGHSTEP programs can access.</li><li>2. Data unit of the -&gt; NC: Data blocks contain data definitions for global user data. These data can be initialized directly when they are defined.</li></ol>
<b>Data transmission program PCIN</b>	PCIN is an auxiliary program which is used to send and receive CNC user data via the serial interface, such as e.g. parts programs, tool offsets etc. The PCIN program can be executed under MS-DOS on standard industrial PCs.
<b>Data word</b>	A data unit, two bytes in size, within a -> data block.
<b>Diagnostics</b>	<ol style="list-style-type: none"><li>1. Control operating area</li><li>2. The control has both a self-diagnostics program and testing aids for service. Status, alarm and service indicators.</li></ol>
<b>Digital input/output module</b>	Digital modules are signal transducers for binary process signals.
<b>Dimensions in metric units and inches</b>	Position and gradient values can be entered in the machining program in inches. The control can be set to a basic system regardless of the programmed measuring system (G70/G71).
<b>DRF</b>	Differential Resolver Function: An NC function, which generates an incremental zero offset in automatic mode in conjunction with an electronic handwheel.
<b>Drift compensation</b>	During the constant traversing phase of the CNC axes an automatic drift compensation is performed for the analog speed control.

**Dynamic feedforward control**

Inaccuracies in the contour caused by following errors can be almost entirely eliminated with the aid of dynamic, acceleration-dependent feedforward control. The result is extraordinary machining precision even at high tool path feed-rates. The feedforward control can be individually selected and deselected for each axis in the parts program.

**E****Editor**

The editor is used to create, modify, add to, compress, and insert programs/texts/program blocks.

**Electronic handwheel**

The electronic handwheels can be used to simultaneously traverse selected axes manually. The meaning of the lines on the handwheels is defined by increment weighting.

**Exact stop**

With a programmed exact stop instruction, the position stated in a block is approached precisely and very slowly, if necessary. In order to reduce the approach time, -> exact stop limits are defined for rapid traverse and feed.

**Exact stop limit**

When all path axes reach their exact stop limits, the control responds as if it had reached its destination point precisely. The -> part program continues execution at the next block.

**External work offset**

Zero offset specified by the -> PLC.

**F****Fast retraction from contour**

When an interrupt arrives a motion can be initiated via the CNC machining program which allows the tool to be quickly retracted from the workpiece contour currently being machined. The retraction angle and the distance retracted can also be parameterized. An interrupt routine can also be executed following the fast retraction of the tool. (SINUMERIK FM-NC, 840D).

**Feed override**

The programmed velocity is overridden by the current velocity setting via the machine control panel or by the PLC (0-200 %). The feedrate can also be corrected by a programmable percentage factor (1 - 200%) in the machining program.

**Finished-part contour**

Contour of the finished workpiece. See also -> blank.

**Fixed machine point**

A point defined uniquely by the machine tool, e.g. the reference point.

<b>Fixed-point approach</b>	Machine tools can approach fixed points such as a tool change point, loading point, pallet change point, etc. in a defined way. The coordinates of these points are stored in the control. Where possible, the control moves these axes in -> rapid traverse.
<b>Frame</b>	A frame is an arithmetic rule that transforms one Cartesian coordinate system into another Cartesian coordinate system. A frame contains the components -> zero offset, -> rotation, -> scaling, -> mirroring.
<b>G</b>	
<b>Geometry</b>	Description of a -> workpiece in the -> workpiece coordinate system.
<b>Geometry axis</b>	Geometry axes are used to describe a 2- or 3-dimensional range in the workpiece coordinate system.
<b>Global main program/subroutine</b>	Every global main program/subroutine can only appear once under its own name in the directory, and it is not possible to have the same program name in different directories with different contents as a global program.
<b>Ground</b>	Ground is taken as the total of all linked inactive parts of a device which will not become live with a dangerous contact voltage even in the event of a malfunction.
<b>H</b>	
<b>Helical interpolation</b>	Helical interpolation is especially suitable for easy machining inside or outside threads with form cutters and for milling lubrication grooves. The helix consists of two motions: <ol style="list-style-type: none"><li>1. A circular movement in one plane</li><li>2. A linear movement perpendicular to this plane</li></ol>
<b>High-level CNC language</b>	The high-level language offers: -> user variable, -> pre-defined user variable, -> system variable, -> indirect programming, -> mathematical and trigonometric functions, -> comparison operations and logic operations, -> program jumps and program branching, -> program coordination (SINUMERIK 840D), -> macro technology.
<b>High-speed digital inputs/outputs</b>	The digital inputs can be used for example to start fast CNC program routines (interrupt routines). The digital CNC outputs can be used to trigger fast, program-controlled switching functions. (SINUMERIK 840D).

<b>HIGHSTEP</b>	Summary of the programming options for the -> PLC in the AS300/AS400 system.
<b>Home position</b>	Point on the machine tool used to reference the measuring system of the -> machine axes.
<b>I</b>	
<b>I/O module</b>	I/O modules represent the link between the CPU and the process. I/O modules are: <ul style="list-style-type: none"><li>• -&gt;Digital input/output modules</li><li>• -&gt;Analog input/output modules</li><li>• -&gt;Simulator modules</li></ul>
<b>Inch system</b>	Dimension system which defines distances in inches and fractions of inches.
<b>Inclined surface machining</b>	Drilling and milling operations on workpiece surfaces that do not lie in the coordinate planes of the machine can be performed easily using the function "inclined-surface machining".
<b>Increment</b>	Traversed distance information via the number of increments. The number of increments can be stored as -> setting data or selected using keys labeled with 10, 100, 1000, 10 000.
<b>Incremental dimension</b>	Also incremental dimension: A destination for axis traversal is defined by a distance to be covered and a direction referenced to a point already reached. See also -> absolute dimension.
<b>Initialization block</b>	Initialization blocks are special -> program blocks. They contain value assignments that are performed before program execution. The primary purpose of initialization blocks is to initialize predefined data or global user data.
<b>Initialization files</b>	It is possible to create an initialization file for each -> workpiece. Various variable assignments which are intended to apply specifically to one workpiece can be stored in this file.
<b>Interconnecting cables</b>	Connecting cables are pre-assembled or user-assembled 2-wire cables with a connector at each end. These interconnecting cables connect the -> CPU via the -> multipoint interface (MPI) with a -> programming device or other CPUs.

**Intermediate blocks**

Traversing movements with tool offset selected (G41/G42) can be interrupted by a limited number of intermediate blocks (block without axis movements in the compensation plane) whereby the tool offset can still be correctly calculated. The permissible number of intermediate blocks which the control reads ahead can be set in system parameters.

**Interpolator**

Logical unit of the -> NCK which determines intermediate values for the movements to be traversed on the individual axes on the basis of destination positions specified in the parts program.

**Interpolatory compensation**

Interpolatory compensation can be used to compensate for leadscrew errors and measuring system errors (LEC, MSEC) caused during production.

**Interrupt routine**

Interrupt routines are special -> subroutines which can be started by events (external signals) in the machining process. A parts program block which is currently being worked through is interrupted and the position of the axes at the point of interruption is automatically saved.

**Interrupts**

All alarms and -> messages are output on the operator panel in plain text with the date and time and a symbol indicating the cancel criterion. The display is divided into alarms and messages.

1. Alarms and messages in the parts program

Alarms and messages can be displayed as plain text directly from the parts program.

2. Alarms and messages from the PLC

Alarms and messages from the machines can be displayed as plain text from the PLC program. No additional function block packages are required to do this.

**Inverse time feedrate**

With the SINUMERIK FM-NC and 840D, it is possible to program the time required to traverse the path of a block instead of programming the feedrate for the axis movement (G93).

**J****Jog**

Control operating mode (setup mode): In JOG mode, it is possible to set up the machine. Individual axes and spindles can be moved in this mode using the direction keys. Other functions available in JOG mode are -> reference point approach, -> repositioning and -> preset (setting an actual value).

## K

**Keyswitch**

1. **S7-300**: The keyswitch is the operating mode switch of the -> CPU. A removable key is used to operate the keyswitch.
2. **840D/FM-NC**: The keyswitch on the -> machine control panel has 4 settings, to which functions are assigned by the operating system of the control. Three differently colored keys also belong to the keyswitch. These keys can be pulled out of the keyswitch in the indicated positions.

 $K_{\dot{u}}$ 

Speed ratio

 $K_v$ 

Servo gain factor, a control variable in a control loop.

## L

**Languages**

The operator guidance display texts and the system messages are available in five system languages (diskette):

**German, English, French, Italian, and Spanish**

**Two** of the above languages are available and selectable in the control.

**Leadscrew error compensation**

Compensation for the mechanical inaccuracies of a leadscrew participating in the feed. The control uses stored deviation values for the compensation.

**Limit speed**

Maximum/minimum (spindle) speed: The maximum speed of a spindle may be limited by values defined in the machine data, the -> PLC or -> setting data.

**Linear axis**

The linear axis is an axis which, in contrast to a rotary axis, describes a straight line.

**Linear interpolation**

The tool travels along a straight line to the destination point while machining the workpiece.

**Load memory**

For the CPU 314 of the -> PLC, the load memory is equal to the -> working memory.

**Look ahead**

With the **look ahead** function, a configurable number of traversing blocks is read in advance in order to calculate the optimum machining velocity.

**Look-ahead detection of contour violations**

The control can recognize and signal the following types of collision:

1. The path distance is shorter than the tool radius.
2. The width of the inner corner is smaller than the tool diameter.

**M**

<b>Machine</b>	Control operating area
<b>Machine axes</b>	Axes which exist physically on the machine tool.
<b>Machine control panel</b>	An operator panel on a machine tool with operating elements such as keys, rotary switches etc. and simple indicators such as LEDs. It is used to control the machine tool directly via the PLC.
<b>Machine coordinate system</b>	System of coordinates based on the axes of the machine tool.
<b>Machine zero</b>	A fixed point on the machine tool, which can be referenced by all (derived) measuring systems.
<b>Machining channel</b>	Via a channel structure, parallel sequences of movements, such as positioning a loading gantry during machining, can shorten unproductive times. Here, a CNC channel must be regarded as a separate CNC control system with decoding, block preparation and interpolation.
<b>Macro techniques</b>	Grouping of a set of instructions under a single identifier. The identifier in the program refers to the collected sequence of instructions.
<b>Main block</b>	A block prefixed by ":" containing all the parameters required to start execution of a -> parts program.
<b>Main program</b>	Parts program identified by a number or identifier in which further main programs, subroutines or -> cycles may be called.
<b>Mains</b>	The term "network" describes the connection of several S7-300 and other terminal devices, e.g. a programming device, via -> interconnecting cables. A data exchange takes place over the network between the connected devices.
<b>MDA</b>	Control operating mode: Manual Data Automatic. In MDA mode, it is possible to enter individual program blocks or sequences of blocks without reference to a main program or subroutine and to then execute them immediately via the NC start key.
<b>Measuring circuit</b>	<ul style="list-style-type: none"><li>• SINUMERIK FM-NC: The requisite control circuits for axes and spindles are integrated in the control module as standard. In total, a maximum of 4 axes and spindles can be realized, with a maximum of up to 2 spindles.</li><li>• SINUMERIK 840D: The signals from the sensors are analyzed in the SIMODRIVE 611D drive modules. The maximum configuration is 8 axes and spindles in total, with up to 5 spindles.</li></ul>

**Messages**

All messages programmed in the parts program and -> alarms recognized by the system are output on the operator panel in plain text with the date and time and a symbol indicating the cancel criterion. The display is divided into alarms and messages.

**Metric measurement system**

Standardized system of units: for lengths in millimeters (mm), meters (m), etc.

**Mirroring**

Mirroring inverts the signs of the coordinate values of a contour with respect to an axis. It is possible to mirror in relation to more than one axis at a time.

**Mode group**

At all times all of the axles/spindles are assigned to precisely one channel. Each channel is assigned to one operating mode group. The same -> mode is always assigned to the channels in a mode group.

**Mounting rail**

A mounting rail is used to attach the modules of an S7-300.

**Multipoint interface**

The multipoint interface (MPI) is a 9-pole Sub-D interface. A configurable number of devices can be connected to a multipoint interface and then communicate with each other.

- Programming devices
- Operator control and monitoring equipment
- Further automation systems

The parameter block "Multipoint Interface MPI" of the CPU contains the -> parameters which define the properties of the multipoint interface.

**N****Names**

Words in compliance with DIN 66025 are supplemented by identifiers (names) for variables (arithmetic variables, system variables, user variables), for subroutines, for keywords and for words with several address letters. In terms of the block structure, these supplements have the same significance as the words. Identifiers must be unique. The same identifier must not be used for different objects.

**NC**

Numerical Control: It incorporates all the components of the machine tool control system: -> NCK, -> PLC, -> MMC, -> COM.

Note: CNC (Computerized Numerical Control) is a more accurate term for the controls SINUMERIK 840D and FM-NC. MARS and Merkur controls.

<b>NCK</b>	Numerical Control Kernel: Component of the NC control which executes -> parts programs and essentially coordinates the movements on the machine tool.
<b>Node number</b>	The node number represents the "contact address" of a -> CPU or the -> programming device or any other intelligent periphery module if these are communicating via a -> network with each other. The node number is assigned to the CPU or the programming device with the S7 tool -> "S7 configuration".
<b>NRK</b>	Numeric Robotic Kernel (operating system of the -> NCK)
<b>NURBS</b>	Internal motion control and path interpolation are performed using NURBS (non-uniform rational B-splines). This provides a uniform internal method for all interpolations in the control (SINUMERIK 840D).
<b>O</b>	
<b>OEM</b>	For machine manufacturers who manufacture their own user interface or wish to integrate their own technology-specific functions in the control, free space has been left for individual solutions (OEM applications) for SINUMERIK 840D.
<b>Offset memory</b>	Data range in the control in which the tool offset data are stored.
<b>Operating mode</b>	An operating concept on a SINUMERIK control. The operating modes -> Jog, -> MDA and -> Automatic are defined.
<b>Operator interface</b>	The user interface (UI) is the display medium for a CNC control in the form of a screen. It is laid out with eight horizontal and eight vertical softkeys.
<b>Oriented spindle stop</b>	Stops the workpiece spindle with a specified orientation angle, e.g. to perform an additional machining operation at a specific position.
<b>Oriented tool retraction</b>	RETTOOL: If machining is interrupted (because of tool breakage, for example), a program command can be used retract the tool with a defined orientation by a defined path.

**Overall reset**

During a general reset the following memories of the -> CPU are deleted:

- the -> working memory
- the read/write area of the -> load memory
- the -> system memory
- the -> backup memory

**Override**

Manual or programmable control feature which enables the user to override programmed feedrates or speeds in order to adapt them to a specific workpiece or material.

**P****Parameters**

**S7-300:** A distinction is made between 2 types of parameters:

1. Parameters of a STEP 7 instruction  
A parameter of a STEP 7 instruction is the address of the operand or a constant to be processed.
2. Parameter of a -> Parameterblock  
A parameter of a parameter block determines the behavior of a module.

**Part program**

A sequence of instructions to the NC control which combine to produce a specific -> workpiece by performing certain machining operation on a given -> blank Likewise, performing a certain machining operation on a specific -> blank.

**Parts program management**

Part programs can be organized according to -> workpieces. The size of the user memory determines the number of programs and the amount of data that can be managed. Each file (programs and data) can be assigned a name comprising up to 24 alphanumeric characters.

**Path axis**

Path axes are all the machining axes in the -> channel which are controlled by the -> interpolator such that they start, accelerate, stop and reach their end positions simultaneously.

**Path feed**

Path feed acts on -> path axes. It represents the geometrical sum of the feeds on the participating -> geometry axes.

**Path velocity**

The maximum programmable path velocity depends on the input resolution. For example, with a resolution of 0.1 mm the maximum programmable path velocity is 1000 m/min.

**PG**

Programming device

<b>PLC</b>	Programmable Logic Control: -> Programmable Logic Controller. Component of the -> NC control: Programmable controller for processing the control logic of the machine tool.
<b>PLC</b>	-> Programmable Logic Controller
<b>PLC program memory</b>	SINUMERIK 840D: PLC user memory is used to store the PLC user program and the user data together with the PLC basic program. The PLC user memory can be upgraded to 96 kByte with memory expansions.
<b>PLC programming</b>	The PLC is programmed using the <b>STEP 7</b> software. The STEP 7 programming software is based on the <b>WINDOWS</b> operating system, and combines the STEP 5 programming functions with additional innovative functional developments.
<b>Polar coordinates</b>	A coordinate system, which defines the position of a point on a plane in terms of its distance from the zero point and the angle formed by the radius vector with a defined axis.
<b>Polynomial interpolation</b>	With polynomial interpolation, it is possible to generate many different curve characteristics, such as <b>straight line-</b> , <b>parabolic-</b> , and <b>exponential functions</b> (SINUMERIK 840D).
<b>Position axis</b>	Axis which performs an auxiliary movement on a machine tool (e.g. tool magazine, pallet transport). Positioning axes are axes that do not interpolate with -> path axes.
<b>Power On</b>	Switching the control off and back on again.
<b>Preset</b>	The preset function can be used to redefine the control zero in the machine coordinate system. Preset does not move the axes, but a new position value is entered for the current axis positions.
<b>Program</b>	<ol style="list-style-type: none"><li>1. Control operating area</li><li>2. Sequence of instructions to the control.</li></ol>
<b>Program block</b>	Program blocks contain the main programs and subprograms for the -> parts programs.
<b>Programmable frames</b>	Programmable -> frames can be used to define new coordinate system starting points dynamically while the parts program is running. A distinction is made between absolute definition using a new frame and additive definition with reference to an existing starting point.

**Programmable logic controller**

Programmable logic controllers (PLC) are electronic controls, the function of which is stored as a program in the control unit. This means that the layout and wiring of the device do not depend on the function of the control. The programmable logic controller has the same structure as a computer; it consists of a CPU (central module) with memory, input/output modules and an internal bus system. The peripherals and the programming language are matched to the requirements of the control technology.

**Programmable working area limitation**

Limitation of the motion space of the tool to a space defined by programmed limitations.

**Programming key**

Characters and character sequences, which have a defined meaning in the programming language for -> parts programs (see programming guide).

**Protection zone**

Three-dimensional space within the -> working area which the tool tip is not permitted to enter.

**Q****Quadrant error compensation**

Contour errors at quadrant transitions, which arise as a result of changing friction conditions on the guideways, can be virtually entirely eliminated with the quadrant error compensation. Parameterization of the quadrant error compensation is performed by means of a circuit test.

**R****R parameters**

Arithmetic parameter for which the programmer of the -> parts program can freely assign or request values in the program.

**Rapid traverse**

The highest speed of an axis. It is used for example to move the tool from rest position to the -> workpiece contour or retract the tool from the contour.

**Reference point approach**

If the utilized distance measuring system is not an absolute value encoder then it is necessary to perform a reference point approach to ensure that the actual values returned by the measuring system match the machine coordinate values.

**REPOS**

1. Repositioning on the contour via the controls  
With the Repos function it is possible to re-approach the interruption point by means of the direction keys.
2. Repositioning on the contour via the program  
Several approach strategies are available through program commands: approaching the interruption point, approaching the block starting point, approaching the block end point, approaching a point on the path between the start of the block and the interruption point.

**Retentive memory**

Data areas in data blocks and times, counters and markers are retentive (non-volatile) if their contents are not lost when the system is restarted or the mains supply is disconnected.

**Rigid tapping**

This function allows threads to be tapped without a compensating chuck. By using the method whereby the spindle, as a rotary axis, and the drilling axis interpolate, threads can be cut to a precise final drilling depth (e.g. for blind hole threads) (requirement: spindles in axis operation).

**Rotary axis**

Rotary axes rotate a workpiece or tool to a defined angular position.

**Rotary axis,  
continuously turning**

Depending on the application, the traversing range of a rotary axis can be selected to be limited to less than 360 degrees or to be endlessly turning in both directions. Endlessly-turning rotary axes are used for non-circular turning, grinding, and winding.

**Rotation**

Component of a -> frame which defines a rotation of the coordinate system through a specific angle.

**Rounding axis**

Rounding axes rotate a workpiece or tool to an angular position corresponding to an indexing grid. When a grid index is reached, the rounding axis is "in position".

**S****S7 configuration**

S7 configuration is a tool with the aid of which modules can be parameterized. With S7 configuration, various -> parameter blocks of the -> CPU and the I/O modules are set on the -> programming unit. These parameters are transmitted to the CPU.

<b>S7-300 bus</b>	The S7-300 bus is a serial databus by means of which the modules communicate with each other and are supplied with the required voltage. The connections between the modules are made with the -> bus connectors.
<b>Safety functions</b>	The controls contain watchdog monitors which are always active. These monitors detect problems in the CNC, PLC or machine in time to prevent damage to workpiece, tool or machine as far as possible. In the event of a malfunction the machining sequence is interrupted and the drives are stopped, the cause of the malfunction is saved and displayed as an alarm. At the same time, the PLC is informed that a CNC alarm is pending.
<b>Scaling</b>	Component of a -> frame, which causes axis-specific scale modifications.
<b>Serial RS-232-C interface</b>	For data input/output there is <ul style="list-style-type: none"><li>• a serial RS-232-C interface on the MMC module MMC100, and on</li><li>• MMC modules PCU 50/70 two RS-232-C interfaces</li></ul> are available. Machining programs and manufacturer and user data can be loaded and saved via these interfaces.
<b>Services</b>	Control operating area
<b>Set</b>	A section of a -> parts program terminated with a line feed. A distinction is made between -> main blocks and -> subblocks.
<b>Setting data</b>	Data which communicate properties of the machine tool to the NC control in a way defined by the system software.
<b>SIMODRIVE 611</b>	<ul style="list-style-type: none"><li>• SINUMERIK FM-NC offers an analog <math>\pm 10V</math> interface to the SIMODRIVE 611A converter system.</li><li>• The SINUMERIK 840D control system is connected to the SIMODRIVE 611D converter system by means of a high-speed digital parallel bus.</li></ul>
<b>Simulator module</b>	A simulator module is a module <ul style="list-style-type: none"><li>• on which digital input variables can be simulated via control elements and</li><li>• digital output variables can be displayed.</li></ul>
<b>Softkey</b>	A key whose name appears on an area of the screen. The selection of keys displayed is adapted dynamically to the operating situation. The freely assignable function keys (softkeys) are assigned defined functions in the software.

<b>Software limit switches</b>	Software limit switches limit the traversing range of an axis and prevent the slide from striking the hardware limit switch. 2 pairs of values can be assigned on each axis, which can then be activated separately via the -> PLC.
<b>Spindles</b>	<p>The spindle functionality is divided into two power ranges.</p> <ol style="list-style-type: none"><li>1. Spindles: Speed or position-controlled analog spindle drives     ±10V      (SINUMERIK FM-NC)     digital     (SINUMERIK 840D)</li><li>2. Auxiliary spindles: speed-controlled spindle drives, "auxiliary spindle" function package e.g. for driven tools.</li></ol>
<b>Spline interpolation</b>	Using spline interpolation, the control can obtain a very smooth curve from just a few defined interpolation points along a set contour.
<b>Standard cycles</b>	<p>Standard cycles are available for frequently recurring machining tasks.</p> <ul style="list-style-type: none"><li>• for drilling/milling technology</li><li>• for turning technology</li></ul> <p>In the "Program" operating area, the available cycles are listed under the menu "Cycle Support". After selecting the desired machining cycle the required parameters for the value assignment are displayed in clear text.</p>
<b>Structure</b>	<ul style="list-style-type: none"><li>• The SINUMERIK FM-NC is integrated into the CPU row of the SIMATIC S7-300. The module is 200 mm wide and fully encapsulated, with the same external structure as the SIMATIC S7-300 modules.</li><li>• The SINUMERIK 840D is integrated as a compact module into the SIMODRIVE 611D converter system. The dimensions correspond to a 50 mm wide SIMODRIVE 611D module. The SINUMERIK 840D module comprises the NCU module and the NCU box.</li></ul>
<b>Subblock</b>	Block prefixed by "N" containing information for a machining step such as position data.
<b>Subroutine</b>	A sequence of instructions in a -> parts program, which can be called repeatedly with various defining parameters. The subroutine is called from a main program. It is not possible to block every subroutine against unauthorized reading and displaying. -> Cycles are a form of subroutine.
<b>Synchronization</b>	Instructions in -> parts programs for coordination of sequences in different -> channels at specific machining points.

**Synchronized actions**

## 1. Auxiliary function output

During the workpiece machining, technology functions (-> auxiliary functions) can be issued from the CNC program to the PLC. These auxiliary functions are used for example to control additional equipment for the machine tool, such as quills, grabbers, clamping chucks etc.

## 2. Fast auxiliary function output

For switching functions which are time-critical, the confirmation times for the -> auxiliary functions are minimized, and unnecessary stopping points in the machining process can be avoided.

**Synchronized axes**

Synchronized axes take the same time to traverse as the geometry axes take for their path.

**System memory**

The system memory is a memory in the CPU in which the following data are stored:

- Data required by the operating system
- The operands times, counters, markers

**System variable**

A variable, which exists although it has not been programmed by the -> parts program programmer. It is defined by a data type and the variable name preceded by the character \$.

See also -> user-defined variable.

**T****Teach In**

**Teach In** can be used to create or correct parts programs. The individual program blocks can be input via the keyboard and traversed immediately. Positions approached via the direction keys or the handwheel can also be saved. Additional details such as G functions, feeds or M functions can be input in the same block.

**Text editor**

-> Editor

**Tool**

A tool is a software tool for inputting and changing the -> parameters of a parameter block. Tools include:

- S7-Configuration
- S7-TOP
- S7-Info

**Tool offset**

By programming a **T function** (5 integer decades) in the block, you can select the tool. Up to 9 cutting edges (D addresses) can be assigned to every T number. The number of tools to be managed in the controller is specified in the configuring data.

<b>Tool radius compensation</b>	In order to be able to program a desired -> workpiece contour directly, the control must traverse a path equidistant to the programmed contour, taking into account the radius of the tool used. (G41/G42).
<b>Tools</b>	A part used on the machine tool for machining. Examples of tools include lathe tools, milling cutters, drills, laser beams, etc.
<b>Transformation</b>	Programming in a Cartesian coordinate system, execution in a non-Cartesian coordinate system (e.g. with machine axes as rotary axes).
<b>Traversing range</b>	The maximum permissible traversing range on linear axes is $\pm 9$ decades. The absolute value depends on the selected input sensitivity and positioning resolution and the system of units used (inches or metric).
<b>U</b>	
<b>User memory</b>	All program and data, such as part programs, subroutines, comments, tool compensations, and work offsets/frames, as well as channel- and program user data can be stored in the shared CNC user memory.
<b>User program</b>	User programs for the S7-300 automation systems are created using the programming language STEP 7. The user program has a modular layout and consists of individual blocks. The basic block types are: Code blocks: these blocks contain the STEP 7 commands. Data blocks: these blocks contain the constants and variables for the STEP 7 program.
<b>User-defined variable</b>	The user can declare user-defined variables for any use in the -> parts program or data block (global user data). A definition contains a data type specification and the variable name. See also -> system variable.
<b>V</b>	
<b>Variable definition</b>	A variable definition includes the specification of a data type and a variable name. The variable names can be used to access the value of the variables.

**Velocity control**

In order to be able to achieve an acceptable traversing velocity on very short traverse movements within a single block, predictive velocity control can be set over several blocks (-> look ahead).

**Vocabulary words**

Words with a specific notation, which have a defined meaning in the programming language for -> parts programs.

**W****Working area**

Three-dimensional zone into which the tool tip can be moved on account of the physical design of the machine tool.

See also -> protection zone.

**Working area limitation**

With the aid of the working area limitation, the traversing range of the axes can be further restricted in addition to the limit switches. One value pair per axis may be used to describe the protected working area.

**Working memory**

The working area is a RAM area in the -> CPU which is accessed by the processor to access the user program during program execution.

**Workpiece**

Part to be created/machined by the machine tool. A workpiece is saved as a separate program in a directory.

**Workpiece contour**

Setpoint contour of the -> workpiece to be created/machined.

**Workpiece coordinate system**

The starting position of the workpiece coordinate system is the -> workpiece zero. In machining operations programmed in the workpiece coordinate system, the dimensions and directions refer to this system.

**Workpiece zero**

The workpiece zero is the starting point for the -> workpiece coordinate system. It is defined in terms of the distance from the machine zero.

**X****Y**

**Z****Zero offset**

Specification of a new reference point for a coordinate system through reference to an existing zero point and a -> frame.

**1. Adjustable**

SINUMERIK FM-NC: Four independent zero offsets can be selected for each CNC axis.

SINUMERIK 840D: A configurable number of adjustable zero offsets is available for each CNC axis. The offsets which can be selected via G functions are effective on an alternating basis.

**2. External**

In addition to all displacements which define the position of the workpiece zero point, an external zero offset can be superimposed via

- a handwheel (DRF offset) or
- the PLC.

**3. Programmable**

Zero offsets are programmable for all path and positioning axes with the TRANS command.



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Order No.: 6FC5297-6AA50-0BP3

**/BHA/** SIMODRIVE Sensor (03.03 Edition)  
User Guide (HW) **Absolute Position Sensor with Profibus DP**  
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Planning Guide **EMC Installation Guide**  
Order No.: 6FC5297-0AD30-0BP1

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**/GHA/** SINUMERIK/SIMOTION (02.03 Edition)  
**ADI4 - Analog Drive Interface for 4 Axes**  
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<b>/PFK7/</b>	SIMODRIVE 611, MASTERDRIVES MC Planning Guide <b>1FK7 Three-Phase AC Servomotors</b> Order No.: 6SN1197-0AD06-0BP0	(01.03 Edition)
<b>/PFS6/</b>	MASTERDRIVES MC Planning Guide <b>1FS6 Three-Phase AC Servomotors</b> Order No.: 6SN1197-0AD08-0BP0	(07.03 Edition)
<b>/PFT5/</b>	SIMODRIVE 611 Planning Guide <b>1FT5 Three-Phase AC Servomotors</b> Order No.: 6SN1197-0AD01-0BP0	(05.03 Edition)
<b>/PFT6/</b>	SIMODRIVE 611, MASTERDRIVES MC Planning Guide <b>1FT6 Three-Phase AC Servomotors</b> Order No.: 6SN1197-0AD02-0BP0	(01.04 Edition)
<b>/PFU/</b>	SINAMICS, MASTERDRIVES, MICROMASTER <b>SIEMOSYN Motors 1FU8</b> Order No.: 6SN1197-0AC80-0BP0	(09.03 Edition)
<b>/PHC/</b>	SINUMERIK 810D <b>Configuring Manual CCU (HW)</b> Order No.: 6FC5297-6AD10-0BP1	(11.02 Edition)
<b>/PHD/</b>	SINUMERIK 840D <b>Configuring Manual NCU (HW)</b> Order No.: 6FC5297-6AC10-0BP3	(11.03 Edition)
<b>/PJAL/</b>	SIMODRIVE 611, MASTERDRIVES MC Planning Guide <b>Three-Phase Servomotors</b> <b>General Part for 1FT / 1FK Motors</b> Order No.: 6SN1197-0AD07-0BP1	(01.04 Edition)
<b>/PJAS/</b>	SIMODRIVE 611, MASTERDRIVES VC/MC Planning Guide Asynchronous Motors Contents: <b>General Part, 1PH2, 1PH4, 1PH7, 1PL6</b> Order No.: 6SN1197-0AC61-0BP0	(06.04 Edition)
<b>/PJFE/</b>	SIMODRIVE Planning Guide <b>1FE1 Built-In Synchronous Motors</b> Three-Phase AC Motors for Main Spindle Drives Order No.: 6SN1197-0AC00-0BP5	(03.04 Edition)
<b>/PJF1/</b>	SIMODRIVE Installation Guide <b>1FE1 051.-1FE1 147. Built-In Synchronous Motors</b> AC Motors for Main Spindle Drives Order No.: 610.43000.02	(12.02 Edition)

<b>/PJLM/</b>	SIMODRIVE Planning Guide <b>1FN1, 1FN3 Linear Motors</b> ALL General Information about Linear Motor 1FN1 1FN1 Three-Phase AC Linear Motor 1FN3 1FN3 Three-Phase AC Linear Motor CON Connections Order No.: 6SN1197-0AB70-0BP4	(06.02 Edition)
<b>/PJM2/</b>	SIMODRIVE 611, MASTERDRIVES MC Planning Guide <b>Servomotors</b> Contents: General Part, 1FT5, 1FT6, 1FK6, 1FK7, 1FS6 Order No.: 6SN1197-0AC20-0BP0	(03.04 Edition)
<b>/PJTM/</b>	SIMODRIVE Planning Guide <b>1FW6 Built-In Torque Motors 1FW6</b> Order No.: 6SN1197-0AD00-0BP1	(05.03 Edition)
<b>/PJU/</b>	SIMODRIVE 611 Planning Guide <b>Converters</b> Order No.: 6SN1197-0AA00-0BP6	(02.03 Edition)
<b>/PKTM/</b>	MASTERDRIVES Planning Guide <b>Torque Motors 1FW3</b> Order No.: 6SN1197-0AC70-0BP0	(03.04 Edition)
<b>/PMH/</b>	SIMODRIVE Sensor Configuring/Installation Guide <b>Hollow-Shaft Measuring System SIMAG H</b> Order No.: 6SN1197-0AB30-0BP1	(07.02 Edition)
<b>/PMH2/</b>	SIMODRIVE Sensor Configuring/Installation Guide <b>Hollow-Shaft Measuring System SIMAG H2</b> Order No.: 6SN1197-0AB31-0BP0	(03.04 Edition)
<b>/PMHS/</b>	SIMODRIVE Installation Guide <b>Measuring System for Main Spindle Drives</b> <b>SIZAG2 Toothed-Wheel Encoder</b> Order No.: 6SN1197-0AB00-0YP3	(12.00 Edition)
<b>/PMS/</b>	SIMODRIVE Planning Guide <b>ECO Motor Spindle for Main Spindle Drives</b> Order No.: 6SN1197-0AD04-0BP1	(03.04 Edition)
<b>/PPH/</b>	SIMODRIVE Planning Guide <b>1PH2 / 1PH4 / 1PH7 Motors</b> AC Induction Motors for Main Spindle Drives Order No.: 6SN1197-0AC60-0BP0	(12.01 Edition)
<b>/PPM/</b>	SIMODRIVE Planning Guide Hollow-Shaft Motors for <b>1PM4 and 1PM6</b> Main Spindle Drives Order No.: 6SN1197-0AD03-0BP0	(11.01 Edition)

**c) Software**  
**/FB1/**

	SINUMERIK 840D/840Di/810D/FM-NC	(03.04 Edition)
	Description of Function <b>Basic Machine (Part 1)</b> (the various sections are listed below)	
	Order No.: 6FC5297-7AC20-0BP0	
A2	Various Interface Signals	
A3	Axis Monitoring, Protection Zones	
B1	Continuous-Path Mode, Exact Stop and Look Ahead	
B2	Acceleration	
D1	Diagnostic Tools	
D2	Interactive Programming	
F1	Traverse to Fixed Stop	
G2	Velocities, Setpoint/Actual Value Systems, Closed-Loop Control	
H2	Output of Auxiliary Functions to PLC	
K1	Mode Group, Channel, Program Operation Mode	
K2	Axes, Coordinate Systems, Frames, Actual-Value System for Workpiece, External Zero Offset	
K4	Communication	
N2	EMERGENCY STOP	
P1	Traverse Axes	
P3	Basic PLC Program	
R1	Reference Point Approach	
S1	Spindles	
V1	Feeds	
W1	Tool Offset	

**/FB2/**

	SINUMERIK 840D/840Di/810D	(03.04 Edition)
	Description of Functions <b>Extended Functions (Part 2)</b> including FM-NC: Turning, Stepper Motor (the various sections are listed below)	
	Order No.: 6FC5297-7AC30-0BP0	
A4	Digital and Analog NCK I/Os	
B3	Several Operator Panels and NCUs	
B4	Operation via PG/PC	
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H1	JOG with/without Handwheel	
K3	Compensations	
K5	Mode Groups, Channels, Axis Replacement	
L1	FM NC Local Bus	
M1	Kinematic Transformation	
M5	Measurement	
N3	Software Cams, Position Switching Signals	
N4	Punching and Nibbling	
P2	Positioning Axes	
P5	Oscillation	
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S5	Synchronized Actions (SW 3 and lower, higher /FBSY/)	
S6	Stepper Motor Control	
S7	Memory Configuration	
T1	Indexing Axes	
W3	Tool Change	
W4	Grinding	

- /FB3/** SINUMERIK 840D/840Di/810D (08.04 Edition)  
 Description of Functions **Special Functions (Part 3)**  
 (the various sections are listed below)  
 Order No.: 6FC5297-7AC80-0BP1  
 F2 3-Axis to 5-Axis Transformation  
 G1 Gantry Axes  
 G3 Clock Times  
 K6 Contour Tunnel Monitoring  
 M3 Coupled Motion and Leading Value Coupling  
 S8 Constant Workpiece Speed for Centerless Grinding  
 T3 Tangential Control  
 TE0 Installation and Activation of Compile Cycles  
 TE1 Clearance Control  
 TE2 Analog Axes  
 TE3 Master-Slave for Drives  
 TE4 Transformation Package Handling  
 TE5 Setpoint Exchange  
 TE6 MCS Coupling  
 TE7 Retrace Support  
 TE8 Pulse-Independent Path-Synchronized Switching Signal Output  
 V2 Preprocessing  
 W5 3D Tool Radius Compensation
- /FBA/** SIMODRIVE 611D/SINUMERIK 840D/810D (03.04 Edition)  
 Description of Functions **Drive Functions**  
 (the various sections are listed below)  
 Order No.: 6SN1197-0AA80-1BP1  
 DB1 Operating Messages/Alarm Reactions  
 DD1 Diagnostic Functions  
 DD2 Speed Control Loop  
 DE1 Extended Drive Functions  
 DF1 Enable Commands  
 DG1 Encoder Parameterization  
 DL1 Linear Motor MD  
 DM1 Calculating Motor/Power Section Parameters  
 and Controller Data  
 DS1 Current Control Loop  
 DÜ1 Monitors/Limitations
- /FBAN/** SINUMERIK 840D/SIMODRIVE 611 DIGITAL (02.00 Edition)  
 Description of Functions **ANA MODULE**  
 Order No.: 6SN1197-0AB80-0BP0
- /FBD/** SINUMERIK 840D (07.99 Edition)  
 Description of Functions **Digitizing**  
 Order No.: 6FC5297-4AC50-0BP0  
 DI1 Start-Up  
 DI2 Scan with Tactile Sensor (scancad scan)  
 DI3 Scan with Laser (scancad laser)  
 DI4 Milling Program Generation (scancad mill)
- /FBDM/** SINUMERIK 840D/840Di/810D (09.03 Edition)  
 Description of Functions DNC **NC Program Management**  
 Order No.: 6FC5297-1AE81-0BP0

<b>/FBDN/</b>	SINUMERIK 840D/840Di/810D Motion Control Information System (MCIS) Description of Functions <b>DNC NC Program Management</b> Order No.: 6FC5297-1AE80-0BP0 DN1 DNC Plant / DNC Cell DN2 DNC IFC SINUMERIK, NC Data Transfer via Network	(03.03 Edition)
<b>/FBFA/</b>	SINUMERIK 840D/840Di/810D Description of Functions <b>ISO Dialects for SINUMERIK</b> Order No.: 6FC5297-6AE10-0BP4	(07.04 Edition)
<b>/FBFE/</b>	SINUMERIK 840D/810D Motion Control Information System (MCIS) Description of Functions <b>Remote Diagnosis</b> Order No.: 6FC5297-0AF00-0BP3 FE1 Remote Diagnosis ReachOut FE3 Remote Diagnosis pcAnywhere	(03.04 Edition)
<b>/FBH/</b>	SINUMERIK 840D/840Di/810D <b>HMI Configuring Package</b> Order No.: (supplied with the software)  Part 1 User's Guide Part 2 Description of Functions	(11.02 Edition)
<b>/FBH1/</b>	SINUMERIK 840D/840Di/810D <b>HMI Configuring Package</b> <b>ProTool/Pro Option SINUMERIK</b> Order No.: (supplied with the software)	(03.03 Edition)
<b>/FBHL/</b>	SINUMERIK 840D/SIMODRIVE 611 digital Description of Functions <b>HLA Module</b> Order No.: 6SN1197-0AB60-0BP3	(10.03 Edition)
<b>/FBIC/</b>	SINUMERIK 840D/840Di/810D Motion Control Information System (MCIS) Description of Functions <b>TDI Ident Connection</b> Order No.: 6FC5297-1AE60-0BP0	(06.03 Edition)
<b>/FBMA/</b>	SINUMERIK 840D/810D Description of Functions <b>ManualTurn</b> Order No.: 6FC5297-6AD50-0BP0	(08.02 Edition)
<b>/FBO/</b>	SINUMERIK 840D/810D Description of Functions Configuring <b>OP 030 Operator Interface</b> (the various sections are listed below) Order No.: 6FC5297-6AC40-0BP0 BA Operator's Guide EU Development Environment (Configuring Package) PSE Introduction to Configuring of Operator Interface IK Screen Kit: Software Update and Configuration	(09.01 Edition)

<b>/FBP/</b>	SINUMERIK 840D Description of Functions <b>C-PLC Programming</b> Order No.: 6FC5297-3AB60-0BP0	(03.96 Edition)
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<b>/FBSI/</b>	SINUMERIK 840D/SIMODRIVE Description of Functions SINUMERIK <b>Safety Integrated</b> Order No.: 6FC5297-6AB80-0BP2	(11.03 Edition)
<b>/FBSP/</b>	SINUMERIK 840D/840Di/810D Description of Functions <b>ShopMill</b> Order No.: 6FC5297-6AD80-0BP2	(11.03 Edition)
<b>/FBST/</b>	SIMATIC Description of Functions <b>FM STEPDRIVE/SIMOSTEP</b> Order No.: 6SN1197-0AA70-0YP4	(01.01 Edition)
<b>/FBSY/</b>	SINUMERIK 840D/810D Description of Functions <b>Synchronized Actions</b> Order No.: 6FC5297-7AD40-0BP2	(03.04 Edition)
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<b>/FBTC/</b>	SINUMERIK 840D/810D IT Solutions Description of Functions <b>Tool Data Communication SinTDC</b> Order No.: 6FC5297-5AF30-0BP0	(01.02 Edition)
<b>/FBTD/</b>	SINUMERIK 840D/810D IT Solutions Description of Functions <b>Tool Information System (SinTDI)</b> with Online Help Order No.: 6FC5297-6AE00-0BP0	(02.01 Edition)
<b>/FBTP/</b>	SINUMERIK 840D/840Di/810D Motion Control Information System (MCIS) Description of Functions <b>TPM Total Productive Maintenance</b> Order No.: Document is supplied with the software	(01.03 Edition)
<b>/FBU/</b>	SIMODRIVE 611 universal/universal E Description of Functions <b>Closed-Loop Control Component for Speed Control and Positioning</b> Order No.: 6SN1197-1AB20-0BP9	(07.04 Edition)
<b>/FBU2/</b>	SIMODRIVE 611 <b>universal</b> Installation Guide (enclosed with SIMODRIVE 611 universal)	(04.02 Edition)

<b>/FBW/</b>	SINUMERIK 840D/810D Description of Functions <b>Tool Management</b> Order No.: 6FC5297-6AC60-0BP1	(11.02 Edition)
<b>/HBA/</b>	SINUMERIK 840D/840Di/810D Manual <b>@Event</b> Order No.: 6AU1900-0CL20-0BA0	(03.02 Edition)
<b>/HBI/</b>	SINUMERIK 840Di Manual <b>SINUMERIK 840Di</b> Order No.: 6FC5297-7AE60-0BP0	(03.04 Edition)
<b>/INC/</b>	SINUMERIK 840D/840Di/810D System Description <b>Commissioning Tool SINUMERIK SinuCOM NC</b> Order No.: (an integral part of the online help for the start-up tool)	(06.03 Edition)
<b>/PGA1/</b>	SINUMERIK 840D/840Di/810D List Manual <b>System Variables</b> Order No.: 6FC5297-6EA10-0BP0	(03.04 Edition)
<b>/PJE/</b>	SINUMERIK 840D/810D Description of Functions <b>Configuring Package HMI Embedded</b> Software Update, Configuration, Installation Order No.: 6FC5297-6EA10-0BP0	(08.01 Edition)
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<b>/S7HT/</b>	SIMATIC S7-300 Manual <b>STEP 7, Fundamentals, V. 3.1</b> Order No.: 6ES7810-4CA02-8BA0	(03.97 Edition)
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<b>/SP/</b>	SIMODRIVE 611-A/611-D <b>SimoPro 3.1</b> Program for Configuring Machine-Tool Drives Order number: 6SC6111-6PC00-0BA□ Order from: WK Fürth	

**d) Installation and Start-up**

<b>/BS/</b>	SIMODRIVE 611 analog Description <b>Start-Up Software for Main Spindle and Asynchronous Motor Modules Version 3.20</b> Order No.: 6SN1197-0AA30-0BP1	(10.00 Edition)
<b>/IAA/</b>	SIMODRIVE 611A <b>Installation and Start-Up Guide</b> Order No.: 6SN1197-0AA60-0BP6	(10.00 Edition)
<b>/IAC/</b>	SINUMERIK 810D <b>Installation and Start-Up Guide</b> (including description of SIMODRIVE 611D start-up software) Order No.: 6FC5297-6AD20-0BP1	(11.02 Edition)
<b>/IAD/</b>	SINUMERIK 840D/SIMODRIVE 611D <b>Installation and Start-Up Guide</b> (including description of SIMODRIVE 611D start-up software) Order No.: 6FC5297-7AB10-0BP0	(03.04 Edition)
<b>/IAM/</b>	SINUMERIK 840D/840Di/810D Installation and Start-Up Guide <b>HMI/MMC</b> Order No.: 6FC5297-6AE20-0BP4 AE1 Updates/Supplements BE1 Expanding the Operator Interface HE1 Online Help IM2 Start-Up HMI Embedded IM4 Start-Up HMI Advanced TX1 Creating Foreign Language Texts	(03.04 Edition)





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**Suggestions**

**Corrections**

For publication:

SINUMERIK 840D/810D

HMI Embedded

User Documentation

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Company/Dept.

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Zip code: \_\_\_\_\_ City: \_\_\_\_\_

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Operator's Guide

Order no.: 6FC5298-6AC00-0BP3  
03.04 Edition

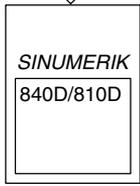
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**Suggestions and/or corrections**



# Overview of SINUMERIK 840D/840Di/810D Documentation (04.2004)

## General Documentation



Brochure

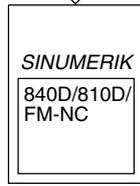


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NC 60 \*)

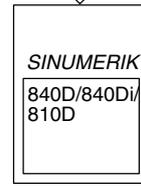


**Safety Integrated**  
Application Manual

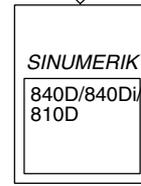
## User Documentation



**AutoTurn**  
– Short Guide  
– Programming/Setup



Operator's Guide  
– HT 6

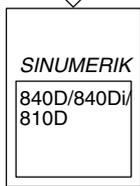


**Diagnostics**  
Guide \*)

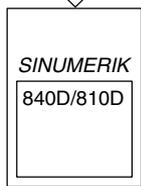


**Operator's Guide \*)**  
– Short Guide  
– HMI Embedded  
– HMI Advanced

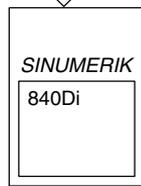
## User Documentation



**Programming Guide**  
– Short Guide  
– Fundamentals \*)  
– Advanced \*)  
– Cycles  
– Measuring Cycles  
– ISO Turning/Milling  
– Lists **System Variables**

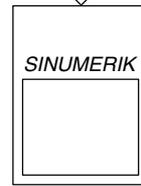


Operator's Guide  
– **ManualTurn**  
– Short Guide ManualTurn  
– **ShopMill**  
– Short Guide ShopMill  
– **ShopTurn**  
– Short Guide ShopTurn



**System Overview**

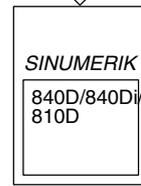
## Manufacturer/Service Documentation



**Configuring**  
(HW) \*)  
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– 840D

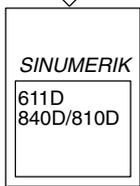


**Operator Components**  
(HW) \*)



Description of Functions  
– **ManualTurn**  
– **ShopMill**  
– **ShopTurn**

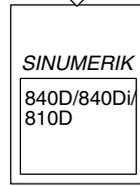
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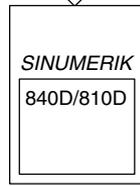
Description of Functions  
**Synchronized Actions**



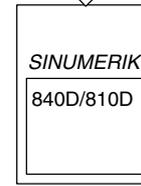
Description of Functions  
**Drive Functions \*)**



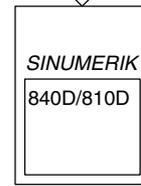
**Description of Functions**  
– Basic Machine \*)  
– Extended Functions  
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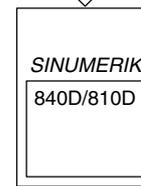
Description of Functions  
**Tool Management**



**Configuring Kit**  
HMI Embedded



Description of Functions  
Operator Interface  
**OP 030**

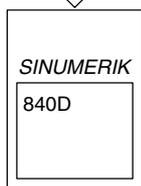


**MCIS**  
– Computer Link  
– Tool Data Inform. Syst.  
– NC Data Management  
– NC Data Transfer  
– Tool Data Communication

## Manufacturer/Service Documentation



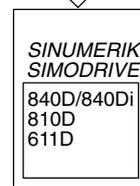
Description of Functions  
SINUMERIK  
**Safety Integrated**



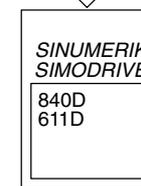
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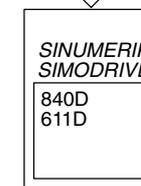
**Installation & Start-Up**  
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– 810D  
– 840D/611D  
– HMI



– Lists \*)



Description of Functions  
**Linear Motor**

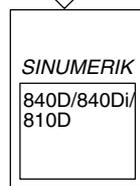


Description of Functions  
– **Hydraulics Module**  
– **Analog Module**



**EMC**  
Guidelines

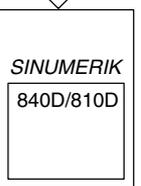
## Manufacturer/Service Documentation



Description of Functions  
**ISO Dialects** for  
SINUMERIK



**Manual**  
(HW + Installation  
and Start-Up)

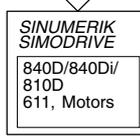


Description of Functions  
**Remote Diagnosis**



**Manual**  
@ Event

## Electronic Documentation



**DOC ON CD \*)**  
The SINUMERIK System

\*) These documents are a minimum requirement

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Subject to change without prior notice  
Order No.: 6FC5298-6AC00-0BP3

Printed in Germany